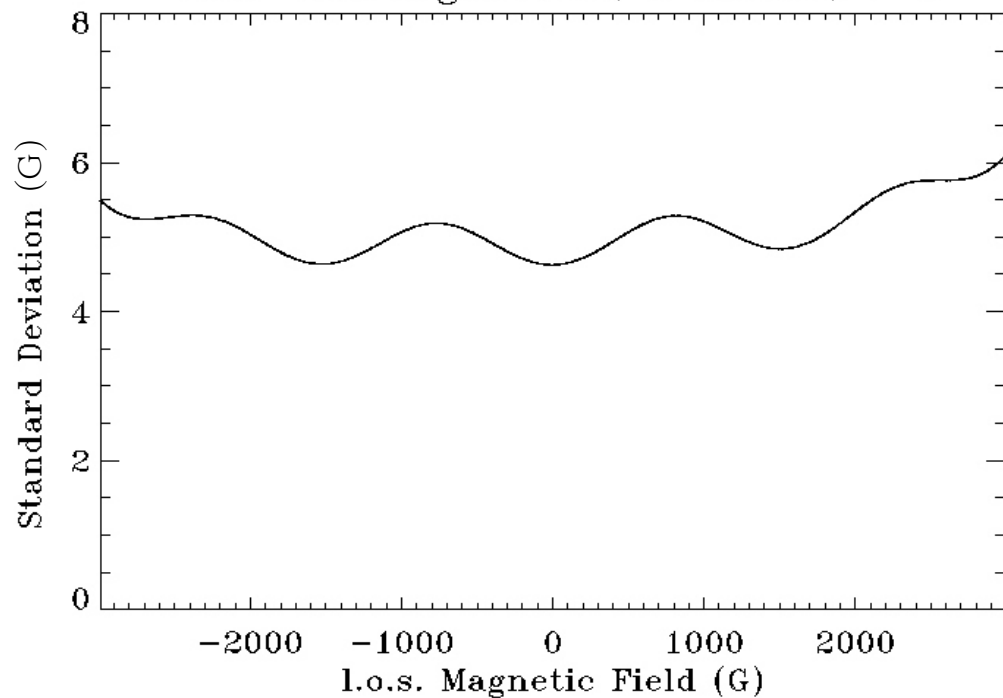
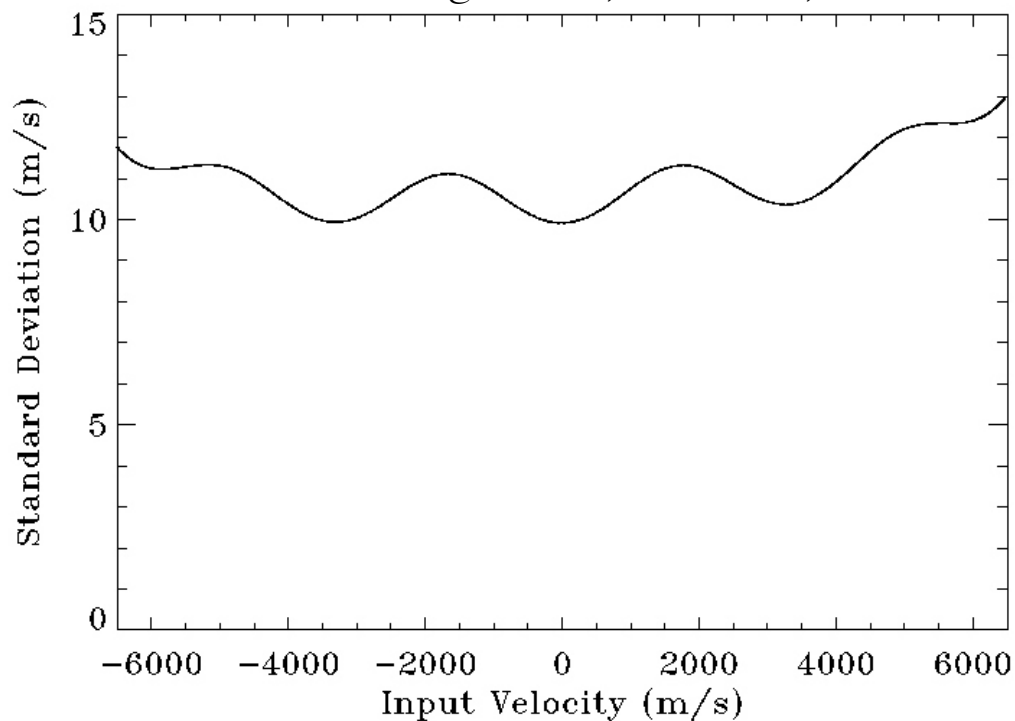


Errors on Doppler Velocity, l.o.s. Magnetic Field Strength, and Continuum Intensity

MDI-like algorithm, 6 filters, v=0



MDI-like algorithm, 6 filters, B=0



Error on Doppler velocity and I.o.s. field strength, with MDI-like algorithm and 6 filters.

“Best case” scenario:

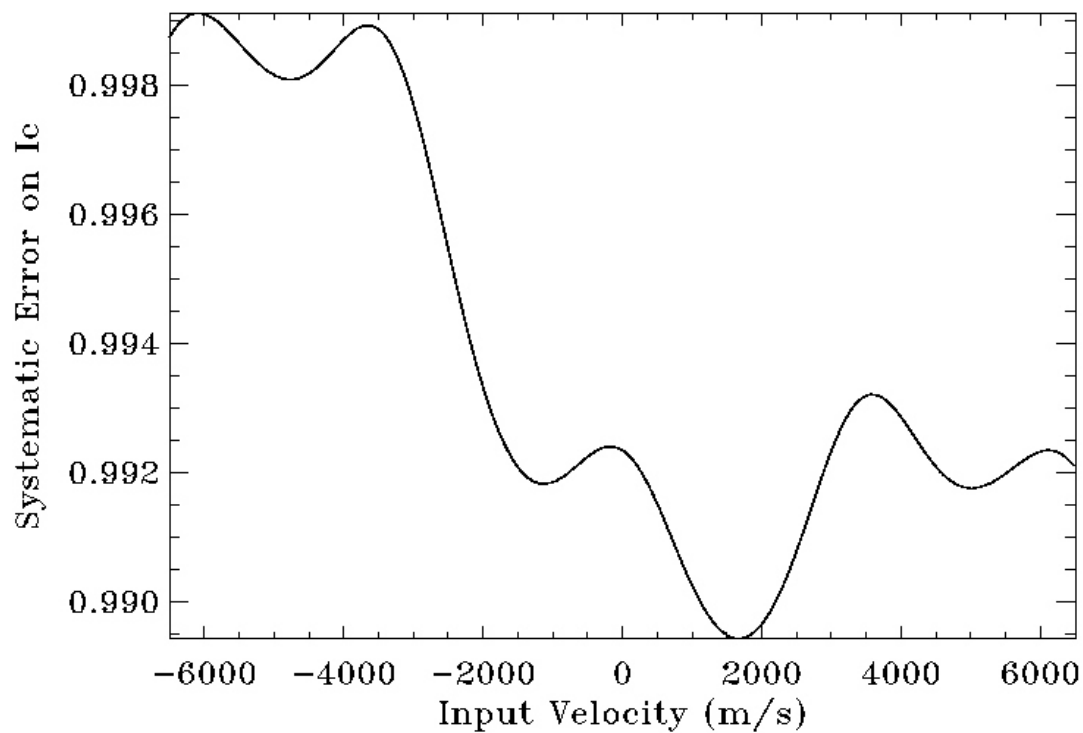
- perfect knowledge of HMI filter system
- error due to photon noise only (full well of 200,000 electrons)
- at disk center

$$V = (V_{LCP} + V_{RCP})/2$$

$$\|B\|_{I.o.s.} = (V_{LCP} - V_{RCP}) * 0.2314$$

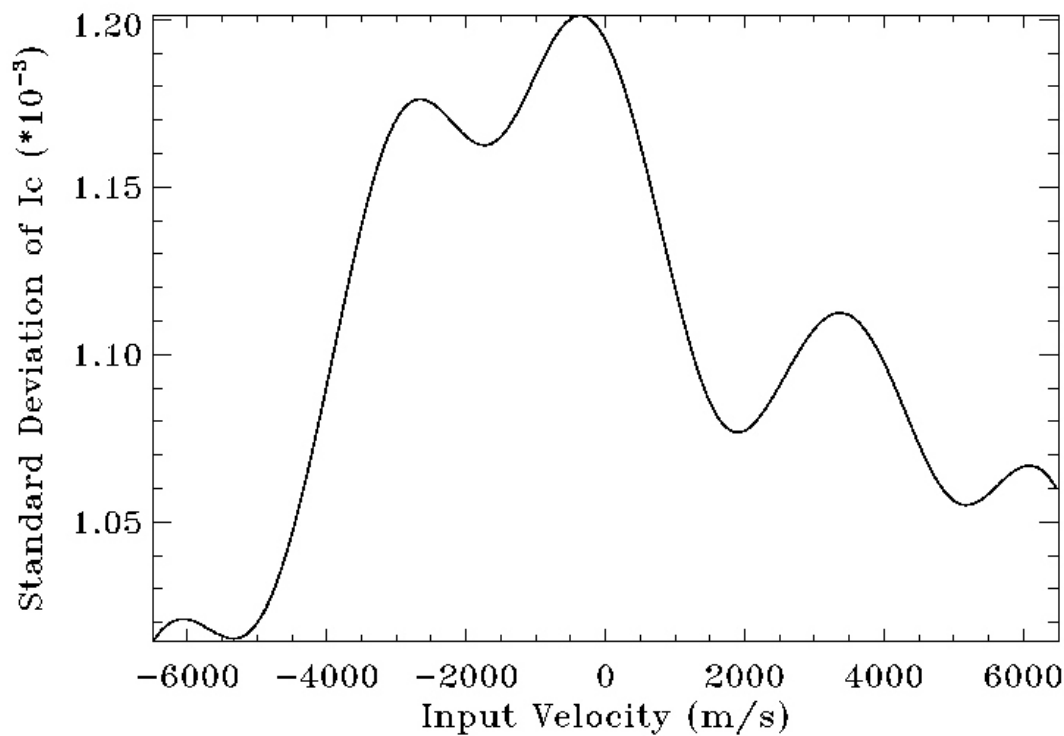
$$\Rightarrow \sigma_B = 2 * 0.2314 * \sigma_V$$

NB: 6500 m/s \Leftrightarrow 3000 G

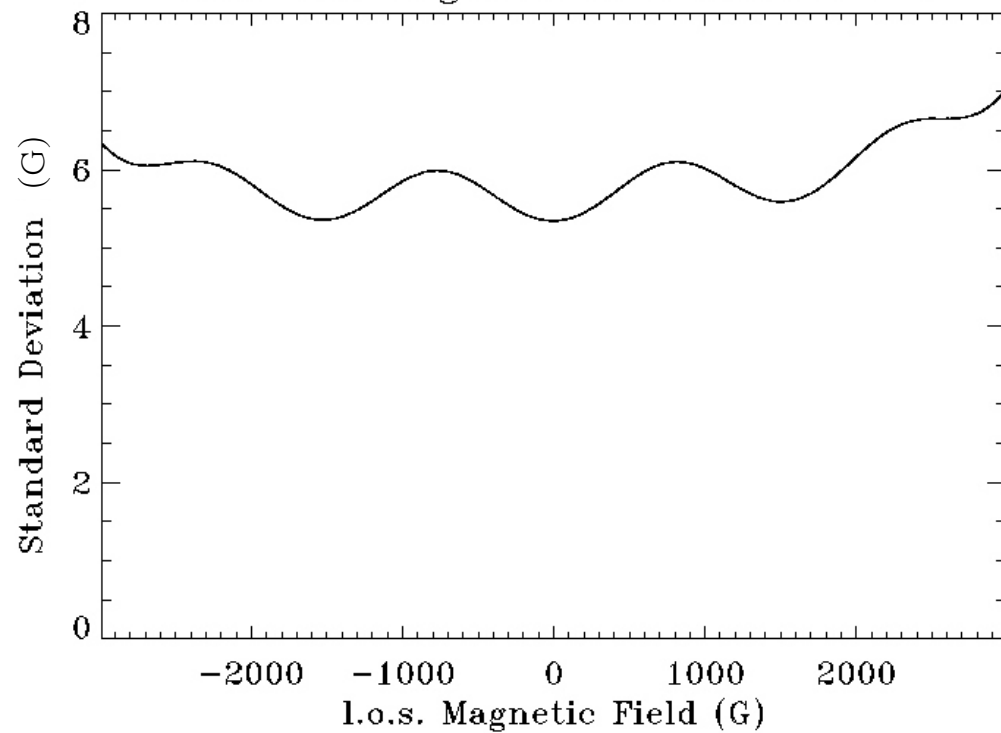


Error on continuum intensity I_c , when Fe I line modeled as $I(\lambda) = I_c - I_d \exp(-\lambda^2/\sigma^2)$

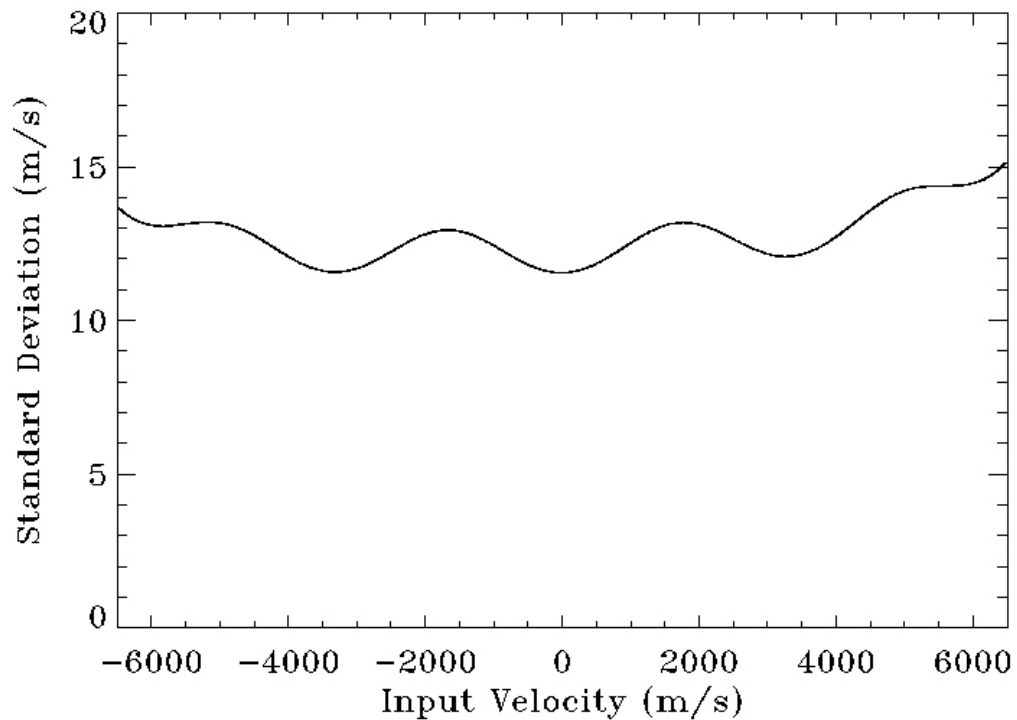
at disk center, $B=0$, full well = 200,000 electrons



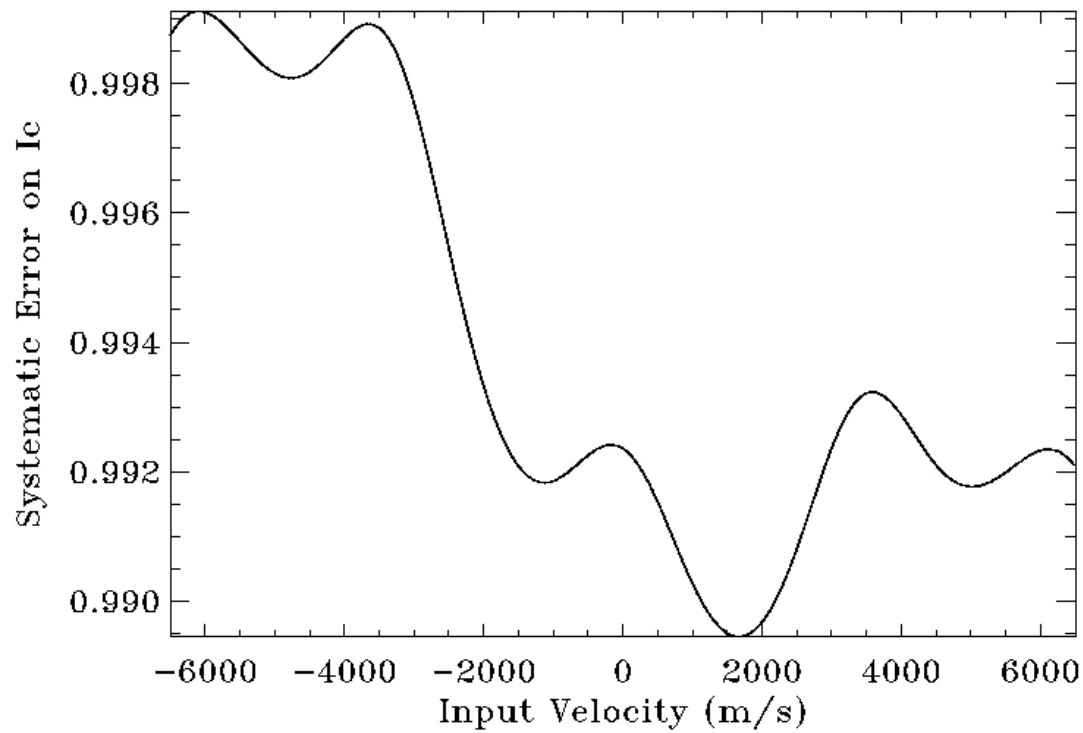
MDI-like algorithm, 6 filters, $v=0$



MDI-like algorithm, 6 filters, $B=0$

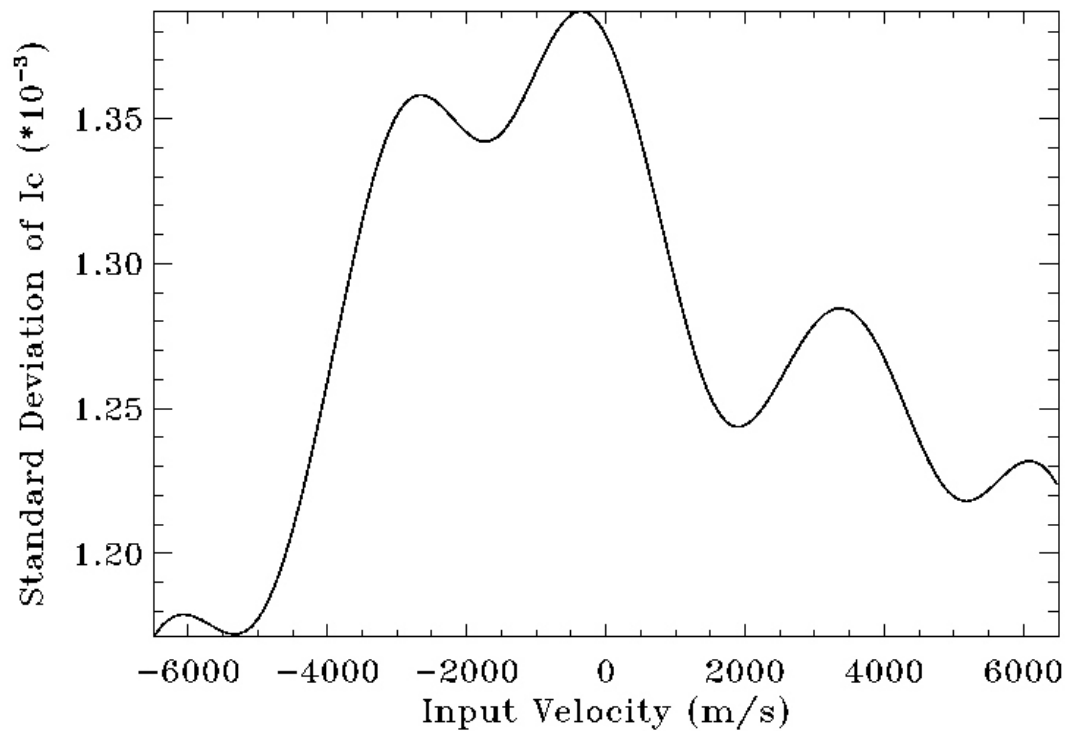


Errors on the Doppler velocity determination in the best case scenario, but with a lower full well (150,000 electrons)

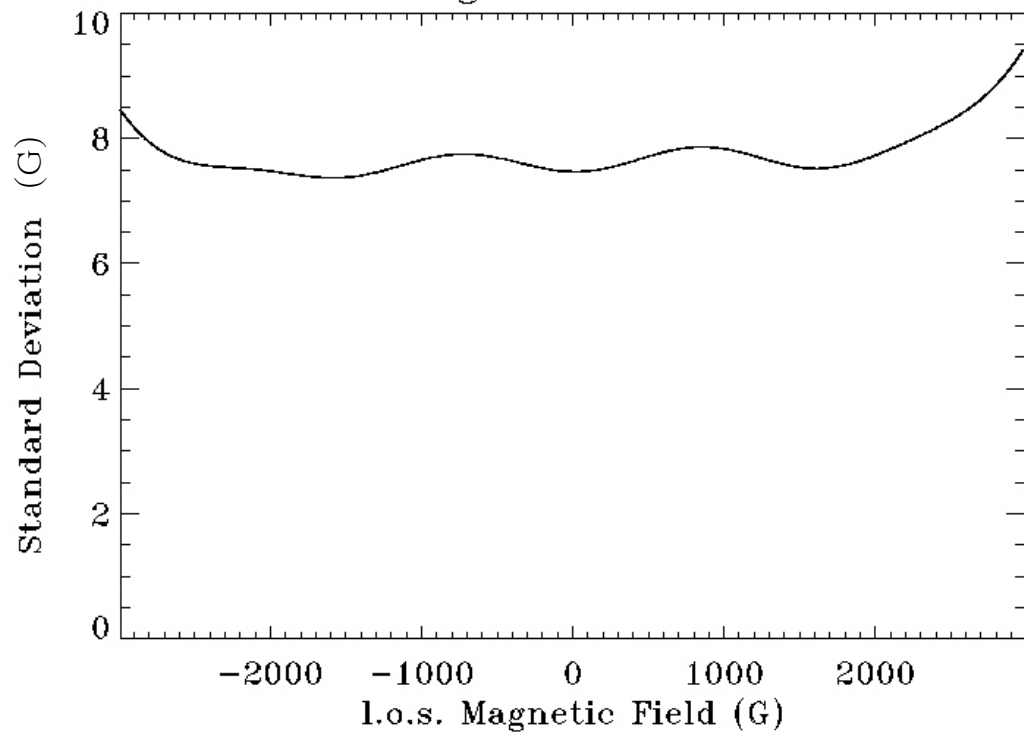


Error on continuum intensity I_c , when Fe I line modeled as $I(\lambda) = I_c - I_d \exp(-\lambda^2/\sigma^2)$

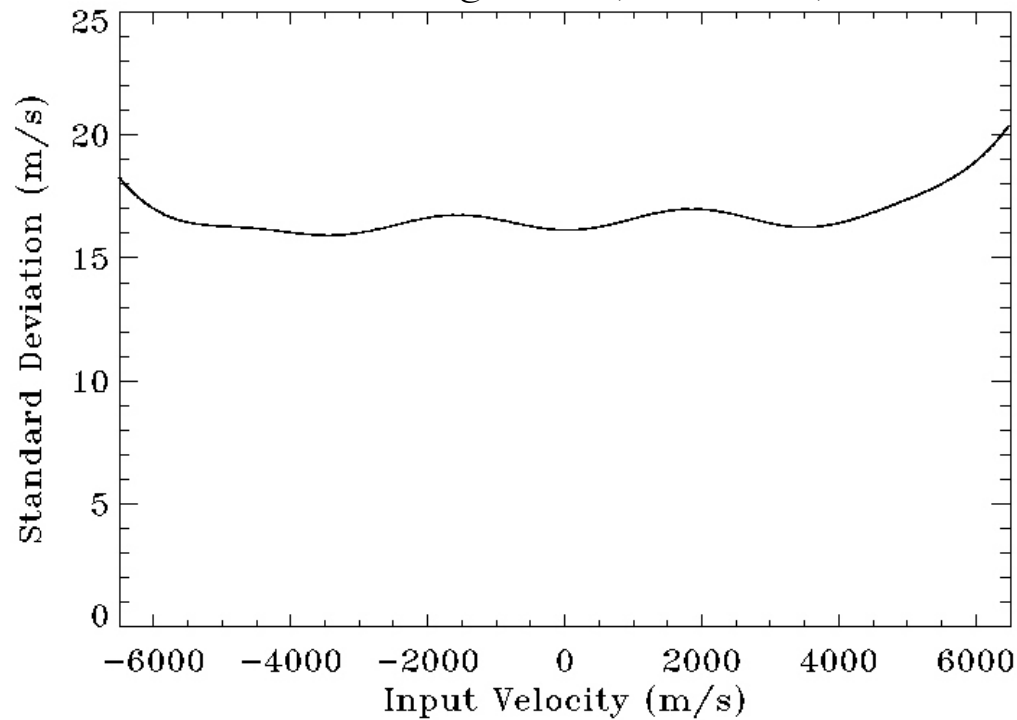
at disk center, $B=0$, full well = 150,000 electrons



MDI-like algorithm, 6 filters, $v=0$

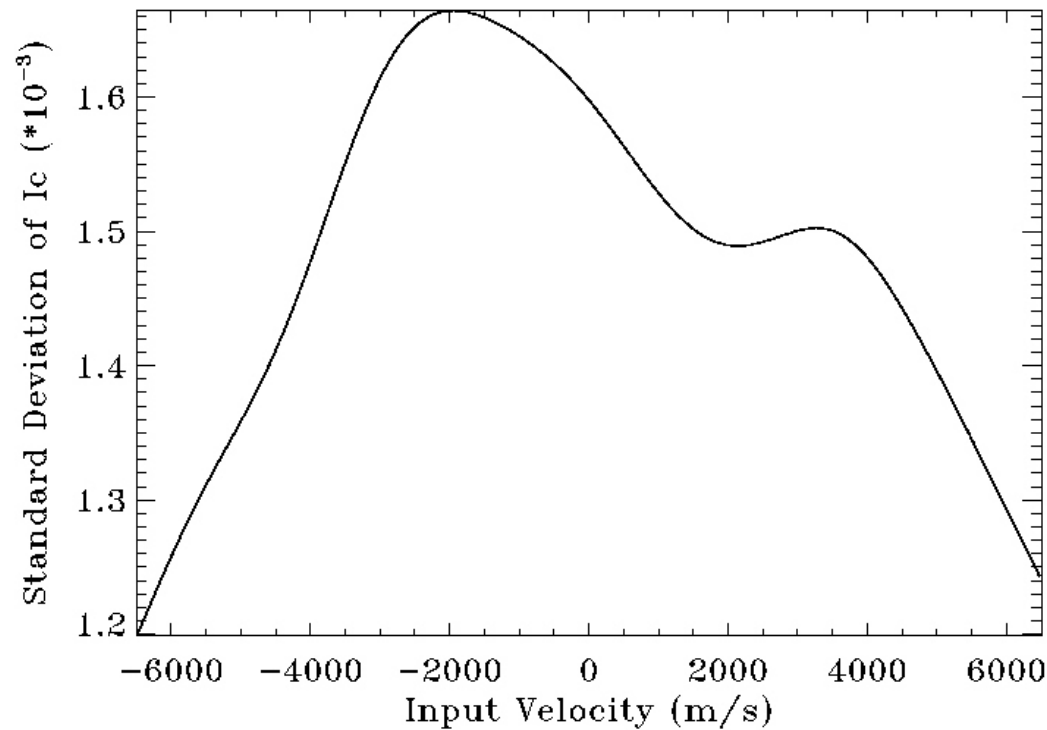
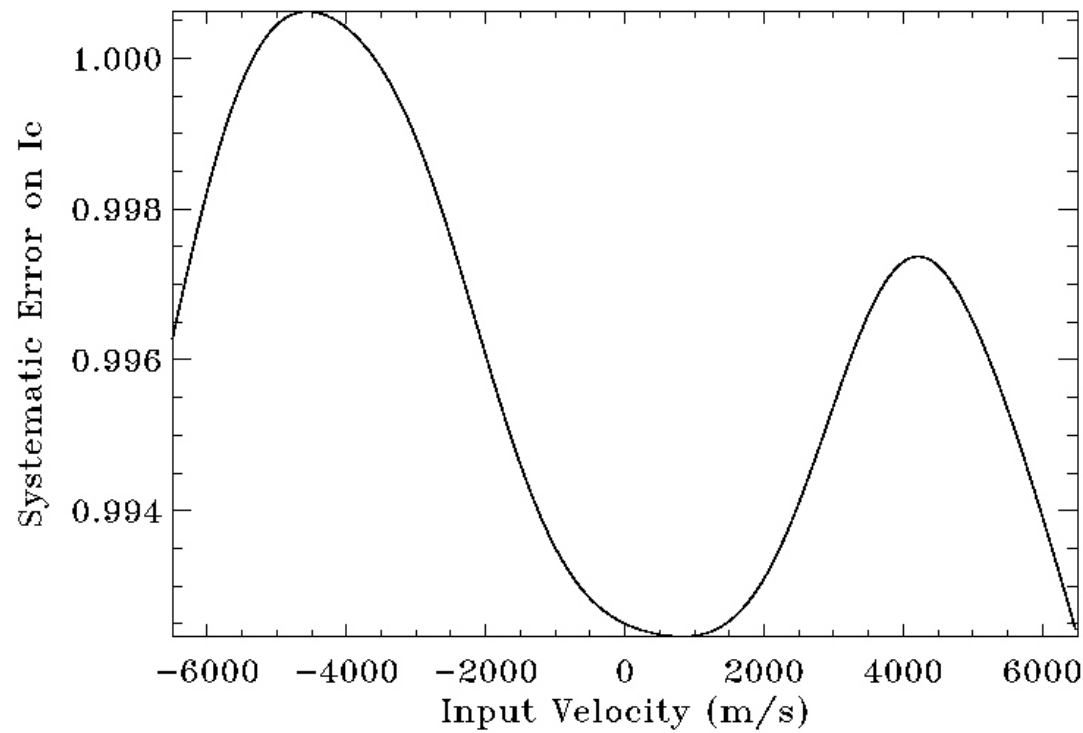


MDI-like algorithm, 6 filters, $B=0$



Error on Doppler
velocity and l.o.s. B.
At 60° from disk
center. Effects of:
-solar line broadening
-limb darkening

(full well= 200,000
electrons)

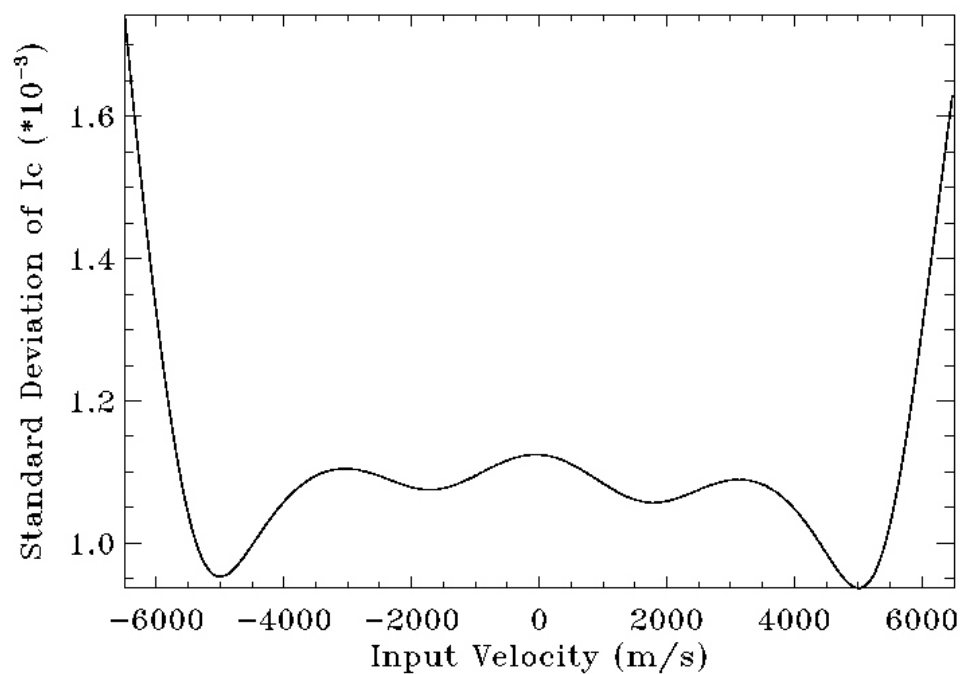
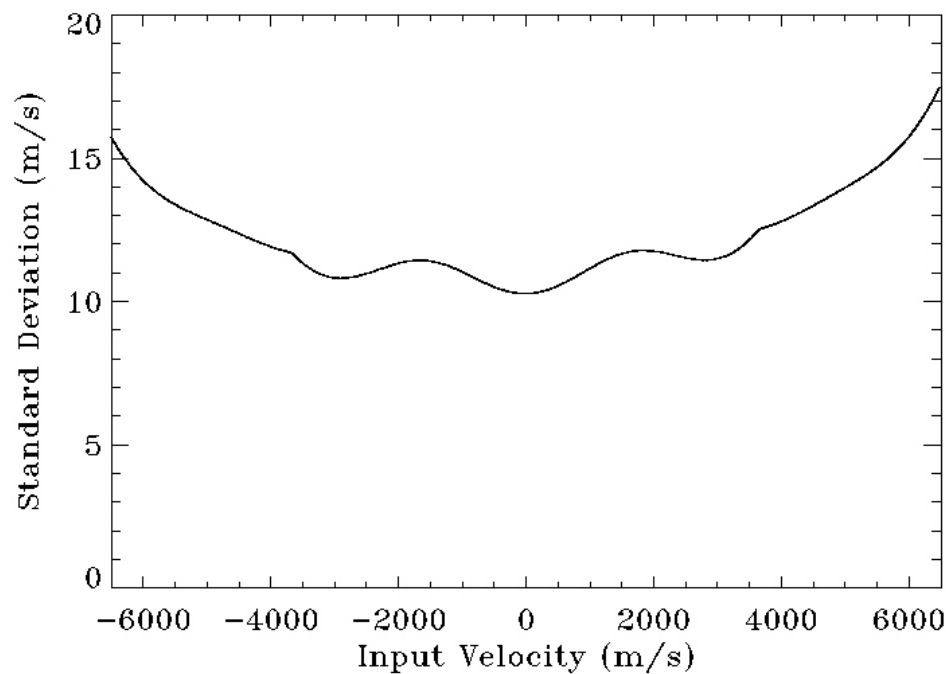
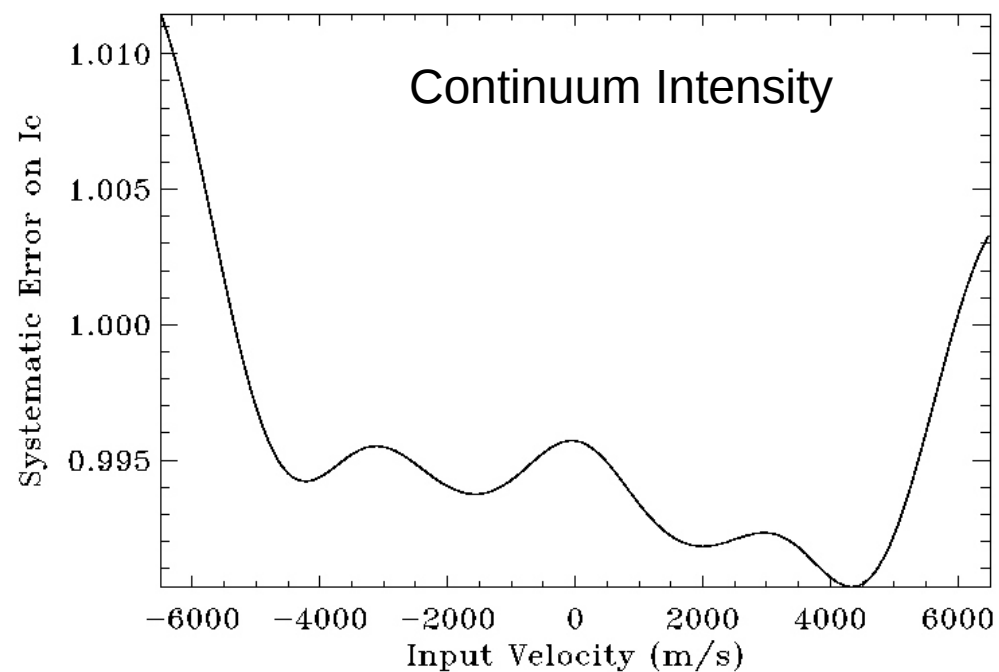
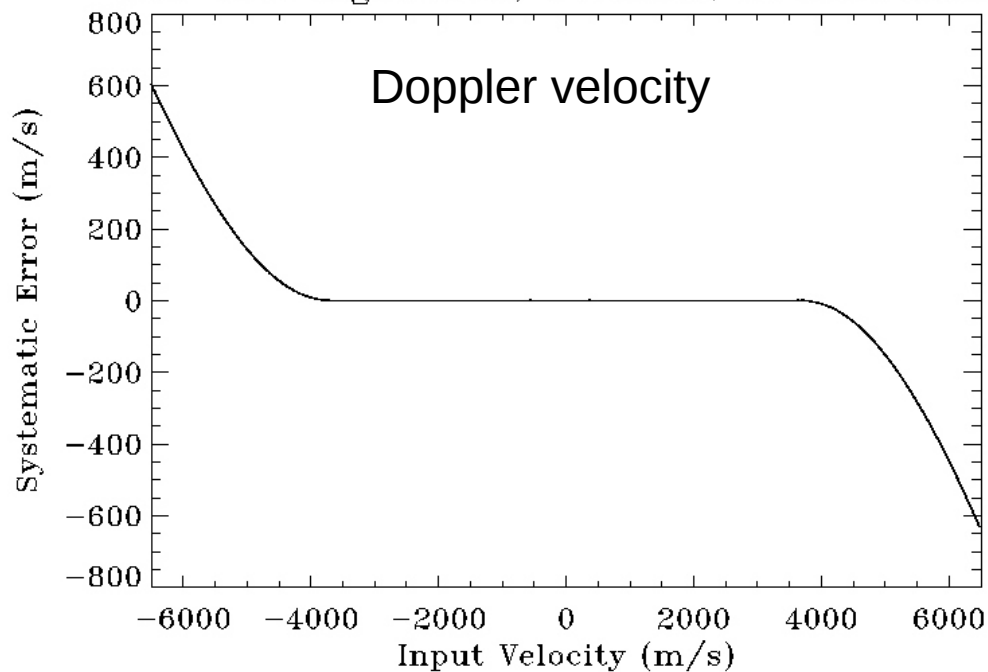


Error on continuum intensity.
At 60° from disk center. Effects of:
-solar line broadening
-limb darkening

(full well= 200,000 electrons)

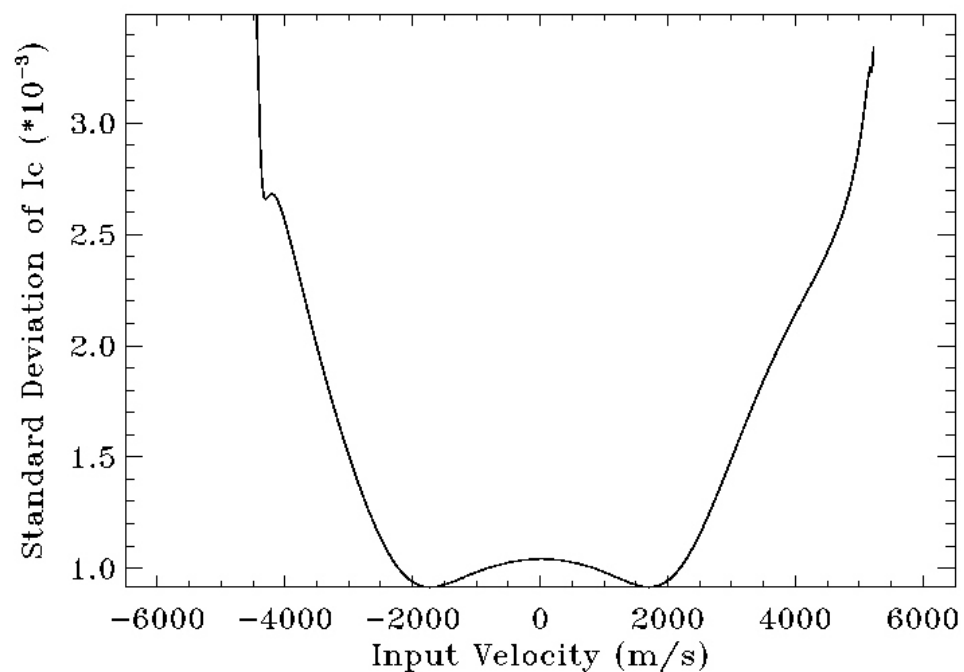
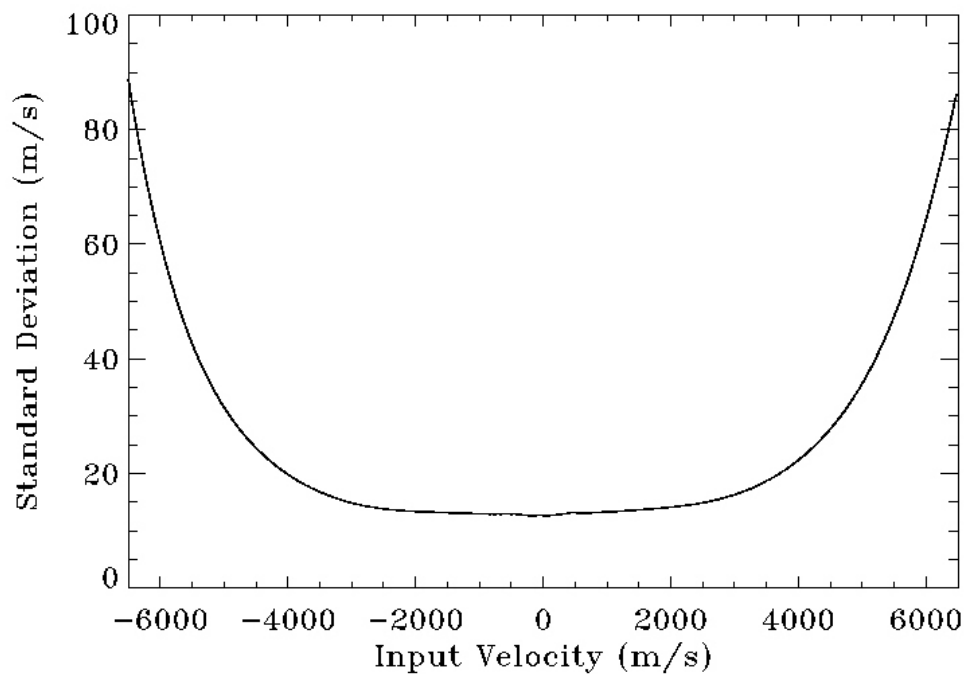
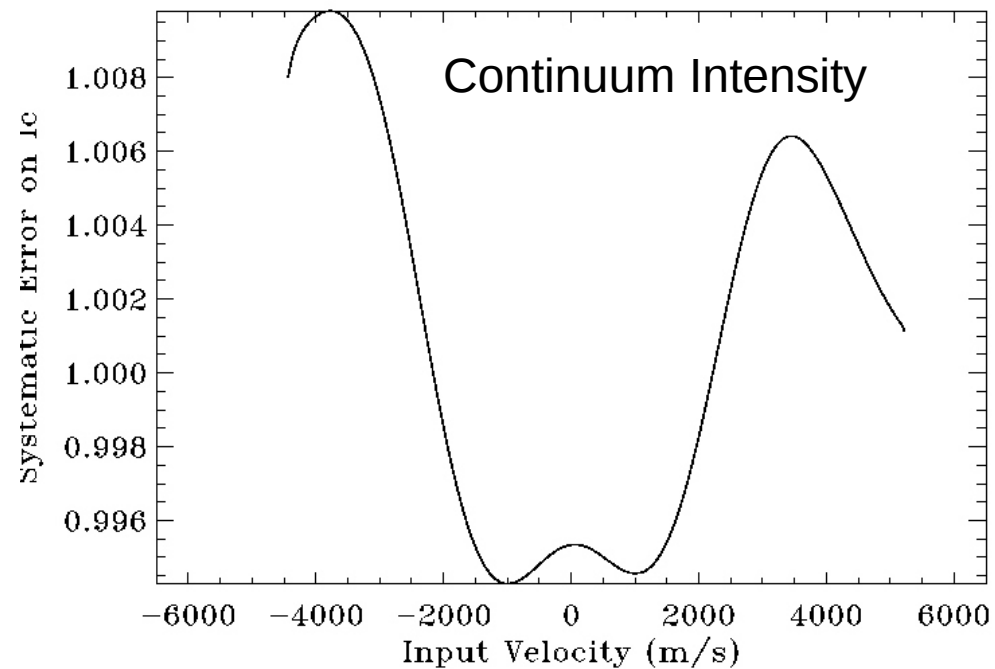
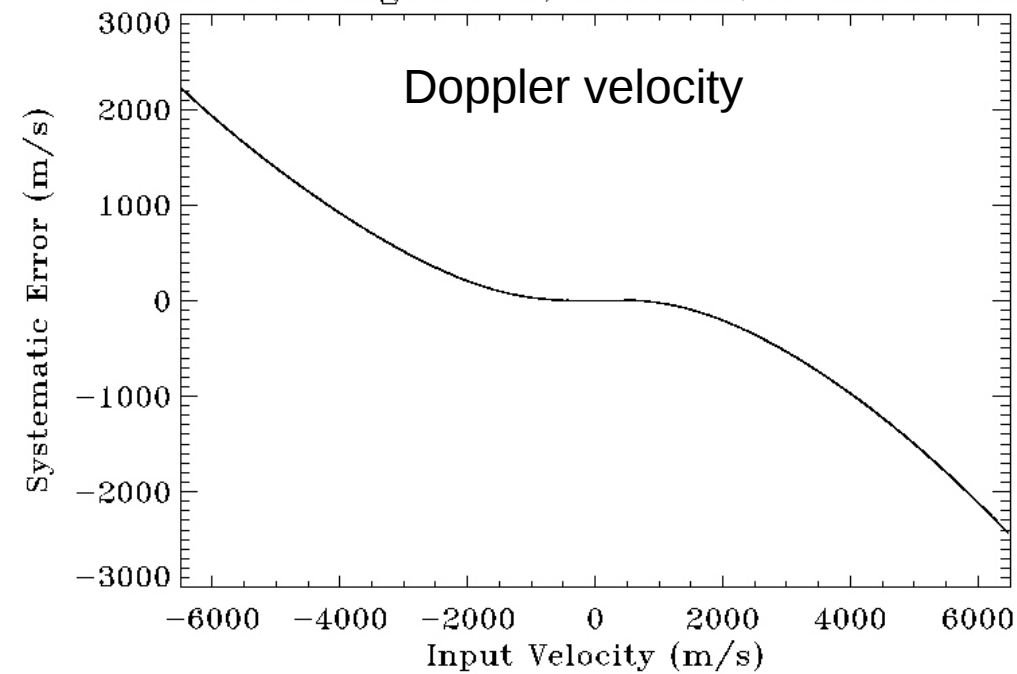
Impact of magnetic field: B = 1500 G

MDI-like algorithm, 6 filters, at disk center



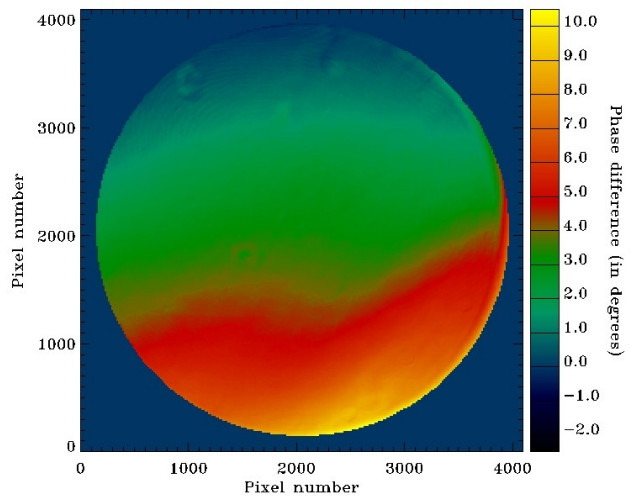
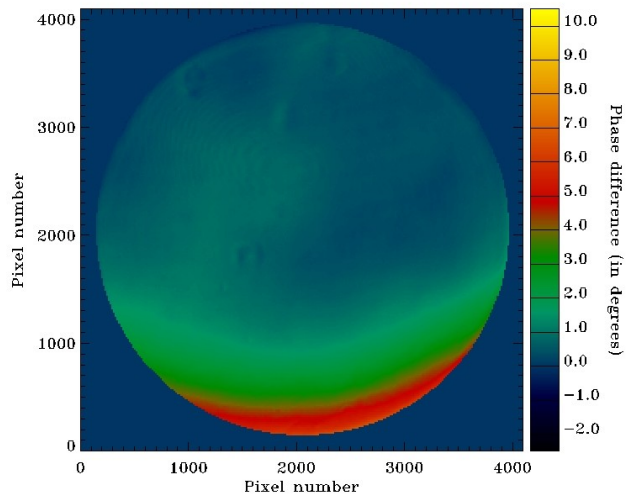
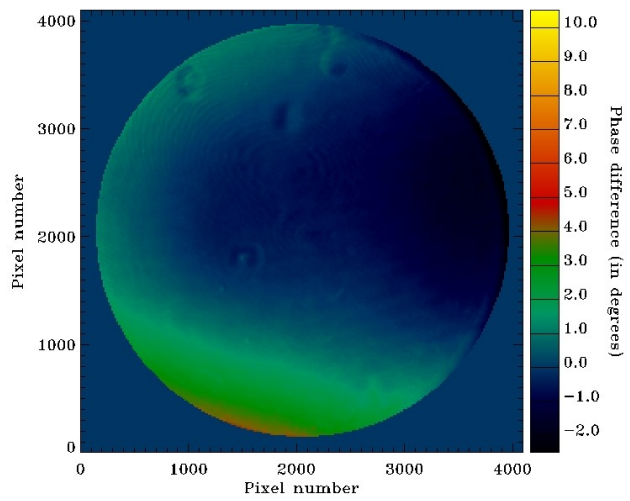
B = 3000 G

MDI-like algorithm, 6 filters, at disk center



Some Selected Sources of Error on the Observables and Their Impact on the Doppler Velocity

- Error on the determination of the phases and contrasts of the filter elements (*e.g.*, difference between Obsmode and Calmode)
- Presence of I-ripples not accounted for
- Simplistic model for solar line

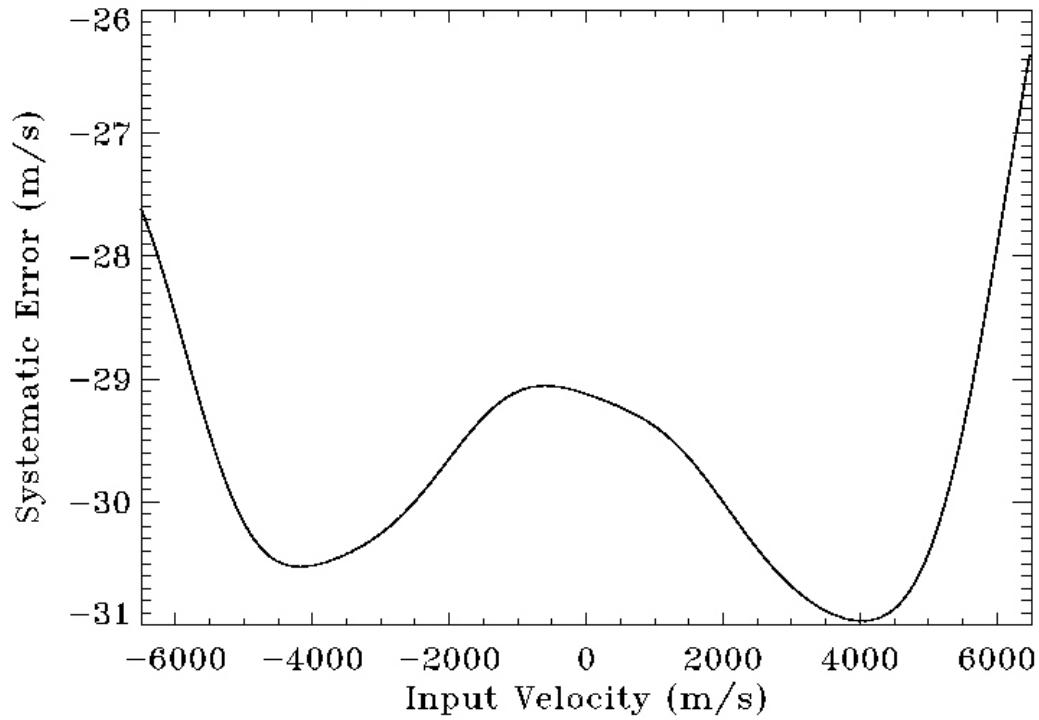


Phase differences between
Calmode and Obsmode

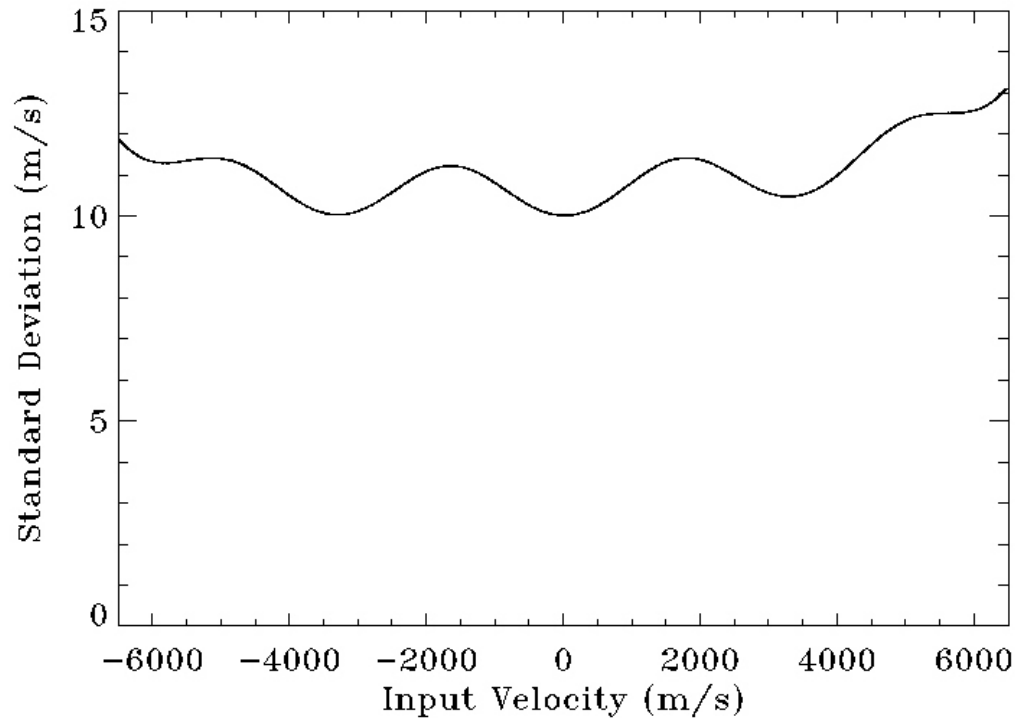
Definition of phase Φ :

$$I(\lambda) = [1 + B \cos(2\pi \lambda / \text{FSR} + \Phi)] / 2$$

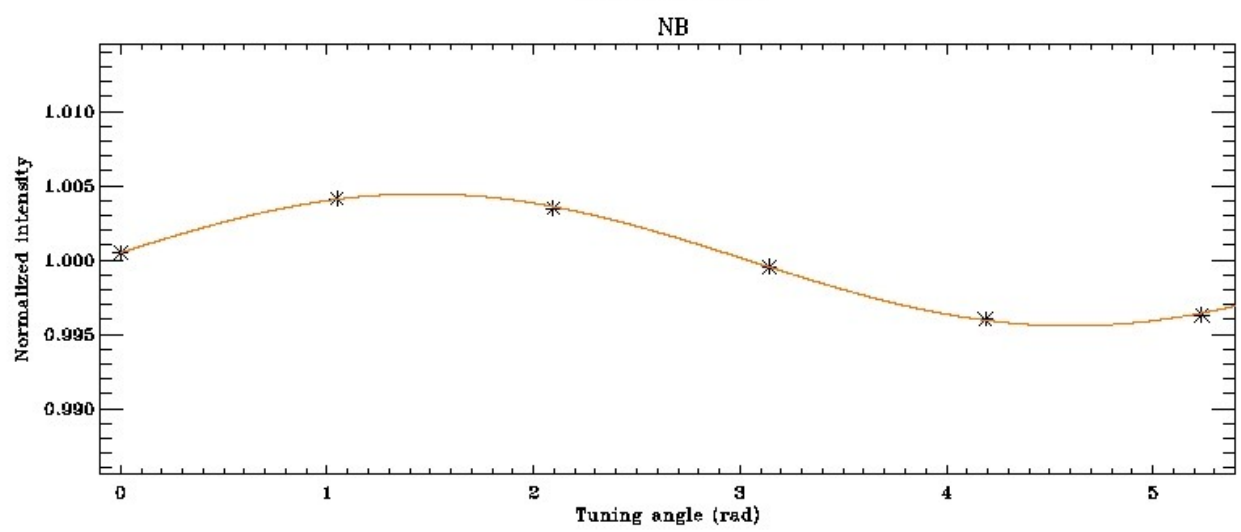
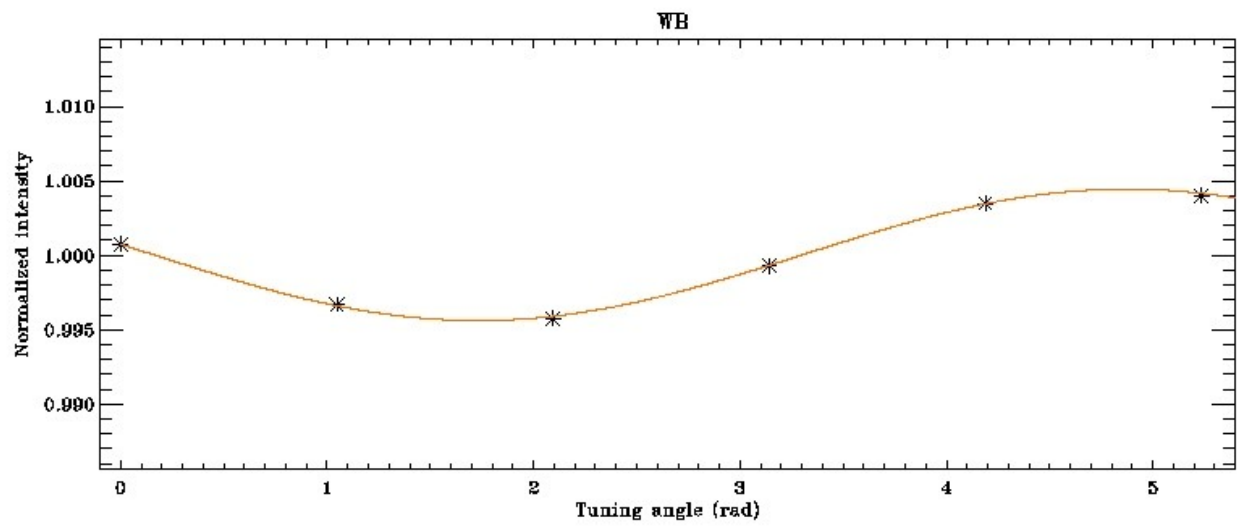
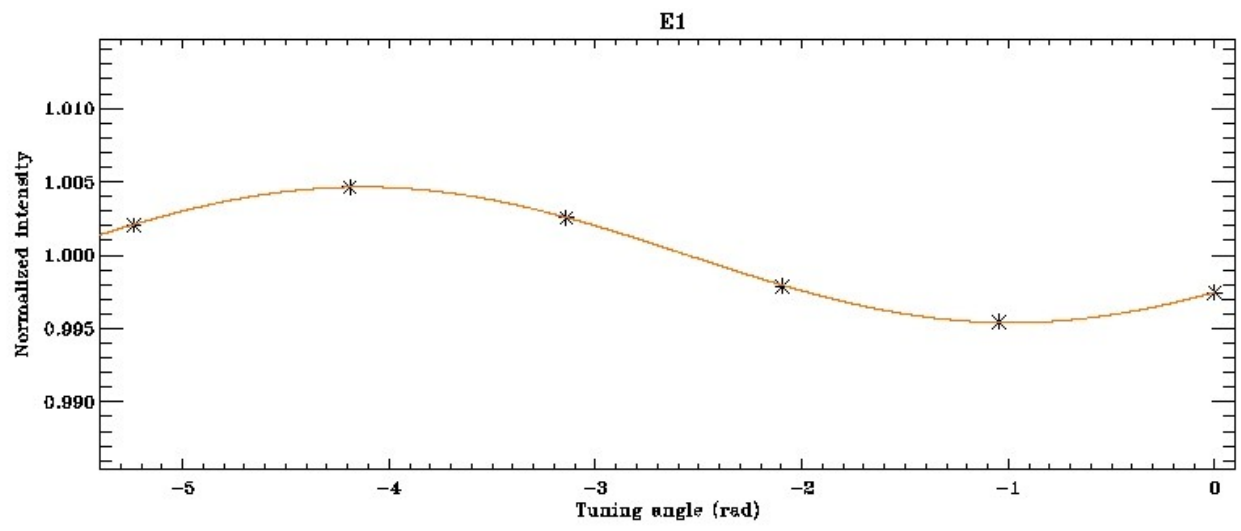
MDI-like algorithm, 6 filters, at disk center



Errors on the Doppler velocity determination when average phase differences between Obsmode and Calmode are not taken into account (1° for NB, 3° for E1).

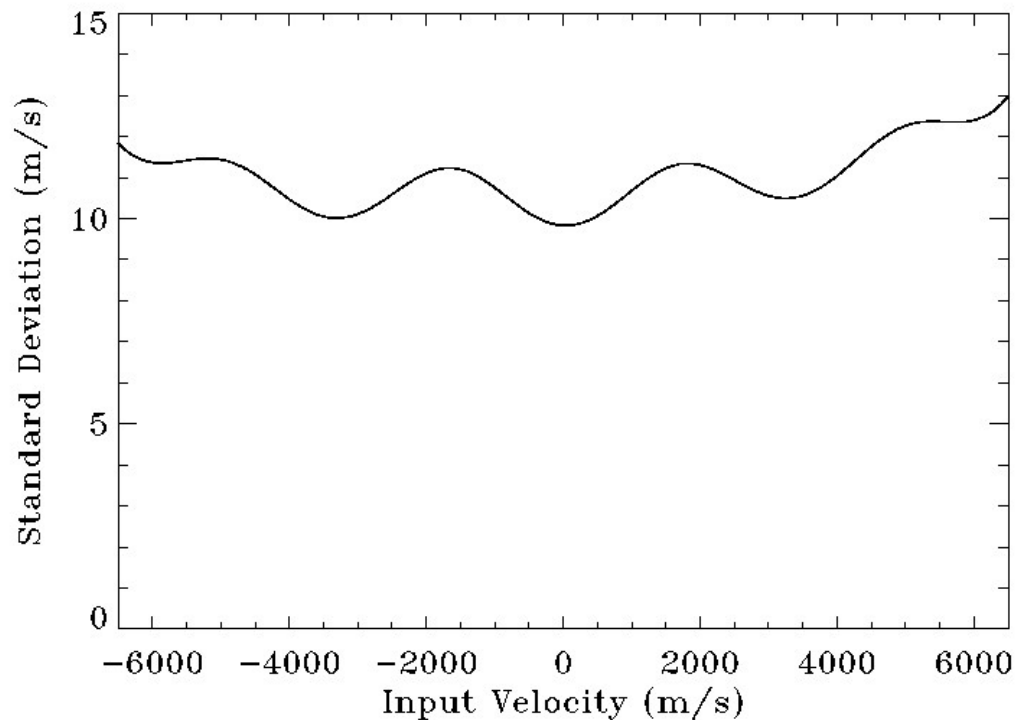
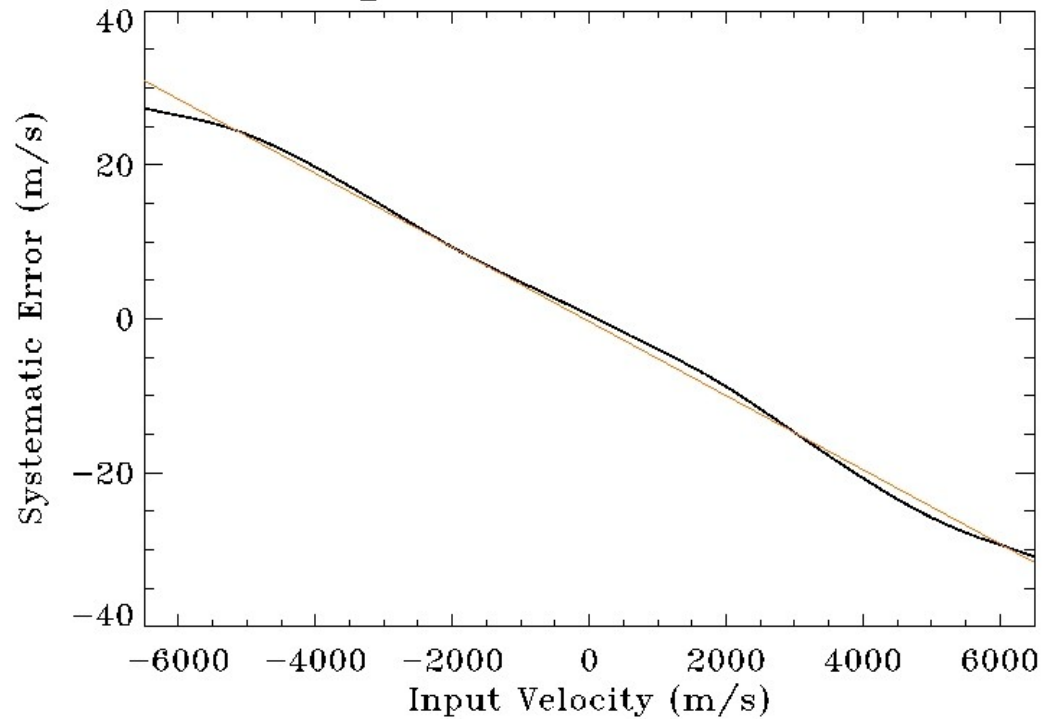


=> almost constant systematic error and no change in std deviation: therefore, not an issue



Individual I-ripples:
0.985%
0.858%
0.839%

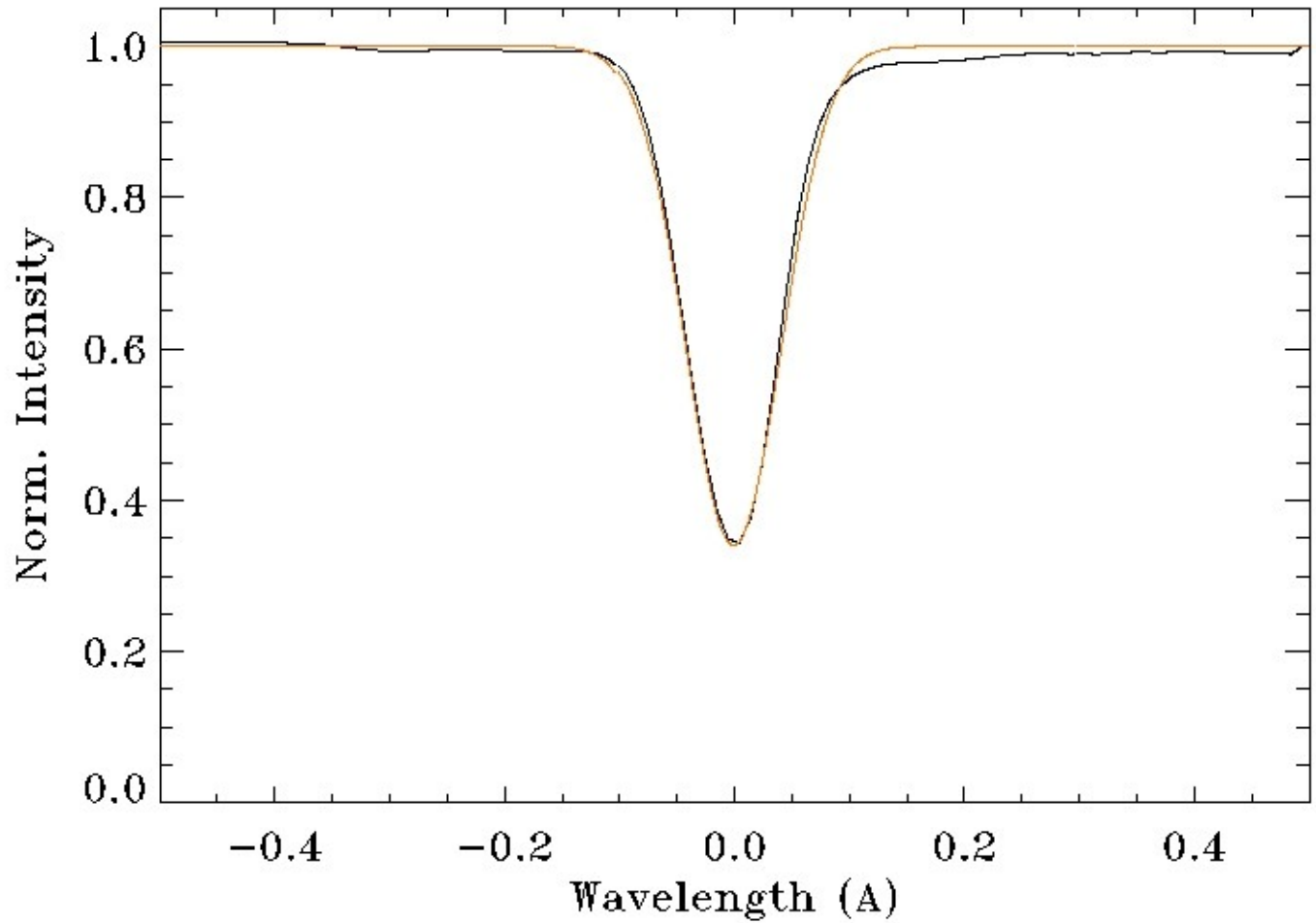
MDI-like algorithm, 6 filters, at disk center



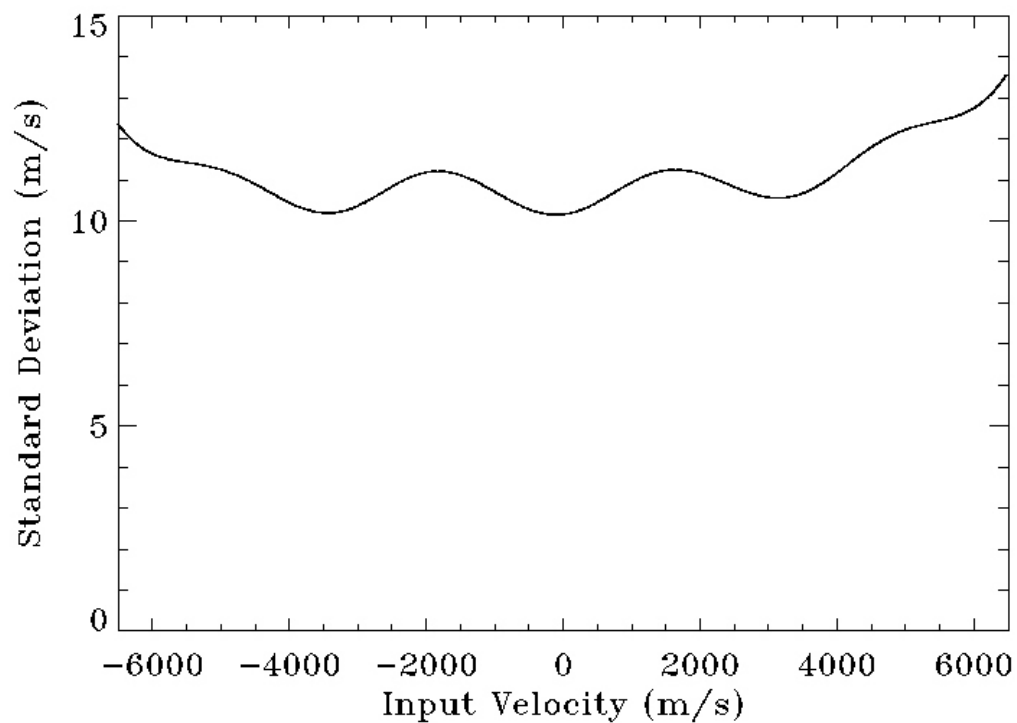
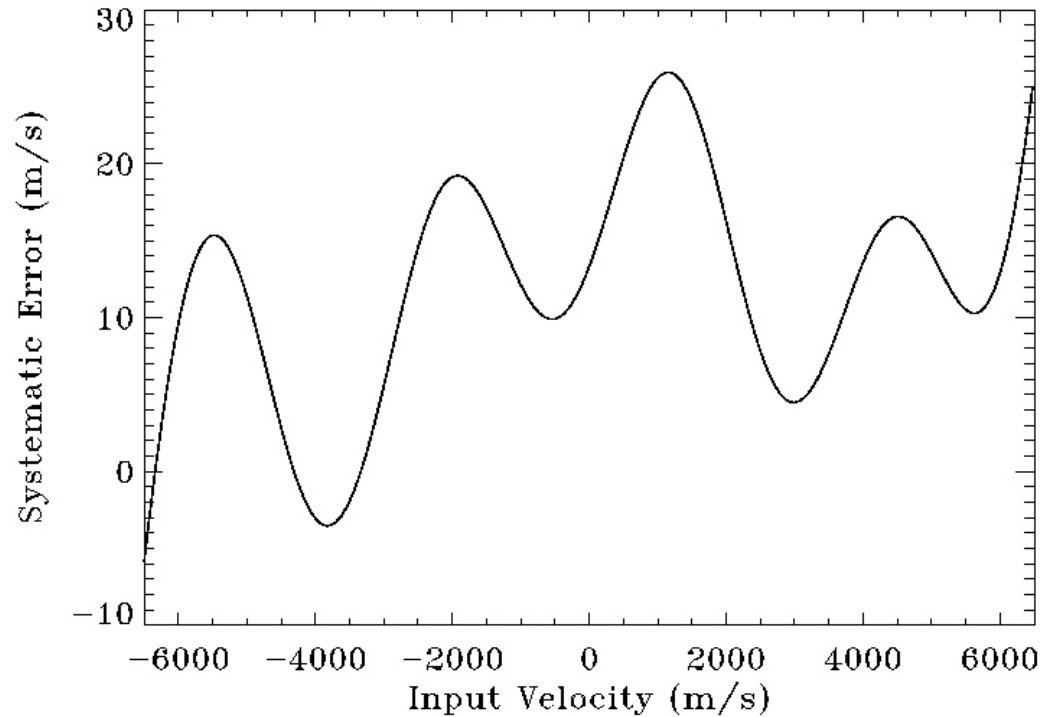
Errors on the Doppler velocity determination when I-ripple of E1 not accounted for in the transmittance models

=> almost linear systematic error and no change in std deviation: probably not an issue because we should be able to use SDO orbital velocity to correct for the systematic error

Black: actual Fe I line (from R. Ulrich) at disk center
Red: Gaussian model for the calculation of look-up tables



MDI-like algorithm, 6 filters, at disk center



Impact of solar line profile used (when Gaussian model is used instead of actual line profile)