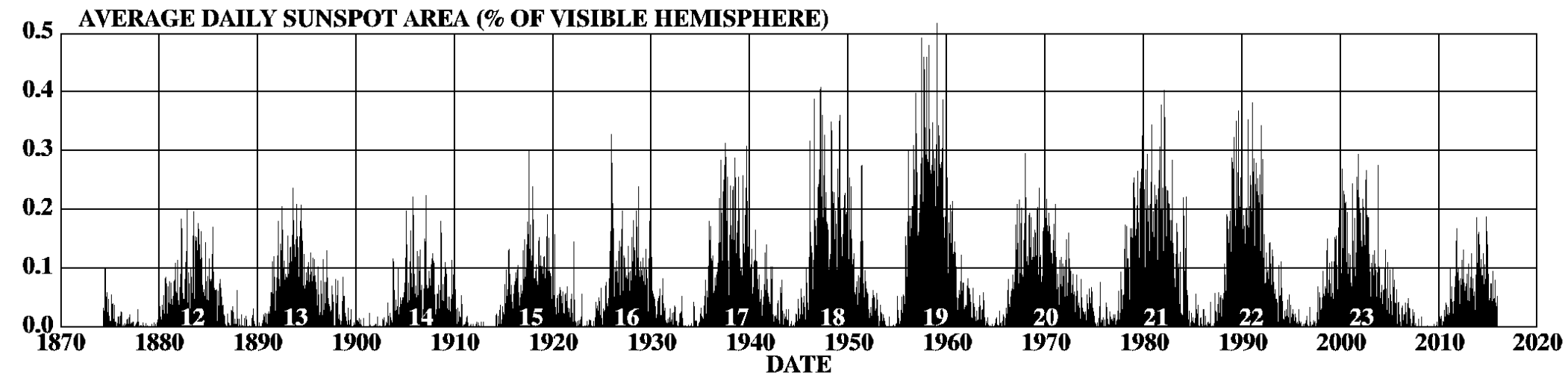
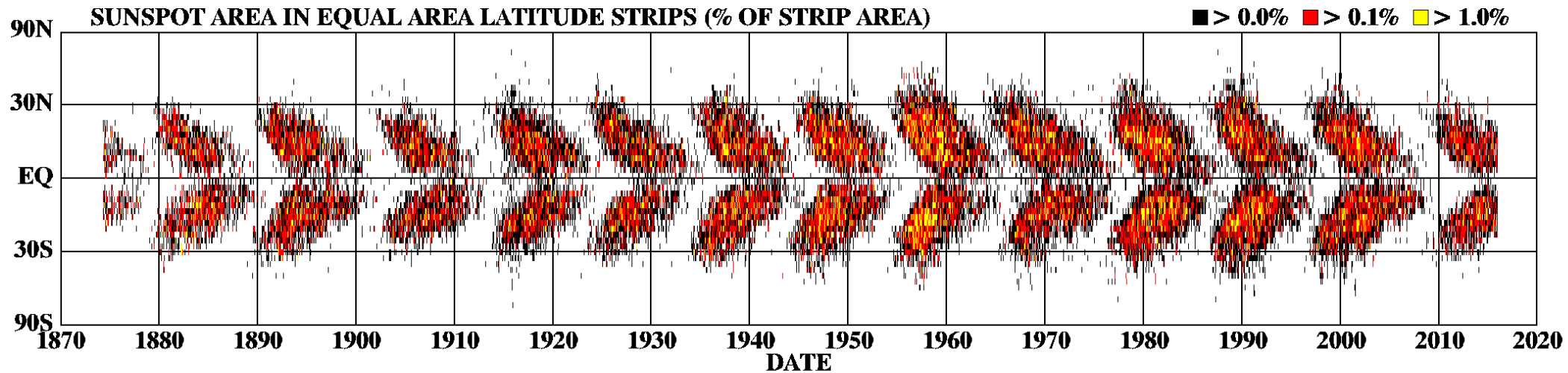


Global-Mode Helioseismology: Extensions of a Well-Used Method

tim defends his thesis
11 april 2016

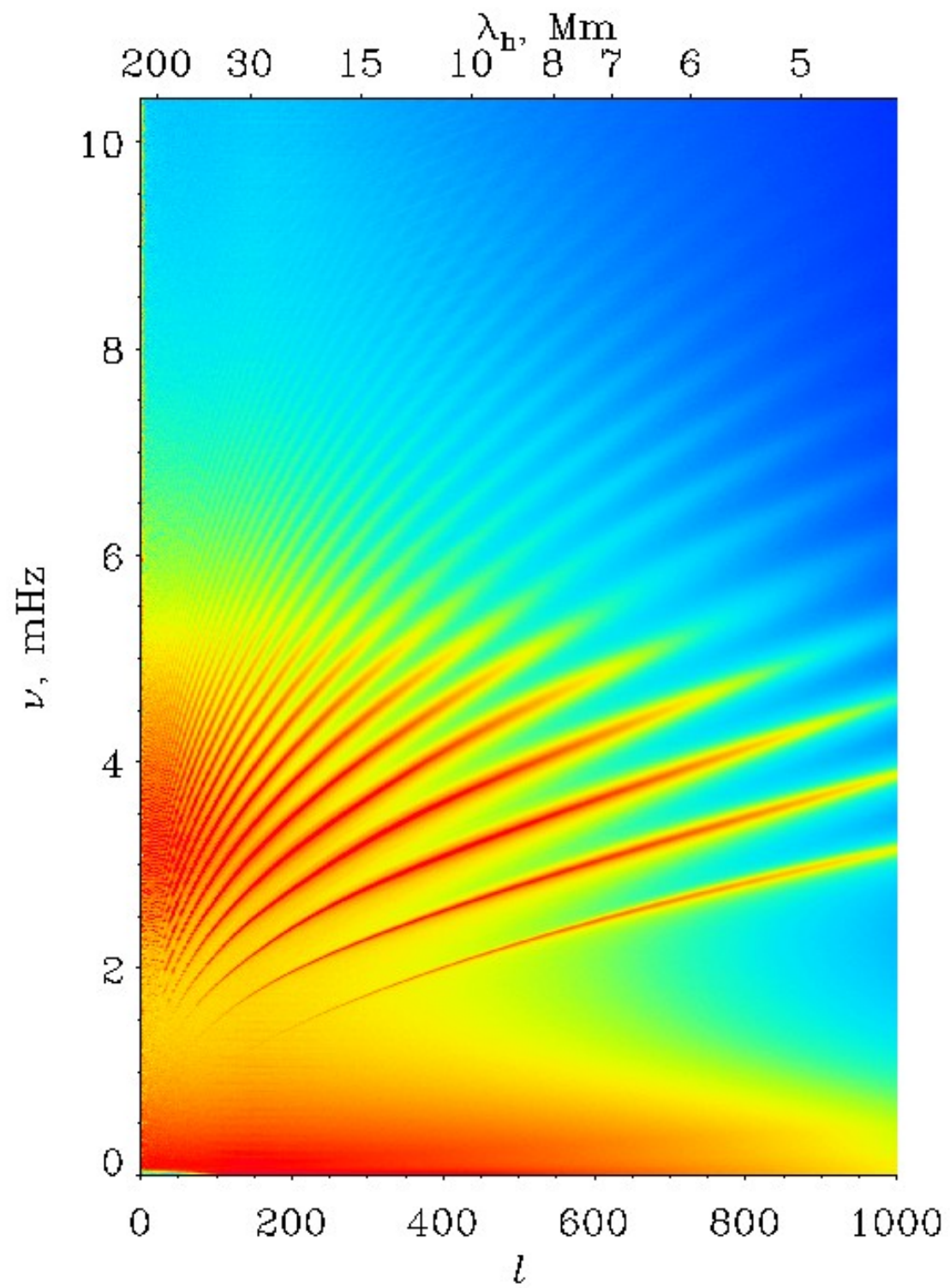
tplarson@sun.stanford.edu

DAILY SUNSPOT AREA AVERAGED OVER INDIVIDUAL SOLAR ROTATIONS



Where did helioseismology come from?

- Richard Carrington
- George Ellery Hale and Mount Wilson Observatory (MWO)
- Robert Leighton
- Roger Ulrich
- Franz Deubner
- Birmingham Solar Oscillation Network (BiSON)
- Tom Duvall and Jack Harvey
- Ed Rhodes and the 60-foot Solar Tower at MWO



Modern Helioseismic Instruments

(relevant to this work)

- Mount Wilson Observatory MWO
- Global Oscillation Network Group GONG
- Michelson Doppler Imager MDI
- Helioseismic and Magnetic Imager HMI

Mathematical Preliminaries

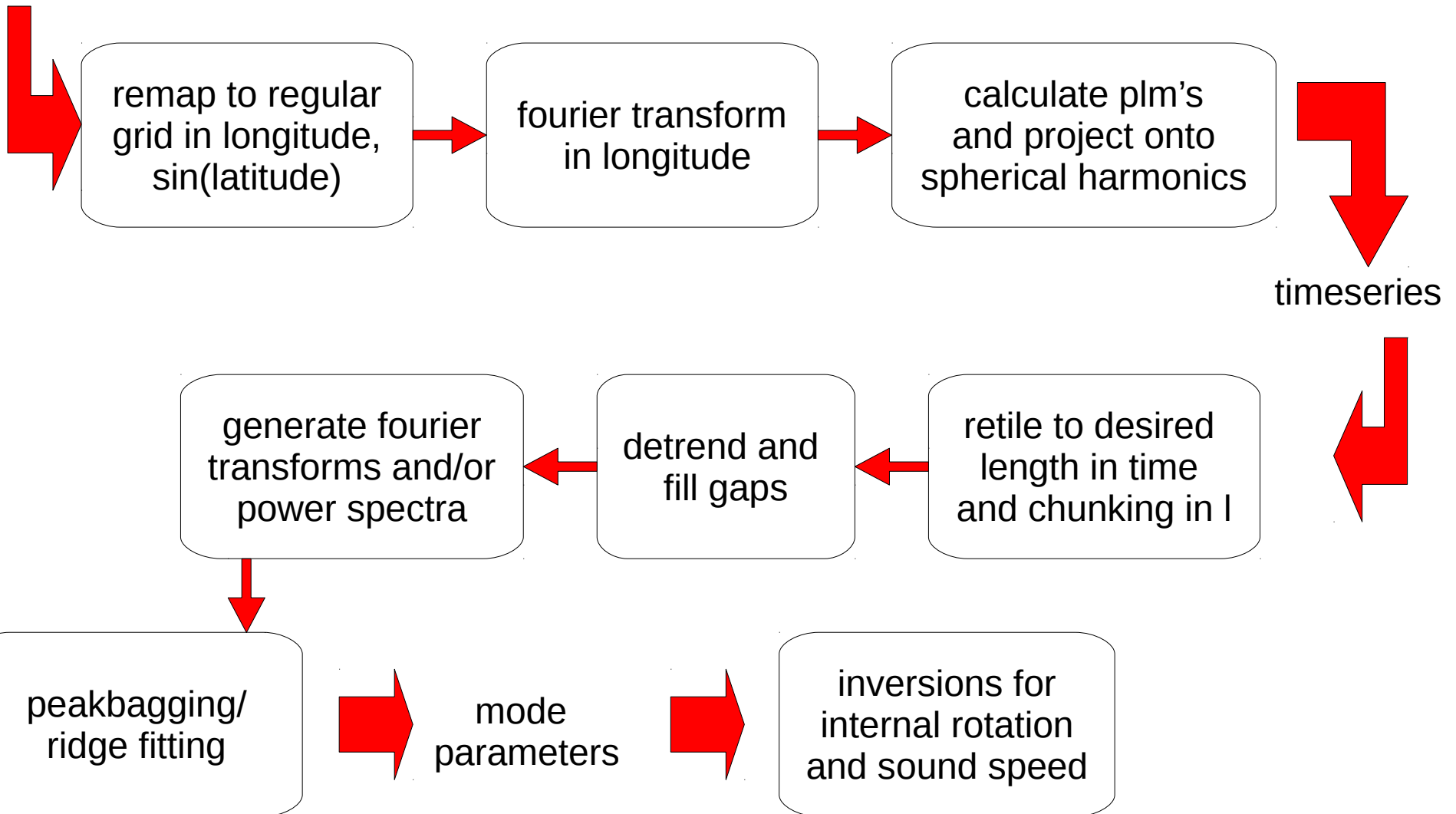
$$\frac{\partial \rho}{\partial t} + \operatorname{div}(\rho \mathbf{v}) = 0 \quad \text{continuity}$$

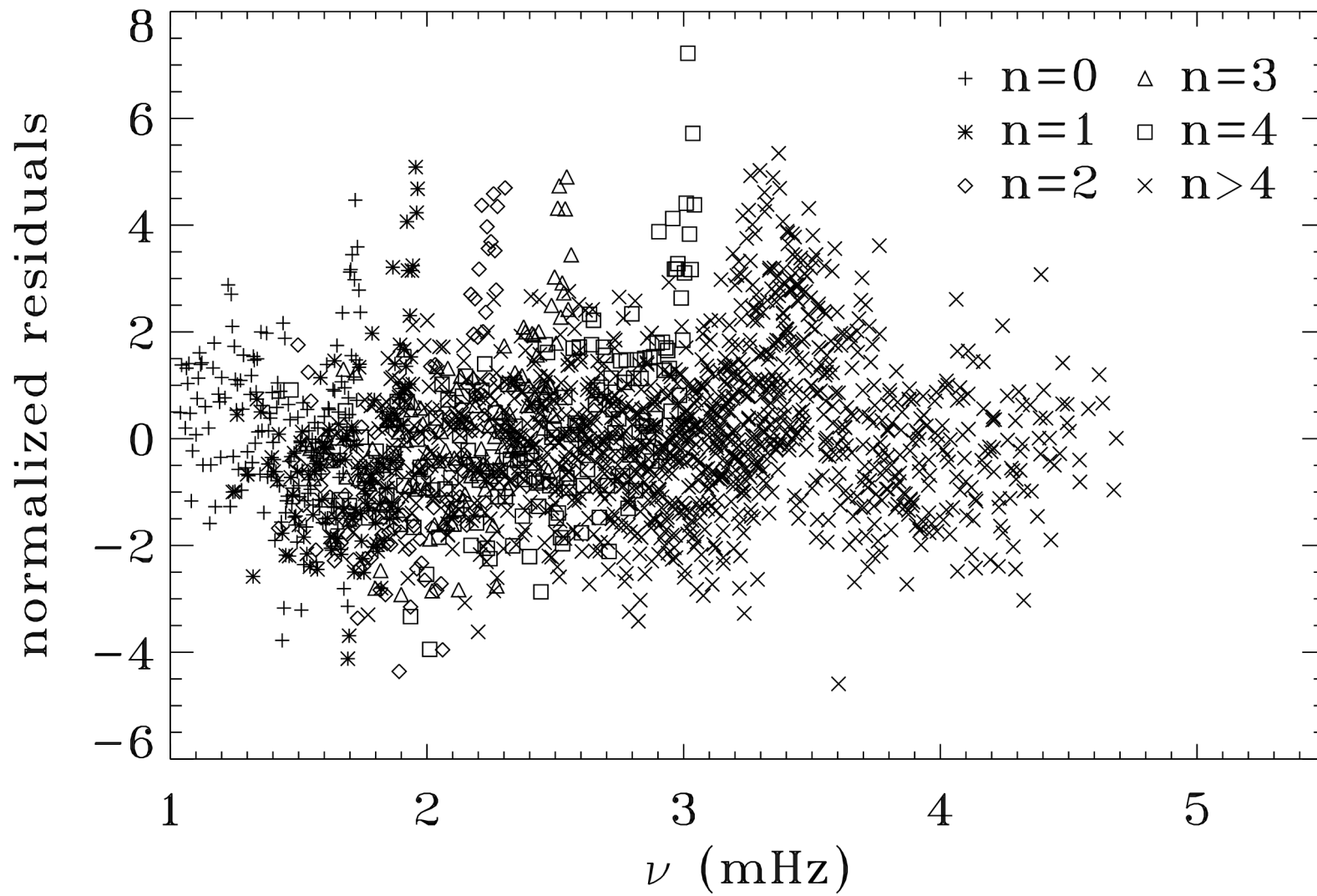
$$\rho \frac{\partial \mathbf{v}}{\partial t} + \rho \mathbf{v} \cdot \nabla \mathbf{v} = -\nabla p + \rho \mathbf{f}$$
$$\mathbf{g} = -\nabla \Phi \quad \nabla^2 \Phi = 4\pi G \rho$$

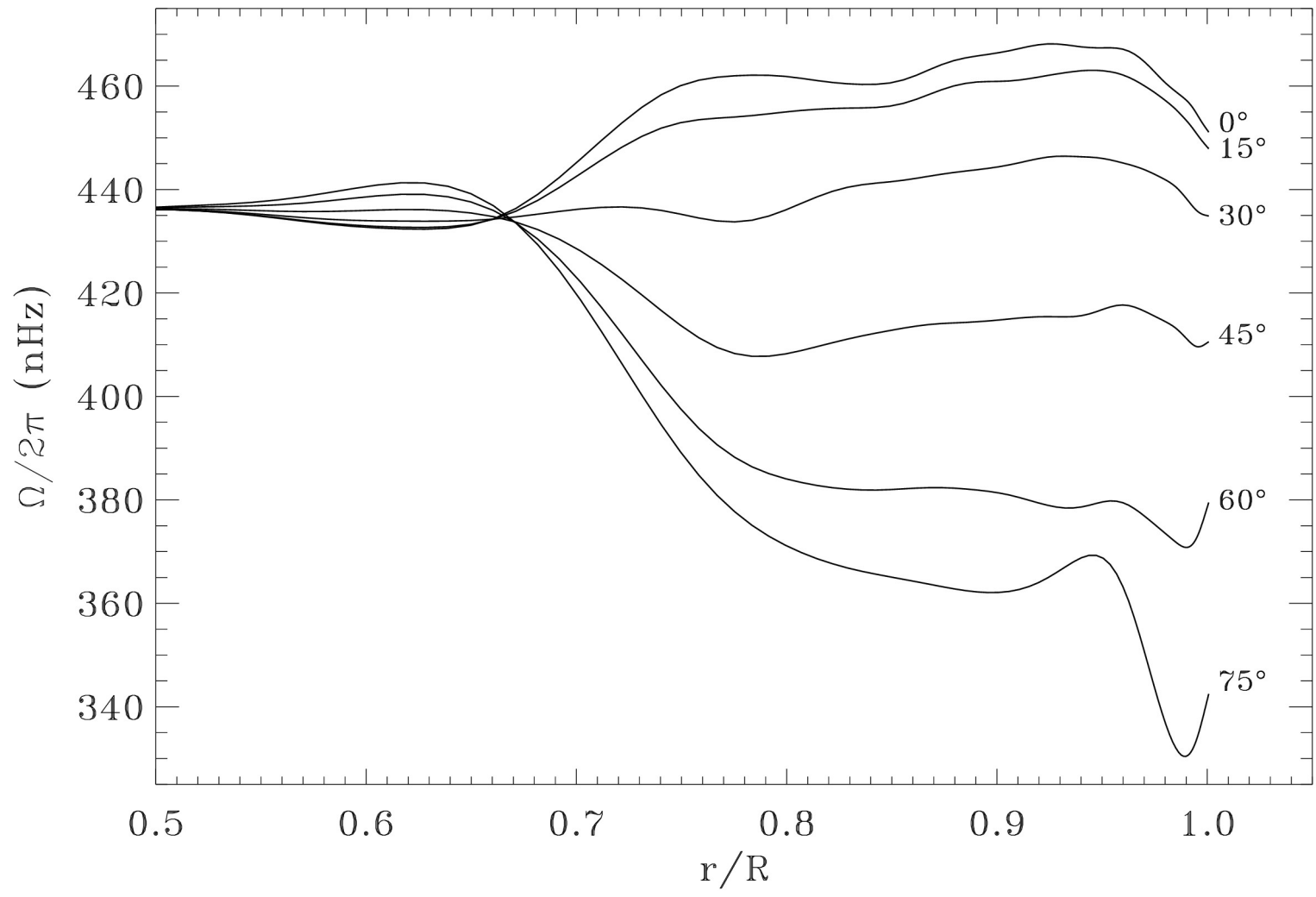
equations of motion

$$\frac{dp}{dt} = \frac{\Gamma_1 p}{\rho} \frac{d\rho}{dt} \quad \text{adiabaticity}$$

dopplergrams







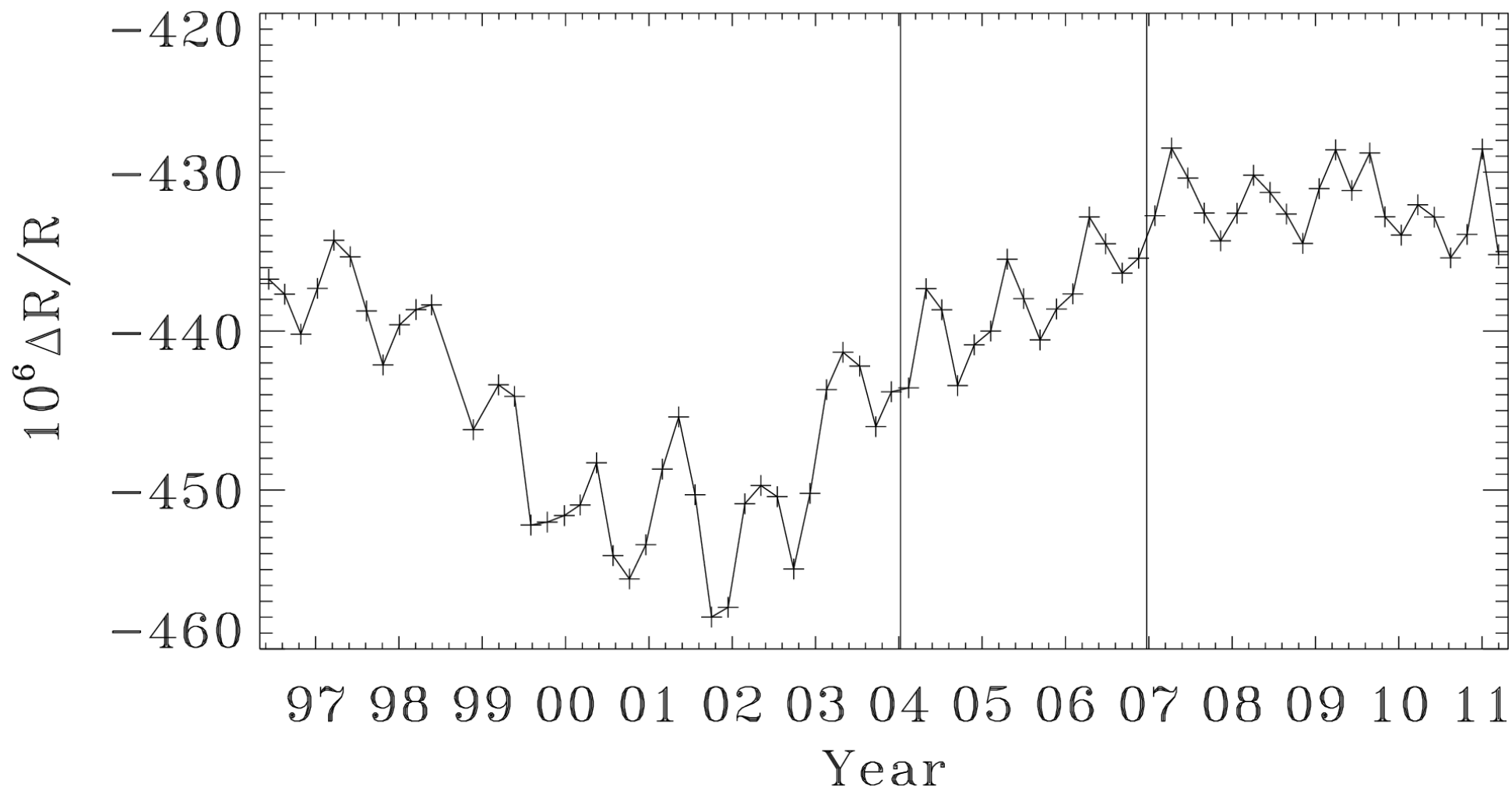


Table 2. Sequence of changes made to the analysis; each analysis includes the changes made in all previous ones.

- 0 original analysis
- 1 image scale
- 2 cubic distortion
- 3 CCD misalignment
- 4 inclination error
- 5 CCD tilt
- 6 window functions and detrending
- 7 gapfilling
- 8 horizontal displacement
- 9 distortion of eigenfunctions (“Woodard effect”)
- 10 asymmetric line profiles

Image Scale

$$f(t) = b_0 + D[b_1 + b_2(t - t_0) + b_3(t - t_0)^2]$$

fit to $(A_{\text{major}} + A_{\text{minor}})/(2R_0)$

Optical Distortion

$$C_{\text{dist}}(r^2 - R^2)$$

$$C_{\text{dist}} = 7.06 \times 10^{-9}$$

Angle Corrections

$$B'_0 = B_0 + \delta I \sin[2\pi(t_{\text{obs}} - t_{\text{ref}})]$$

$$P'_{\text{eff}} = P_{\text{eff}} + \delta P + \delta I \cos[2\pi(t_{\text{obs}} - t_{\text{ref}})]$$

$$\delta P = 0.2^\circ \quad \delta I = 0.1^\circ$$

Ellipticity

$$x' = x \cos \beta + y \sin \beta,$$

$$y' = -x \sin \beta + y \cos \beta.$$

$$x'' = x' \left(1 + \frac{y'}{f} \alpha \right) - x' \frac{\alpha^2}{4},$$

$$y'' = y' \left(1 + \frac{\alpha^2}{2} + \frac{y'}{f} \alpha \right) - y' \frac{\alpha^2}{4} - \frac{r_m^2}{f} \alpha,$$

Gapfilling

$$x_t = \sum_{j=1}^L \alpha_j x_{t-j} + e_t^f. \quad (1)$$

The coefficients α_j are the model parameters to be determined. The parameter e_t^f is most easily interpreted when equation (1) is written in the form

$$e_t^f = x_t - \sum_{j=1}^L \alpha_j x_{t-j} = \sum_{j=0}^L \gamma_j x_{t-j}. \quad (2)$$

$$\frac{de}{d\alpha_K} = 0, \quad (5)$$

where

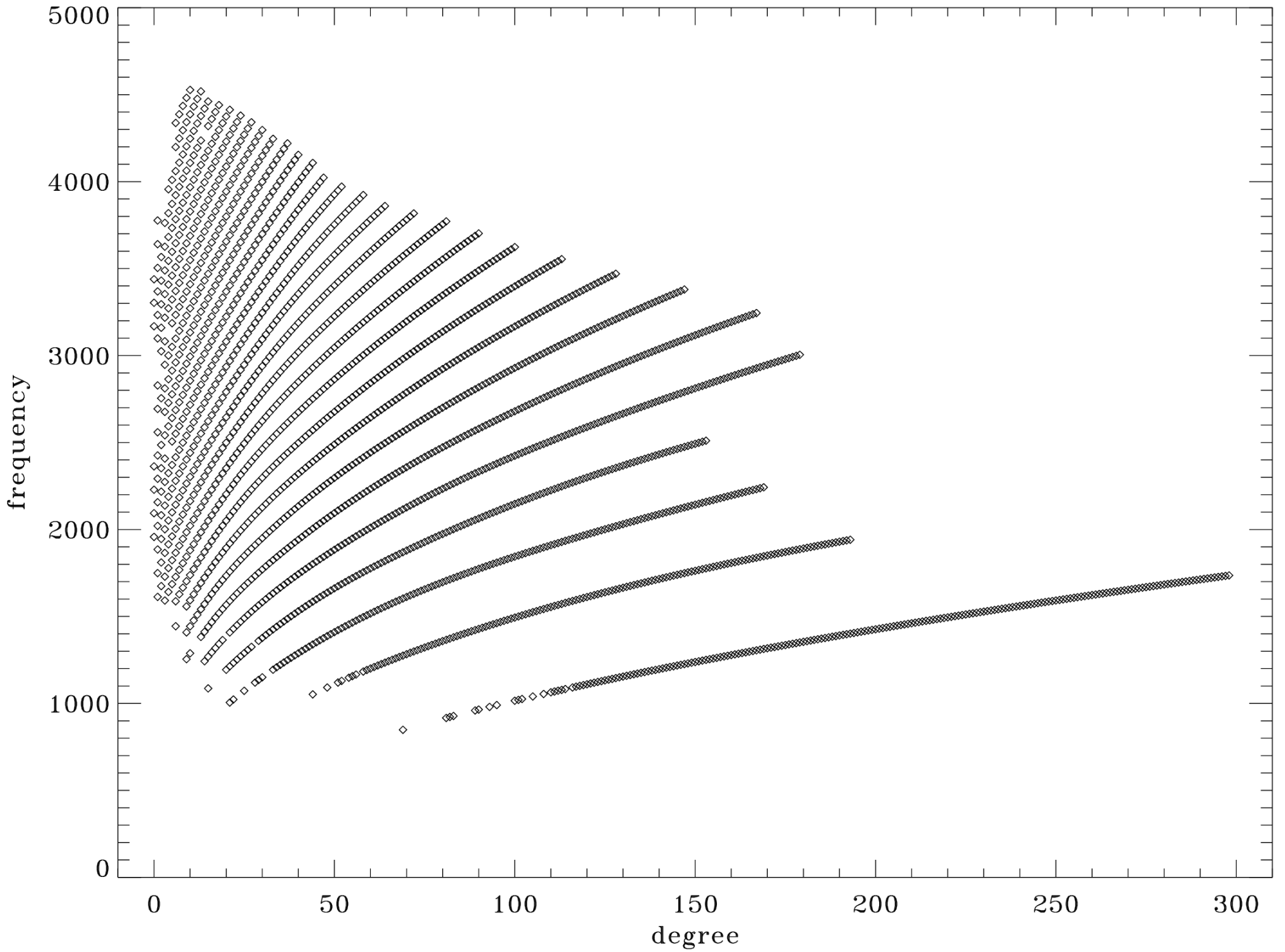
$$\epsilon = \sum_{q=1}^Q \sum_{t=M_q+K+1}^{N_q} (e_t^f)^2 + \sum_{t=M_q+1}^{N_q-K} (e_t^b)^2.$$

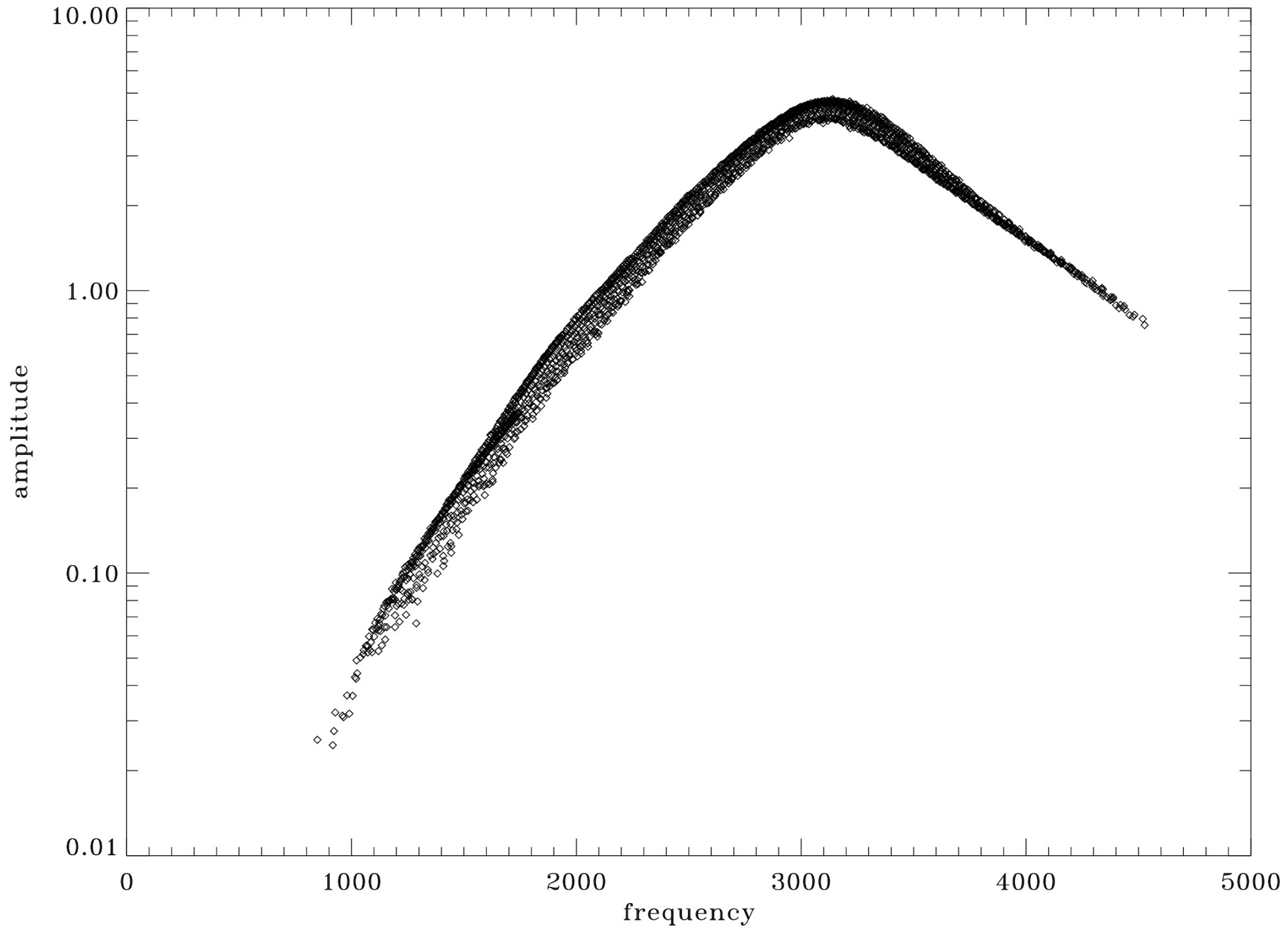
$$\frac{\partial \epsilon_q}{\partial x_t} = 0, \quad t = (N_q + 1, M_{q+1}), \quad (9)$$

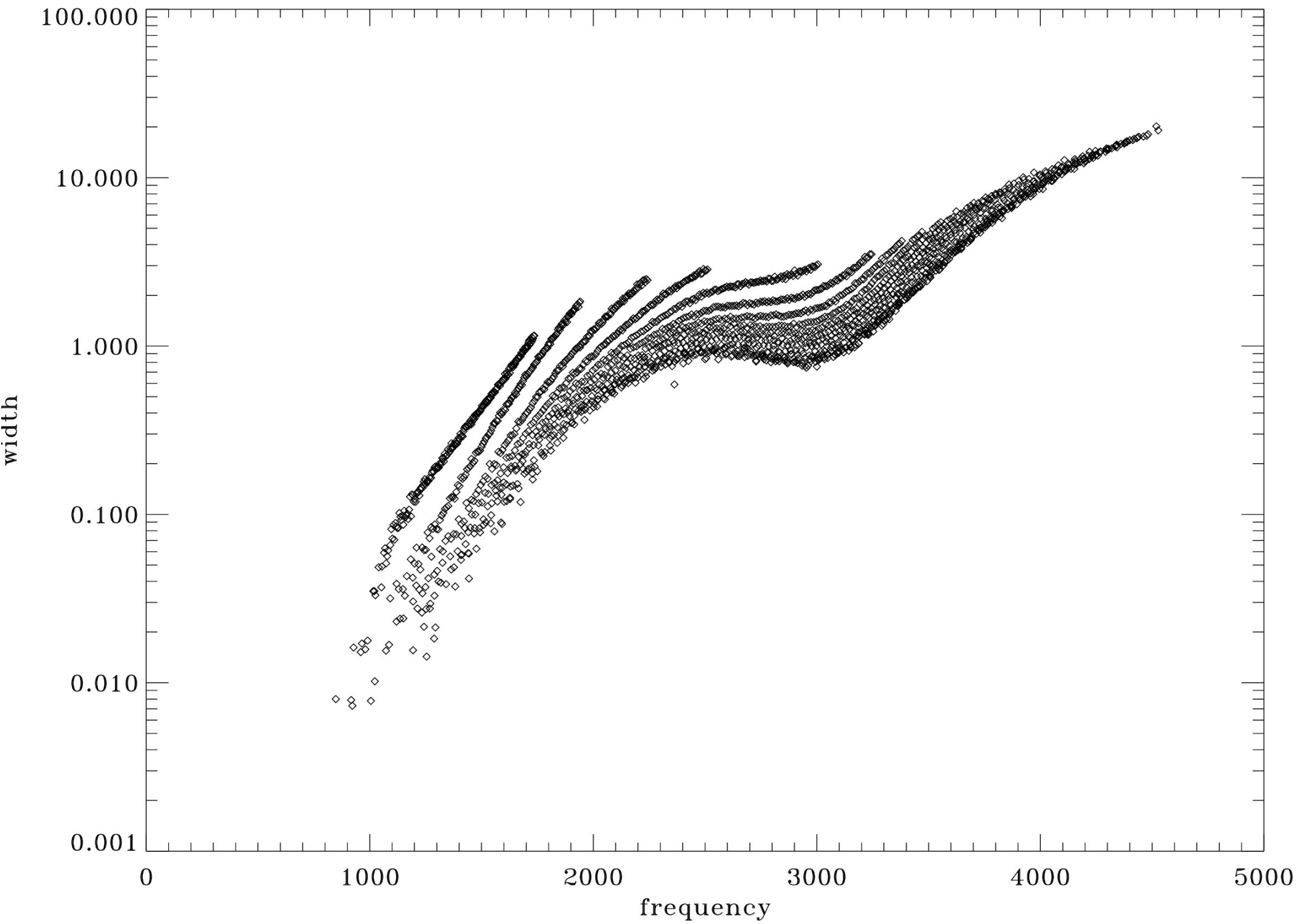
Peakbagging

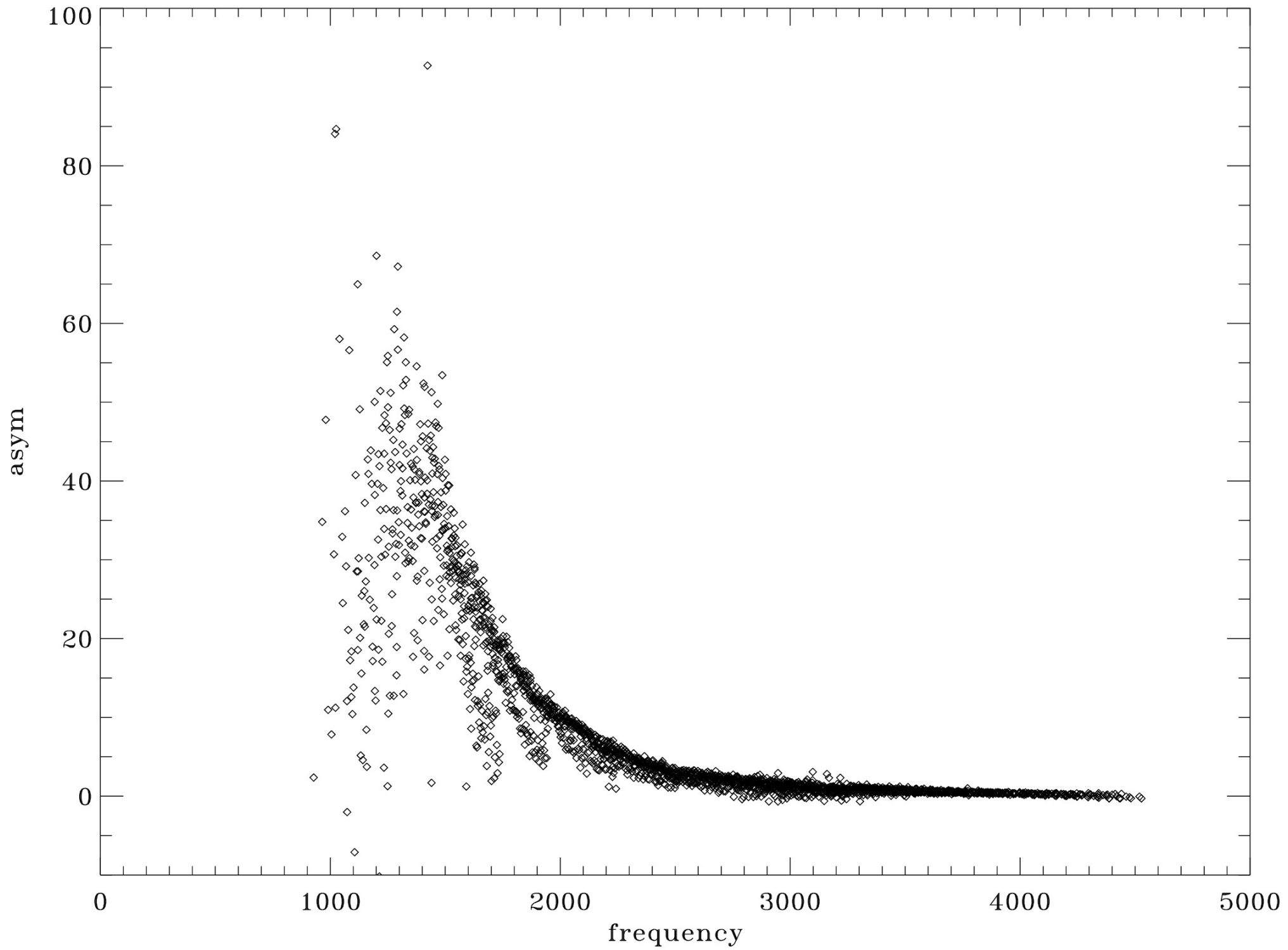
Asymmetry

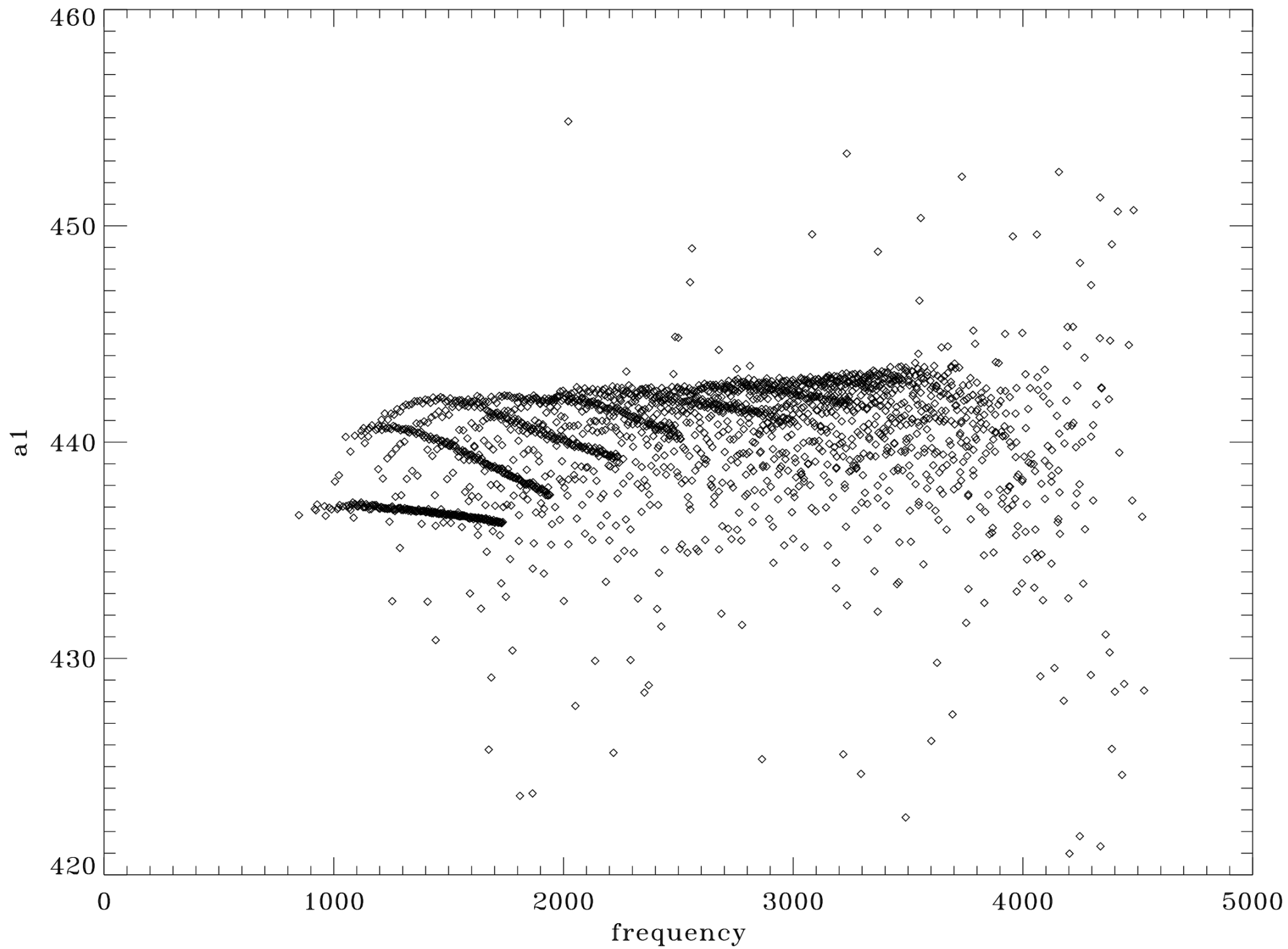
$$A_{\Psi}(X) = -A_w \frac{\sin(\beta X - p_w) + (i/2)\beta \cos(\beta X - p_w)}{\sin(\beta X) + (i/2)\beta \cos(\beta X)}$$

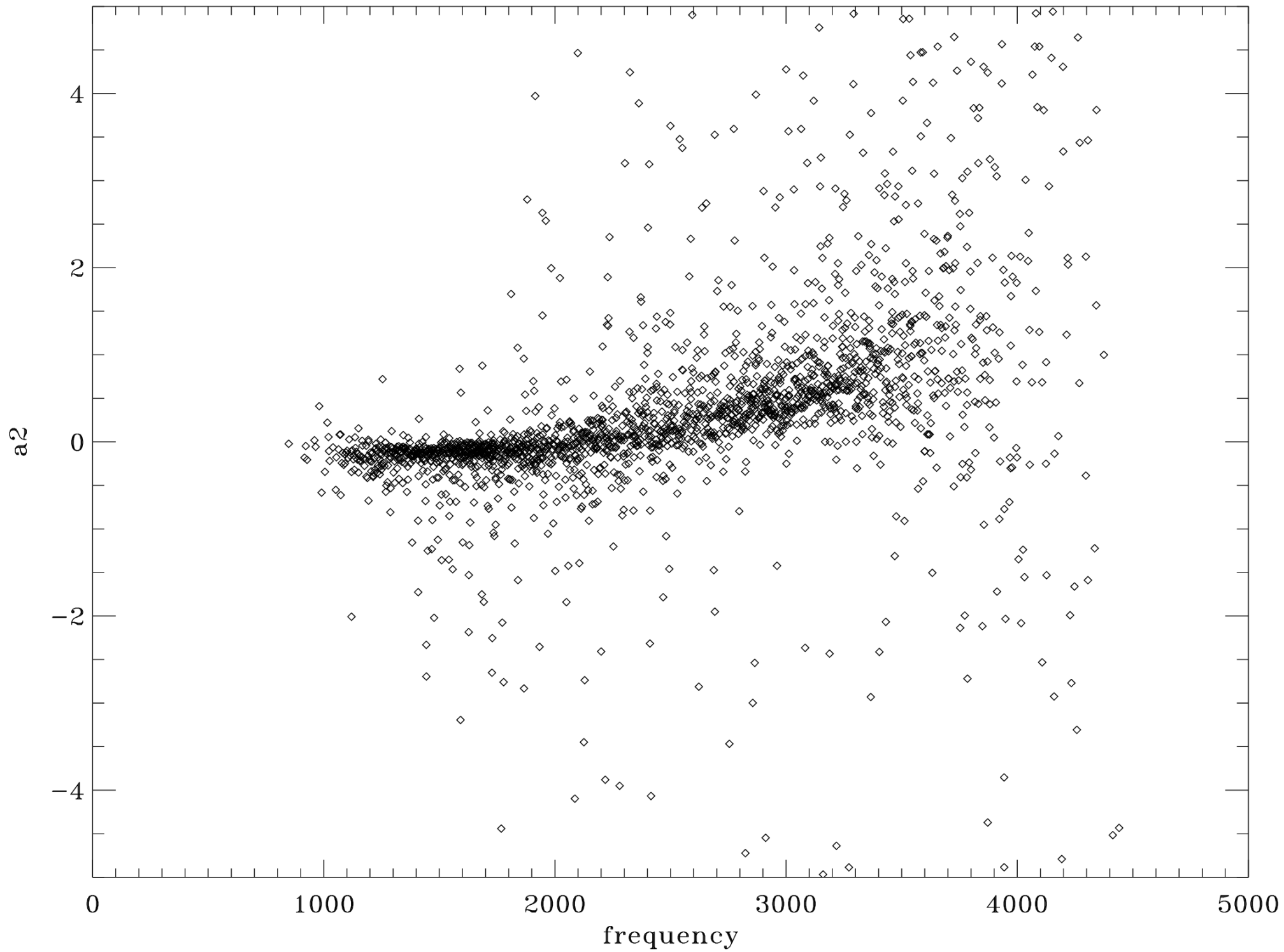






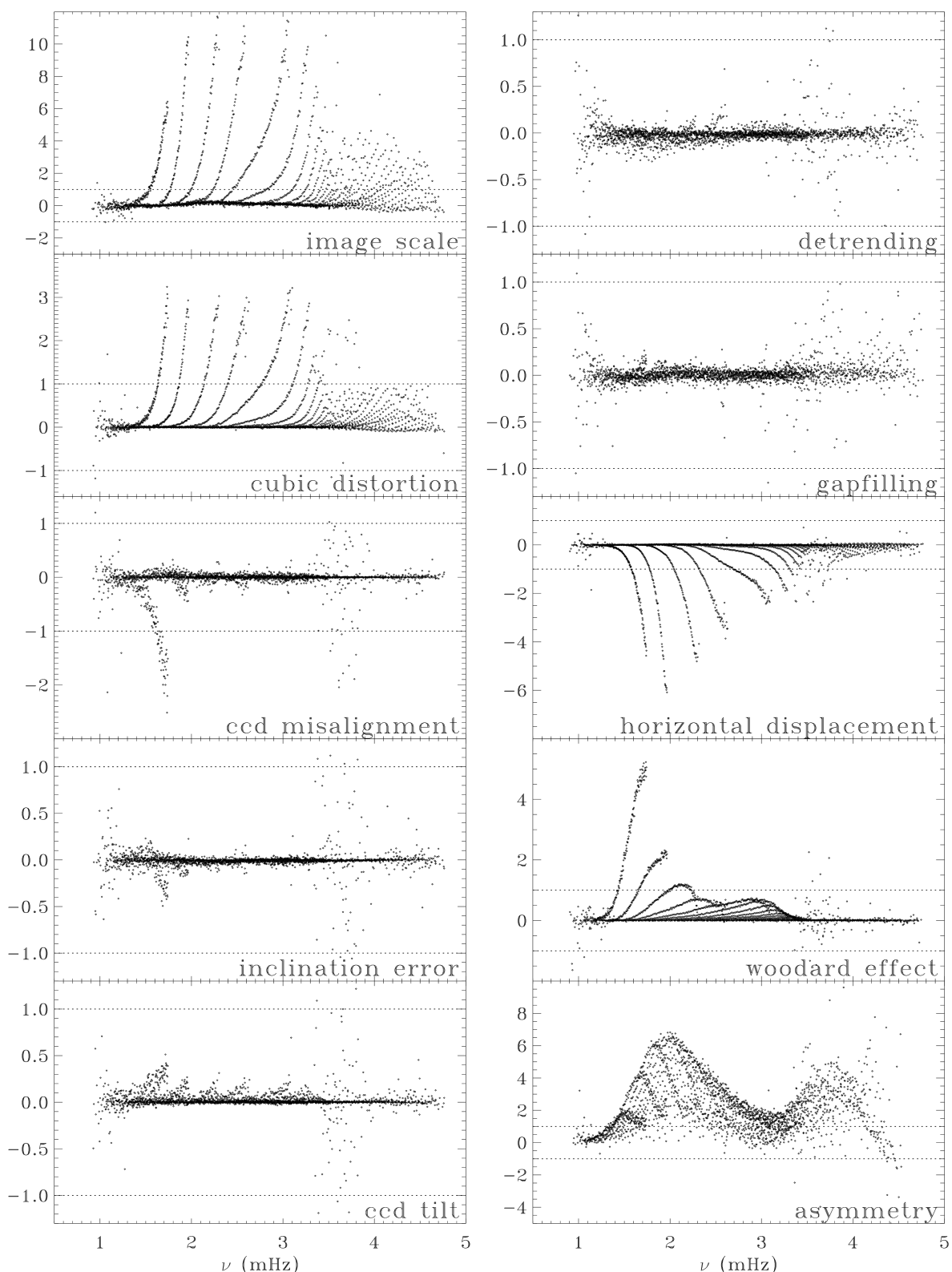




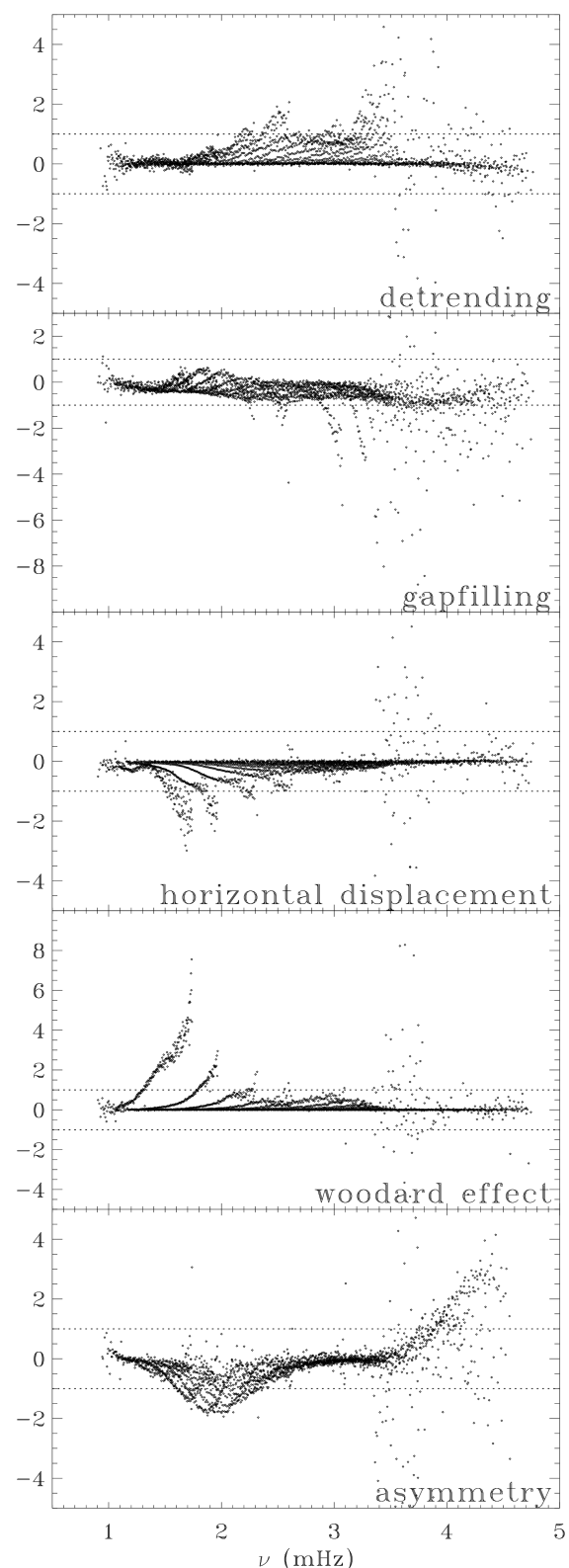
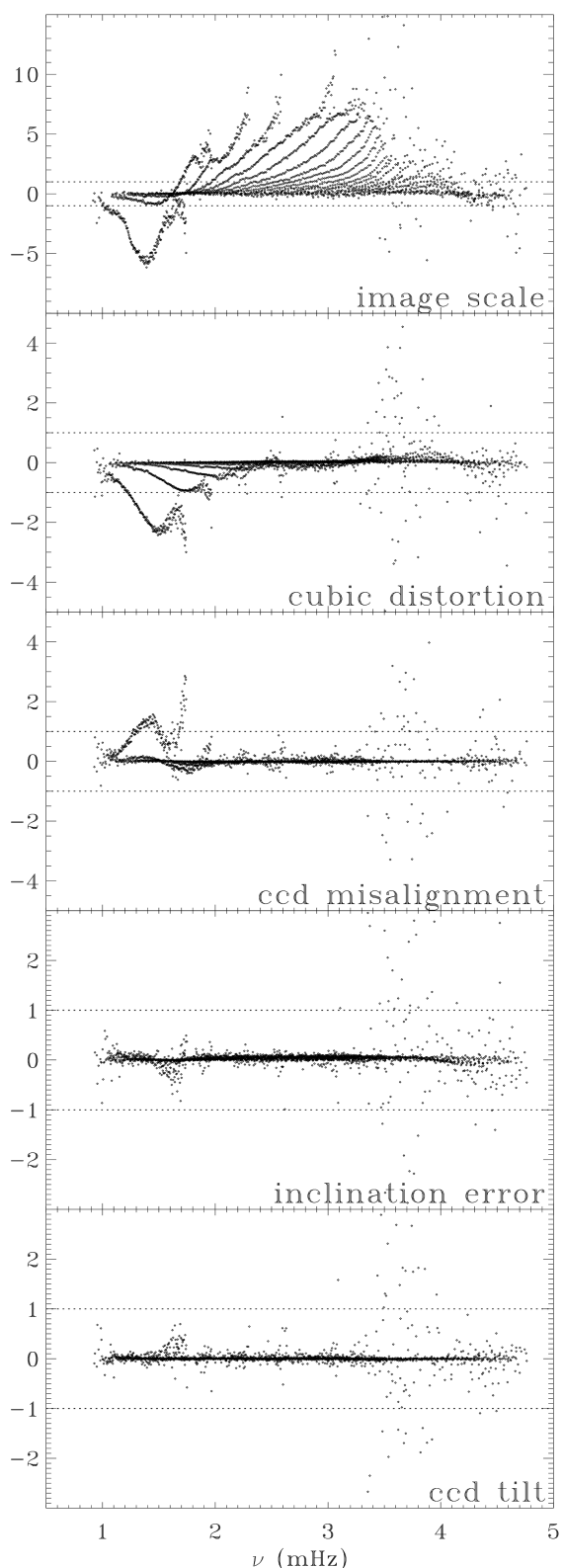


Effect on Mode Parameters

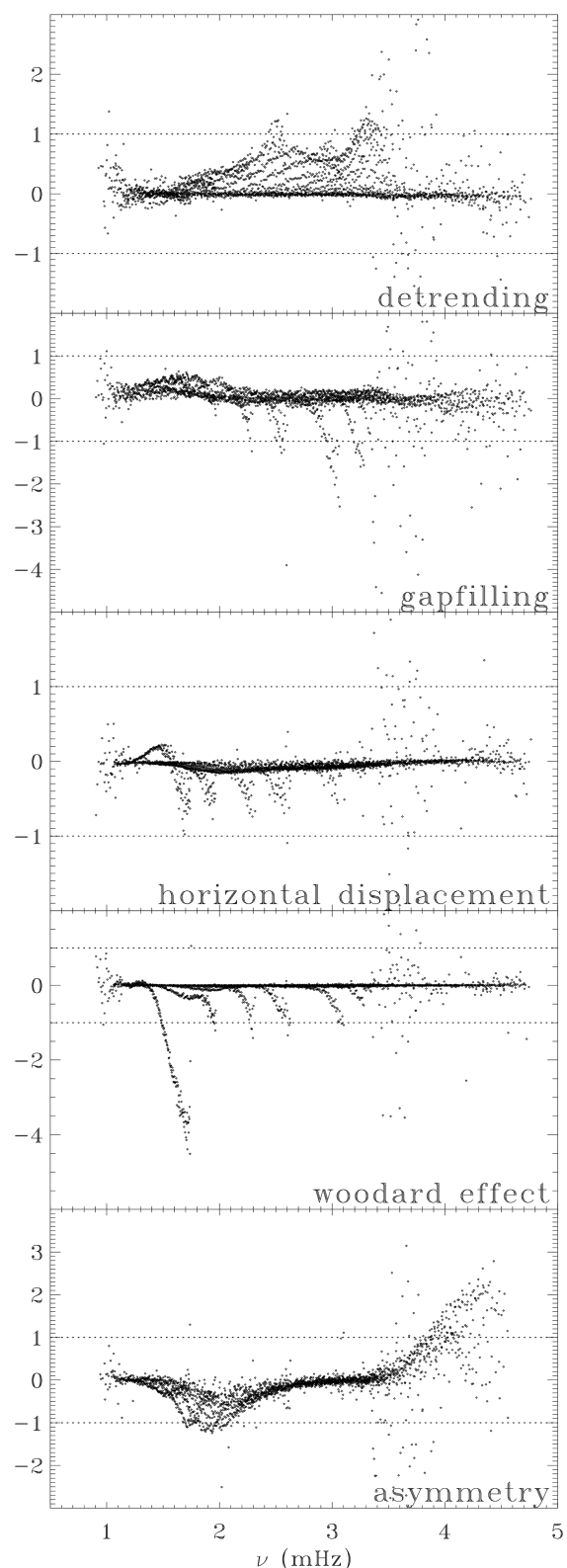
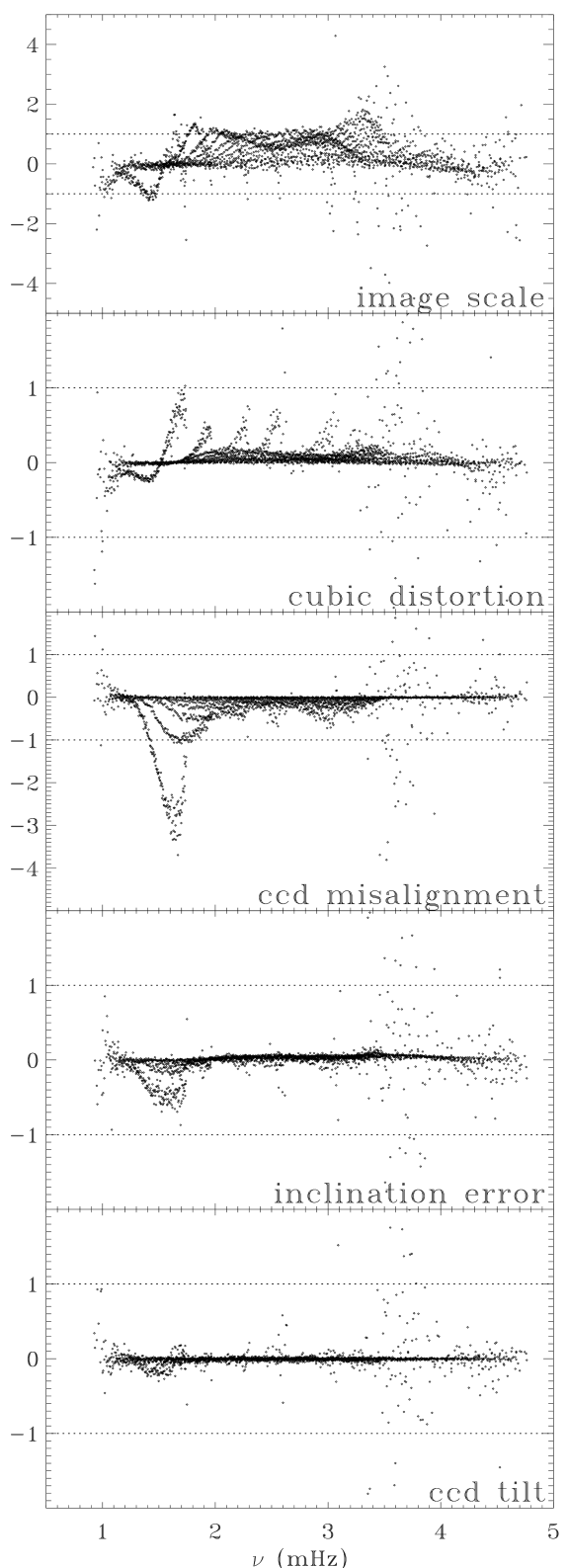
frequency



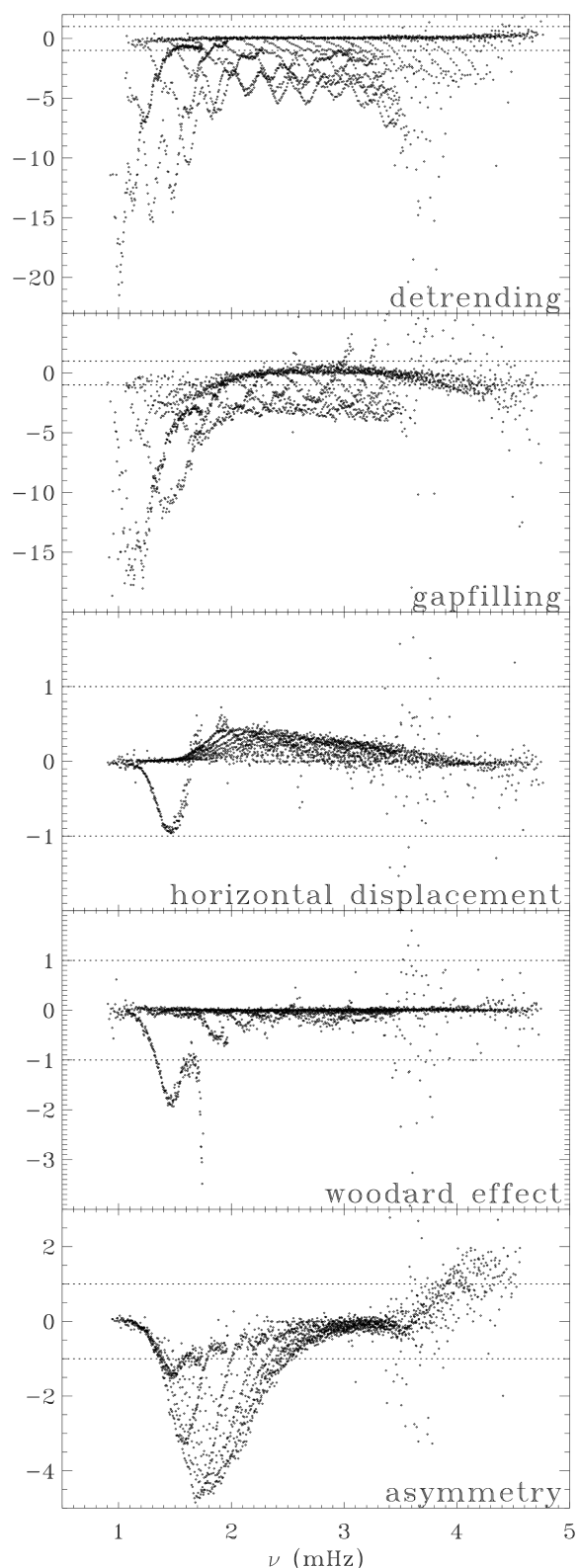
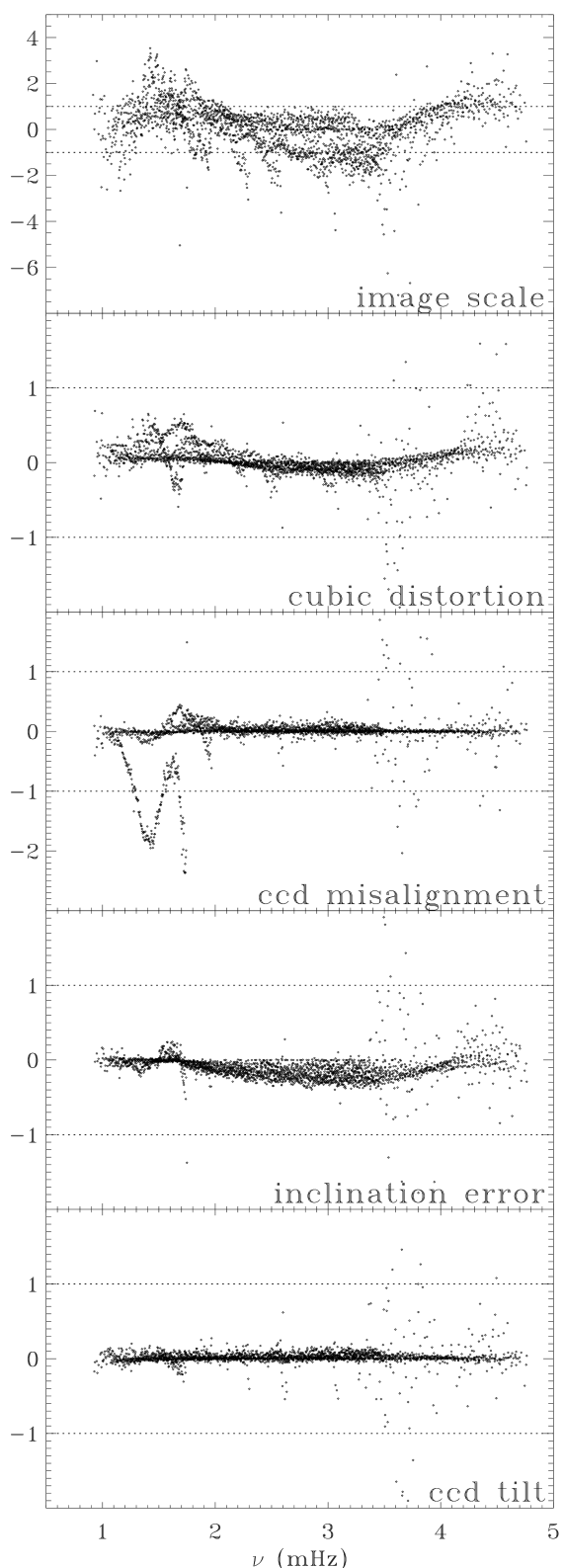
amplitude



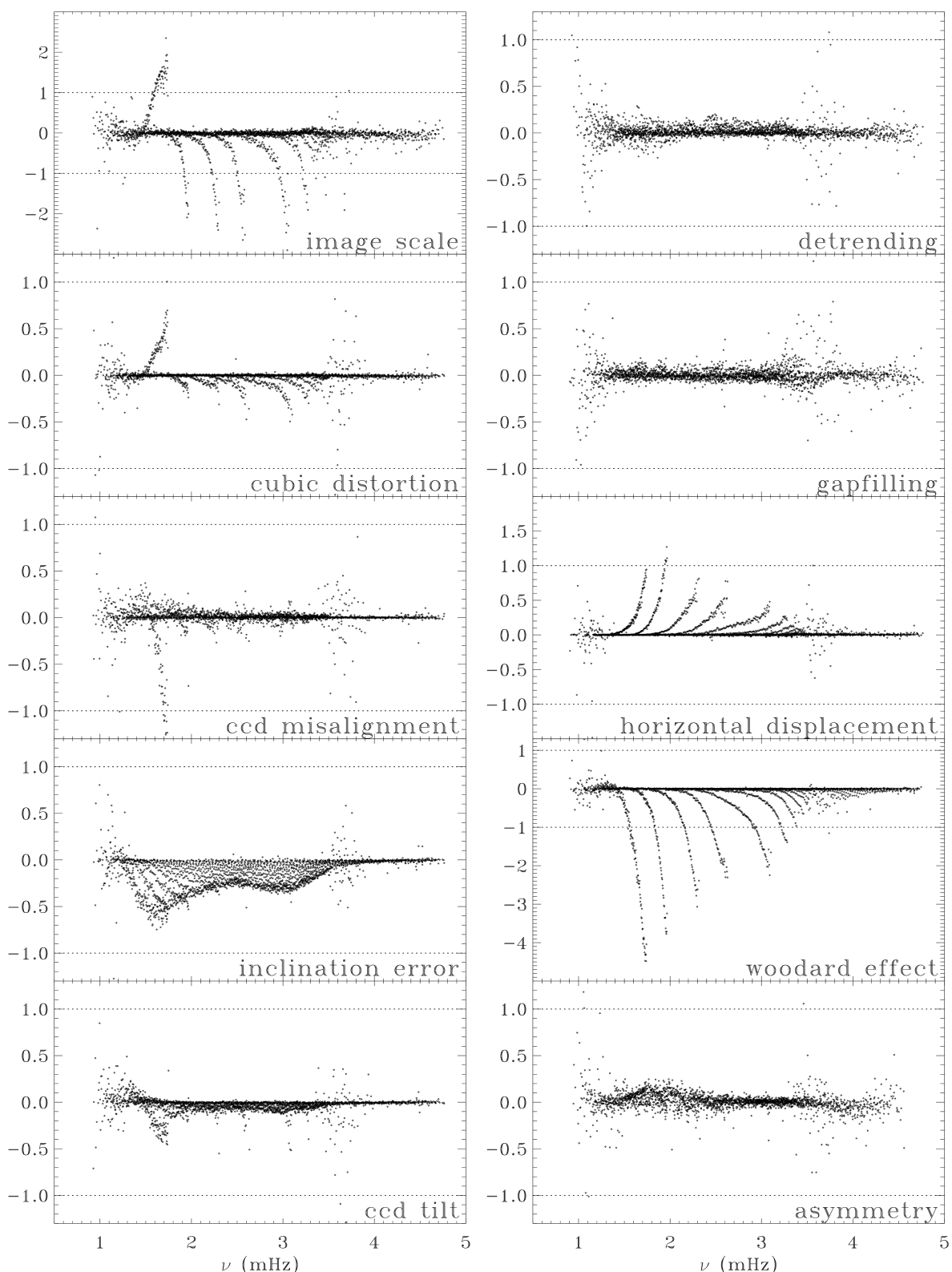
width



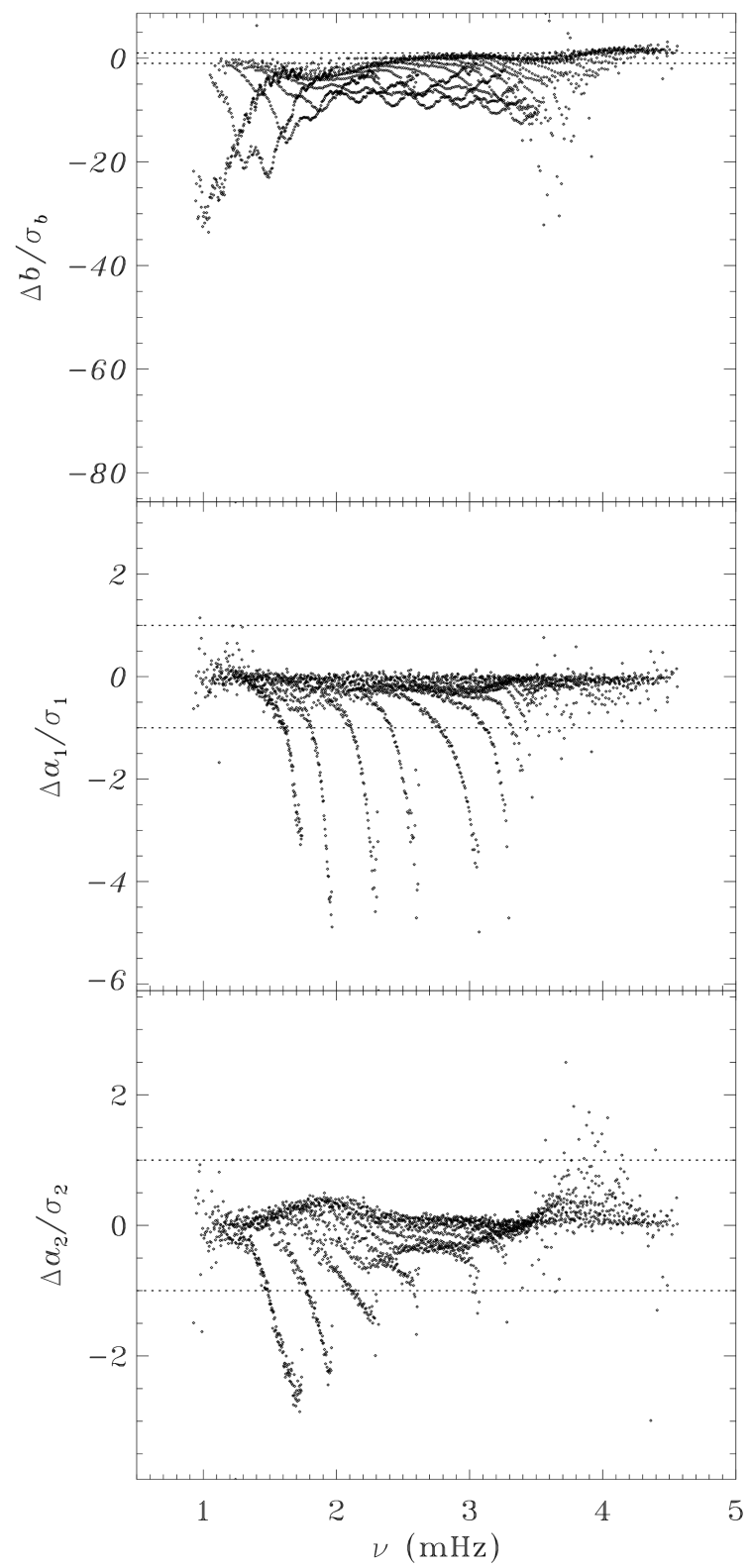
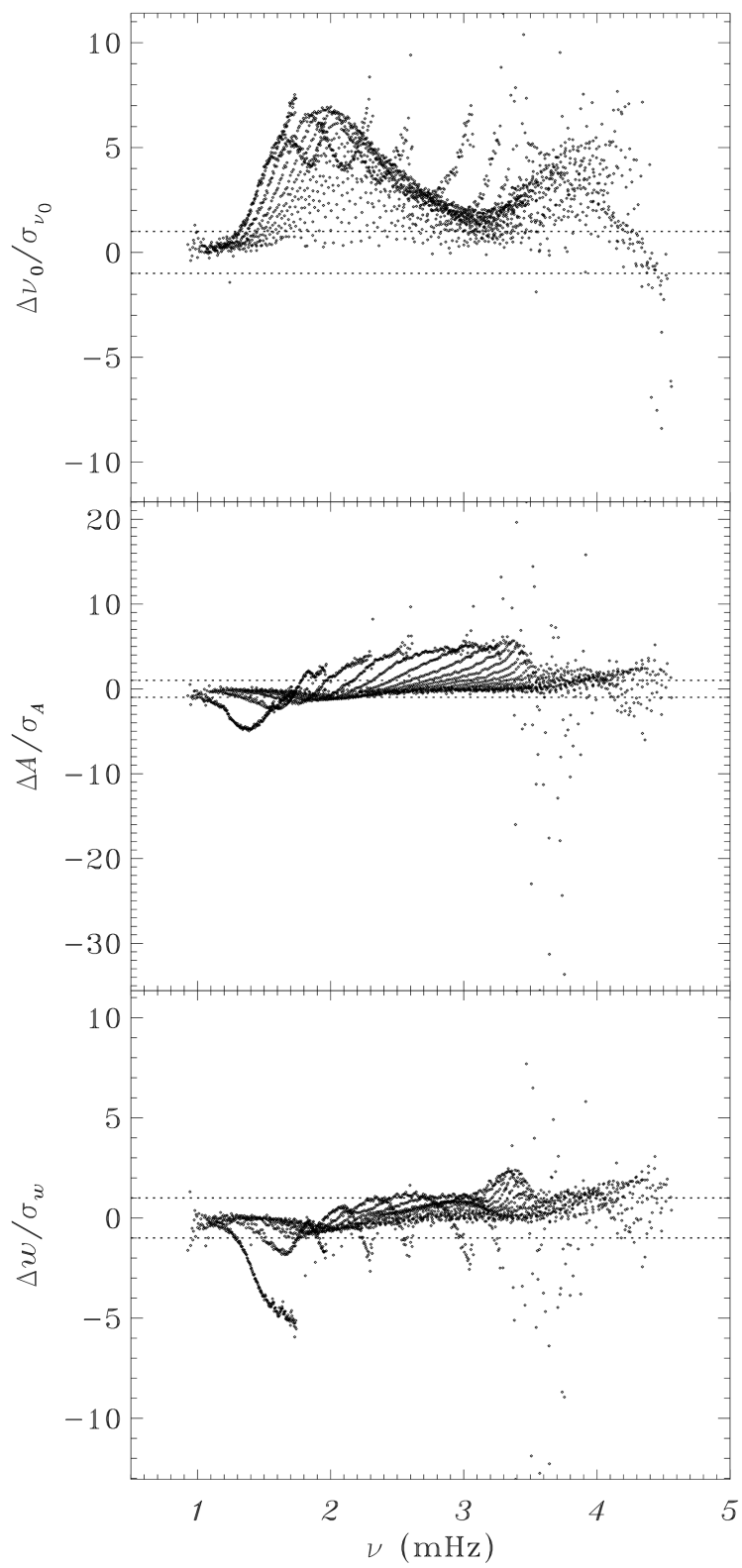
background



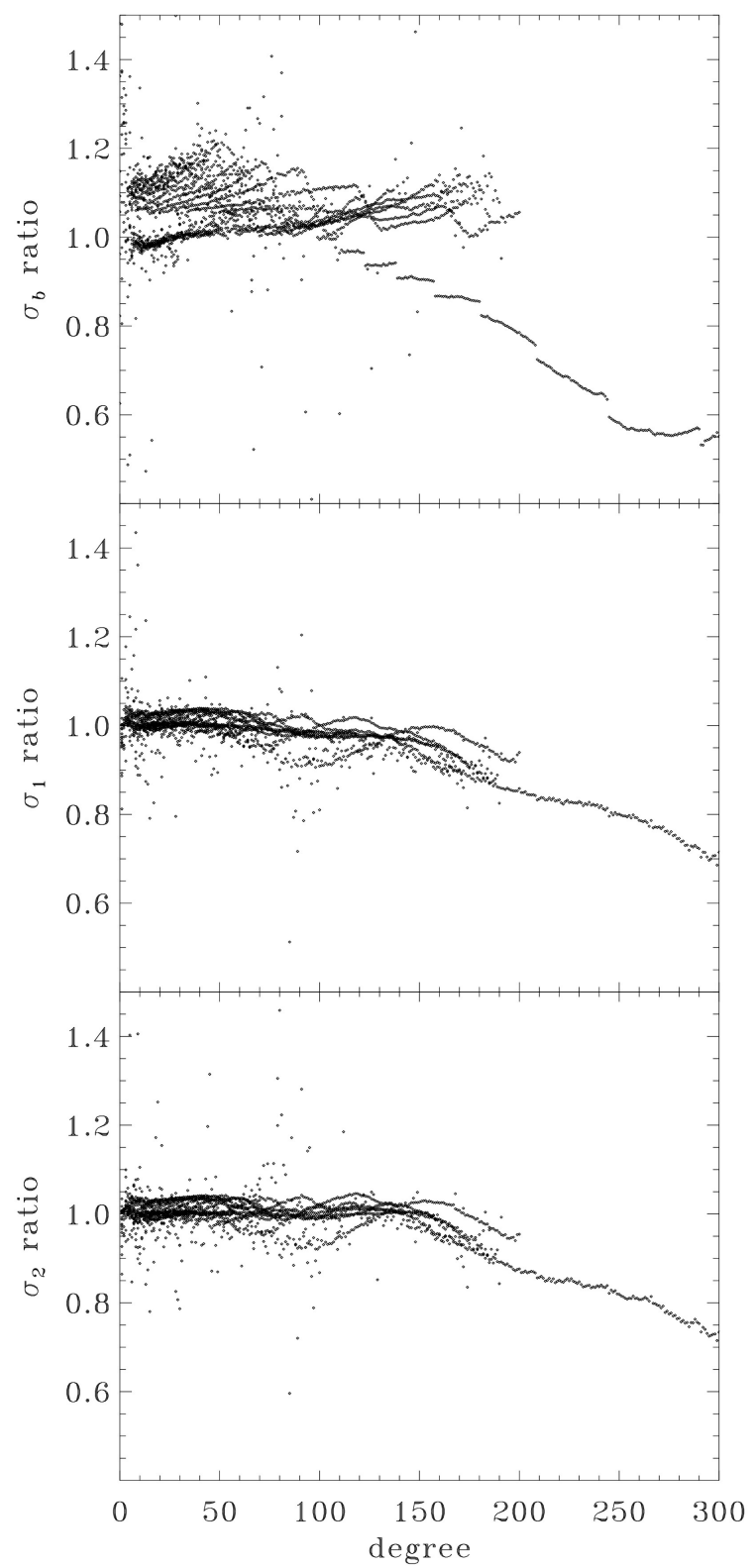
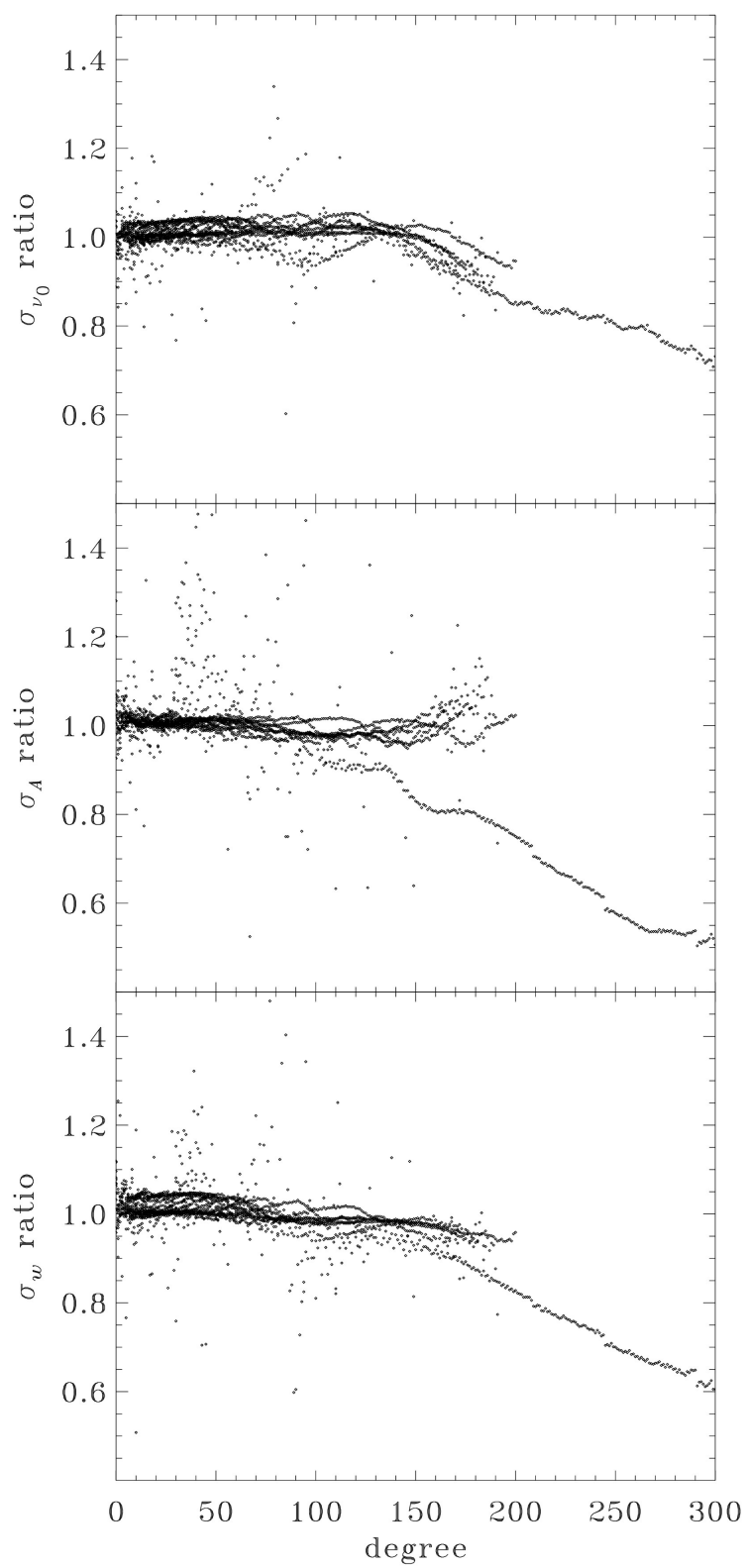
a1



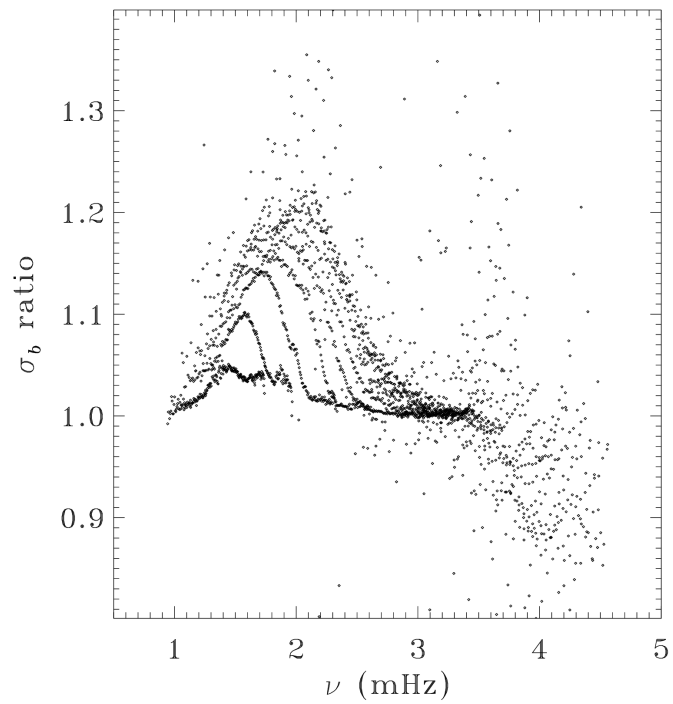
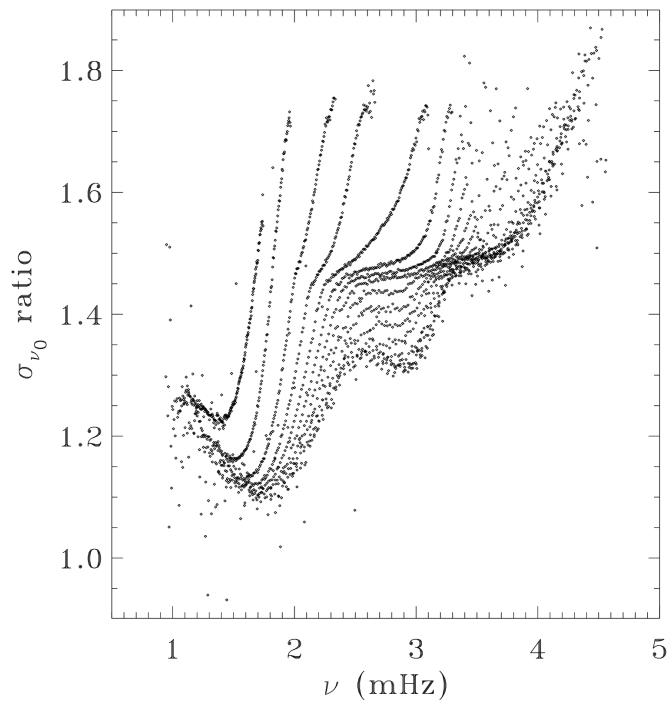
final - initial

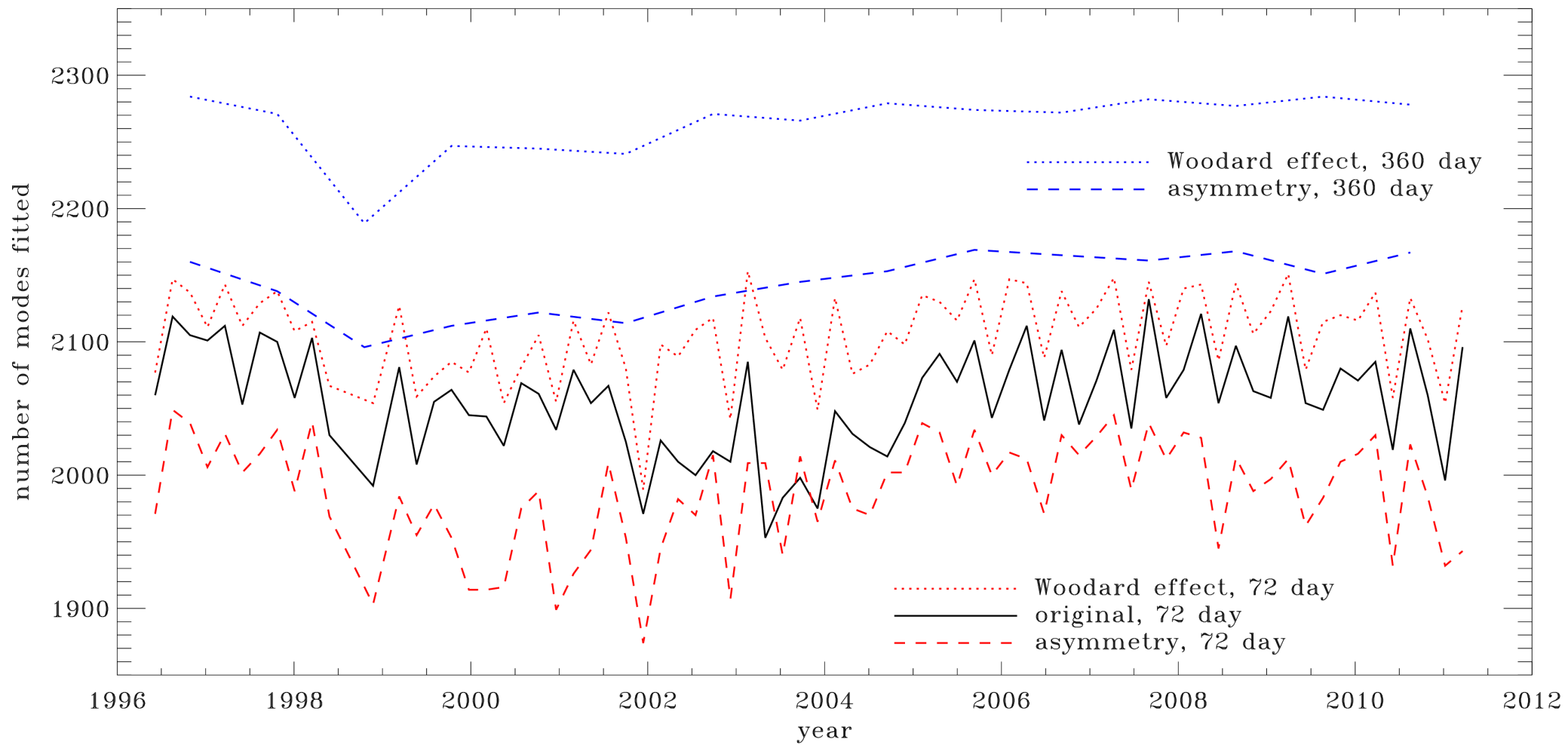


error reduction

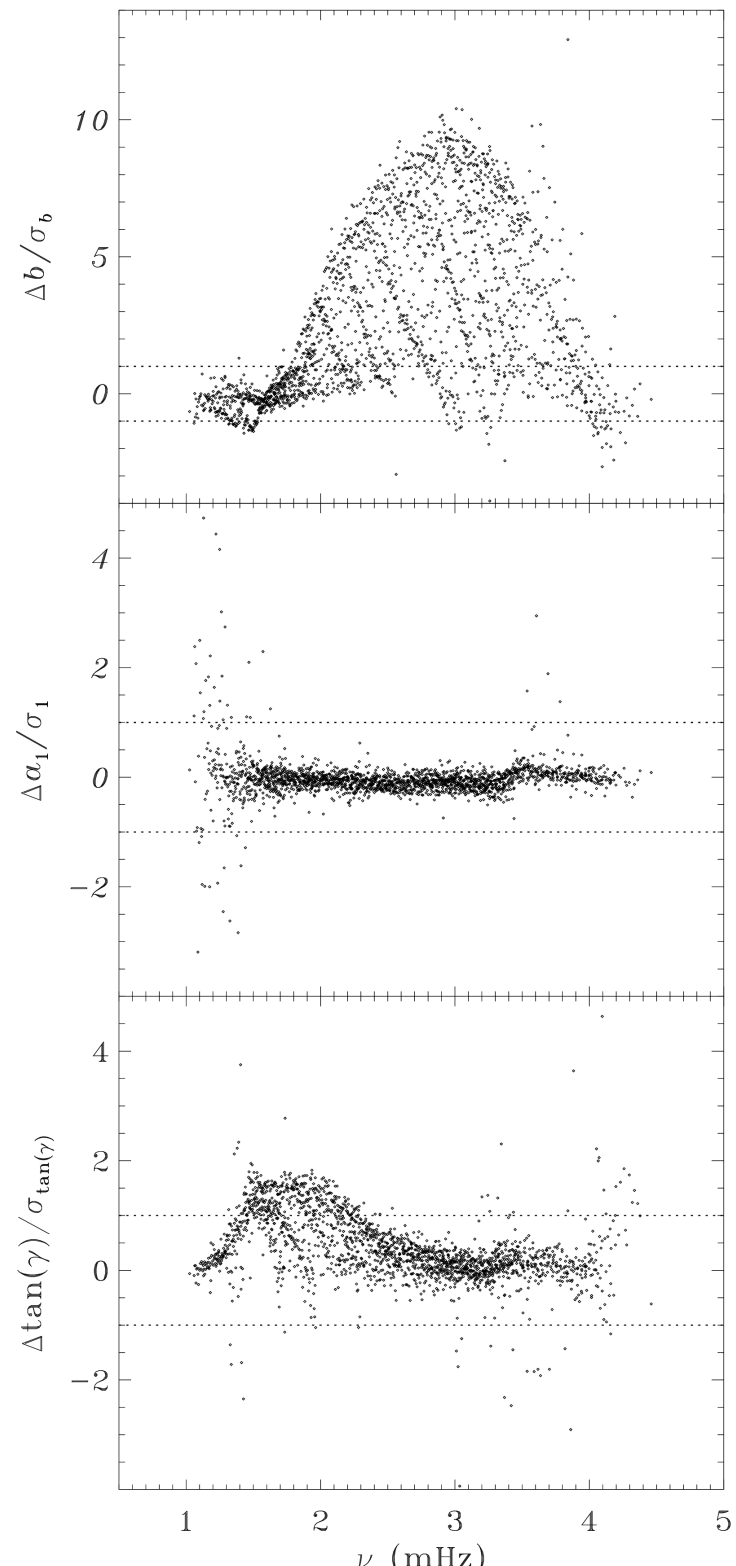
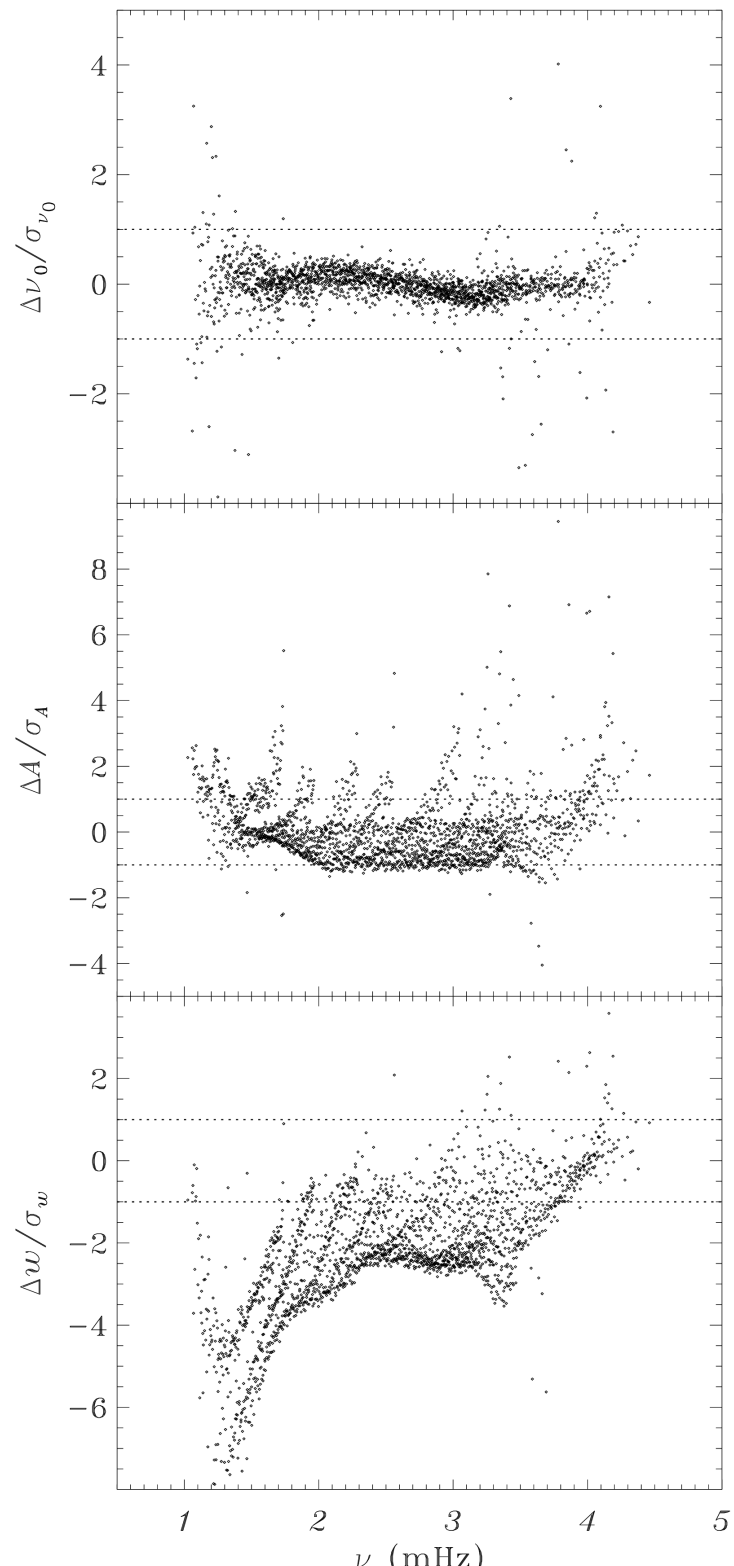


error magnification

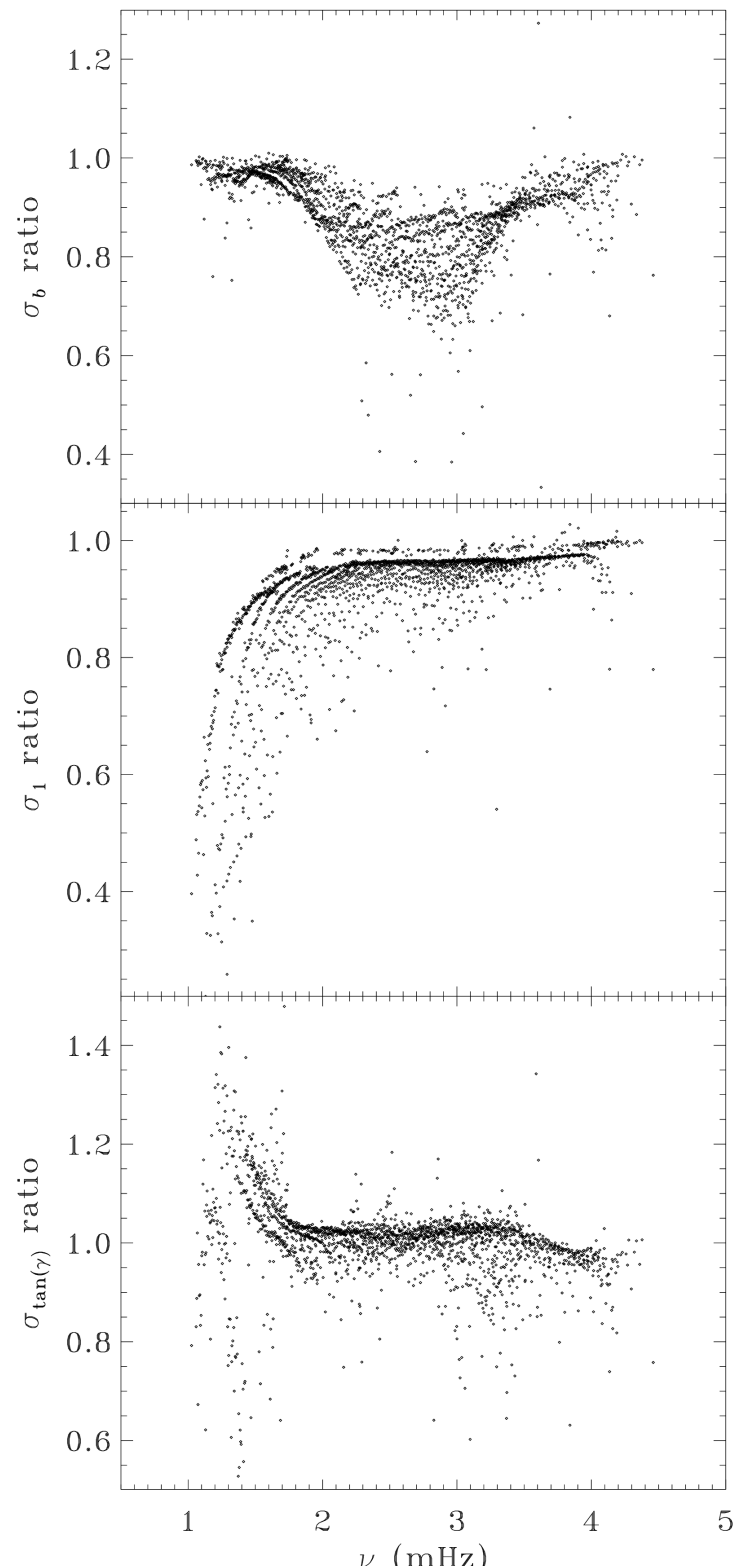
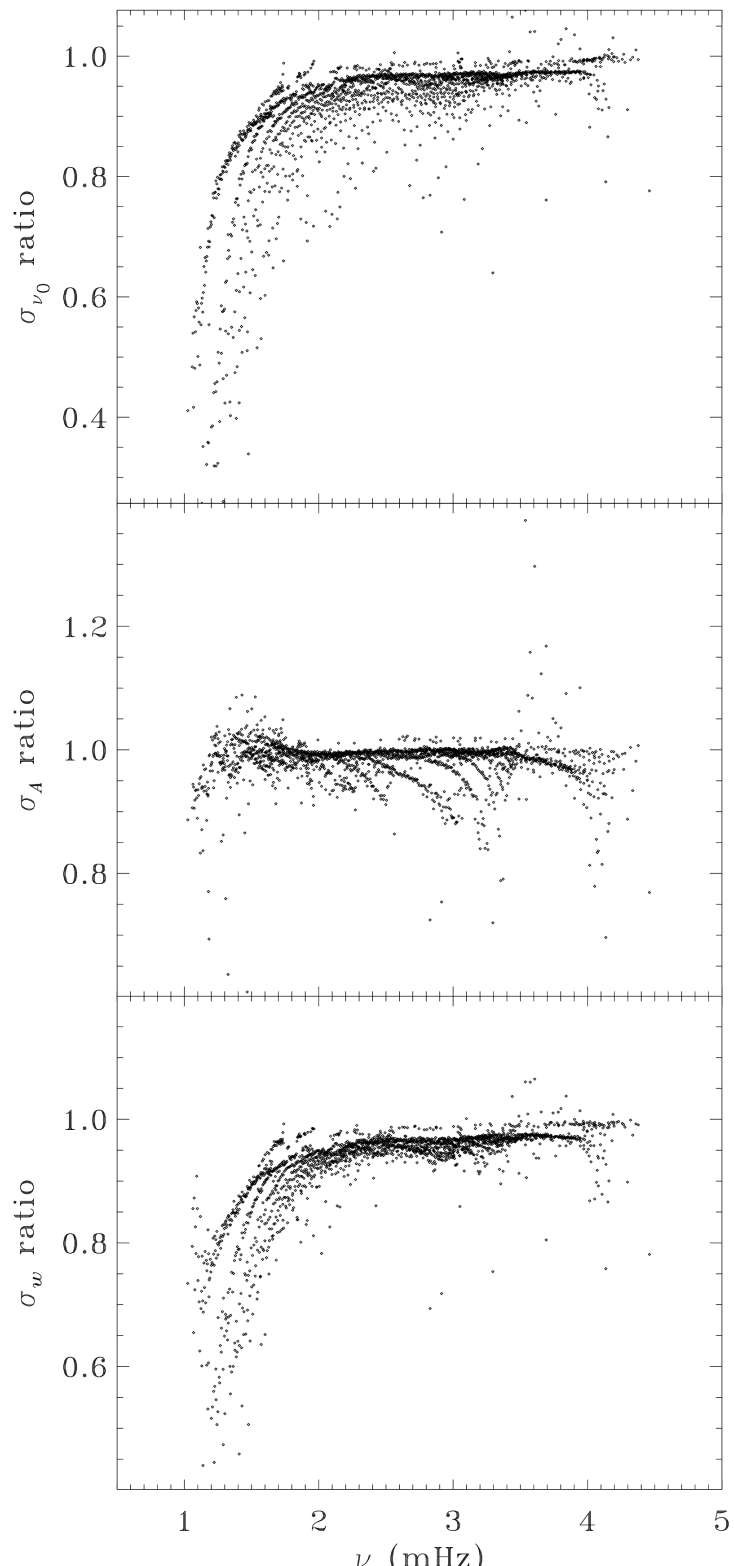




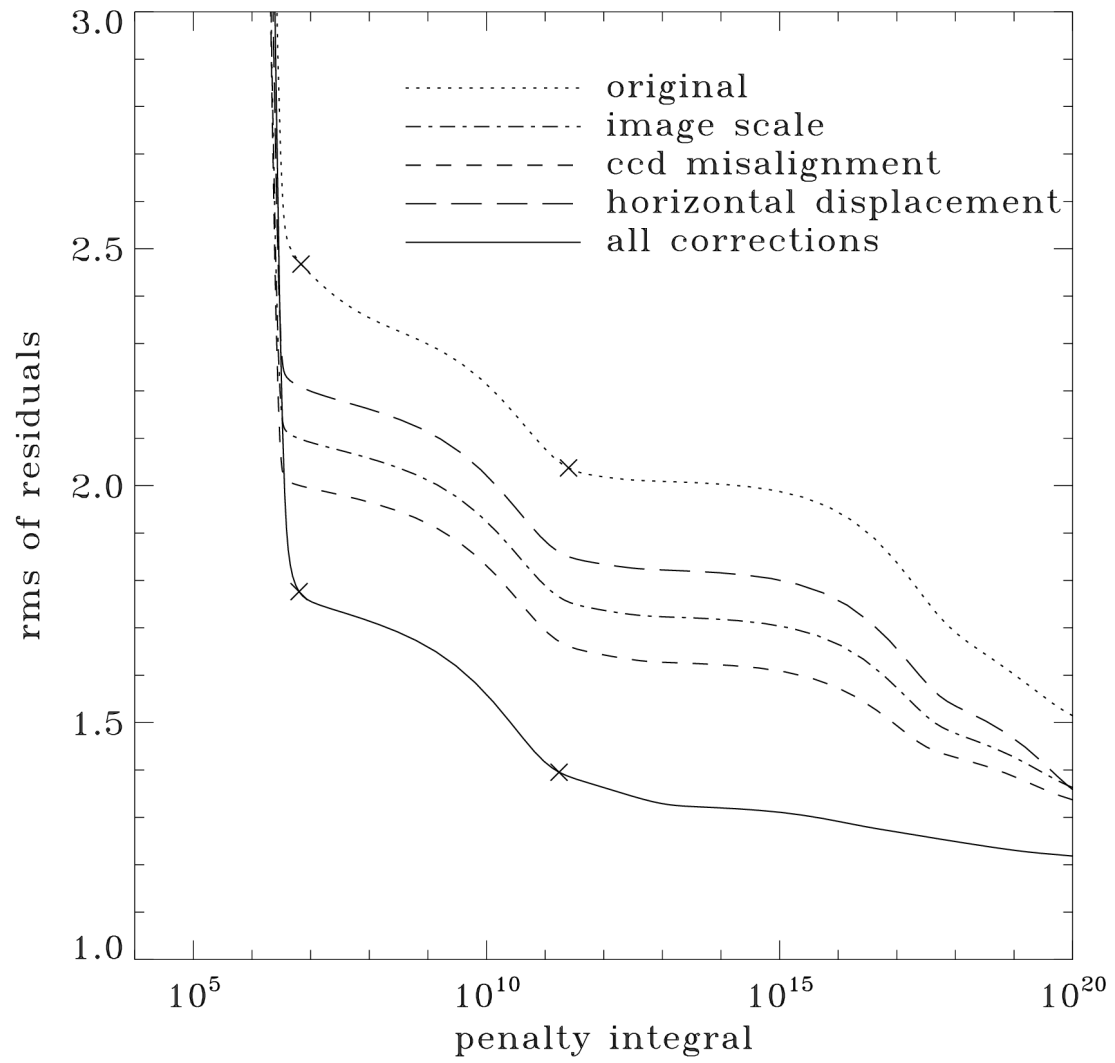
360d fits

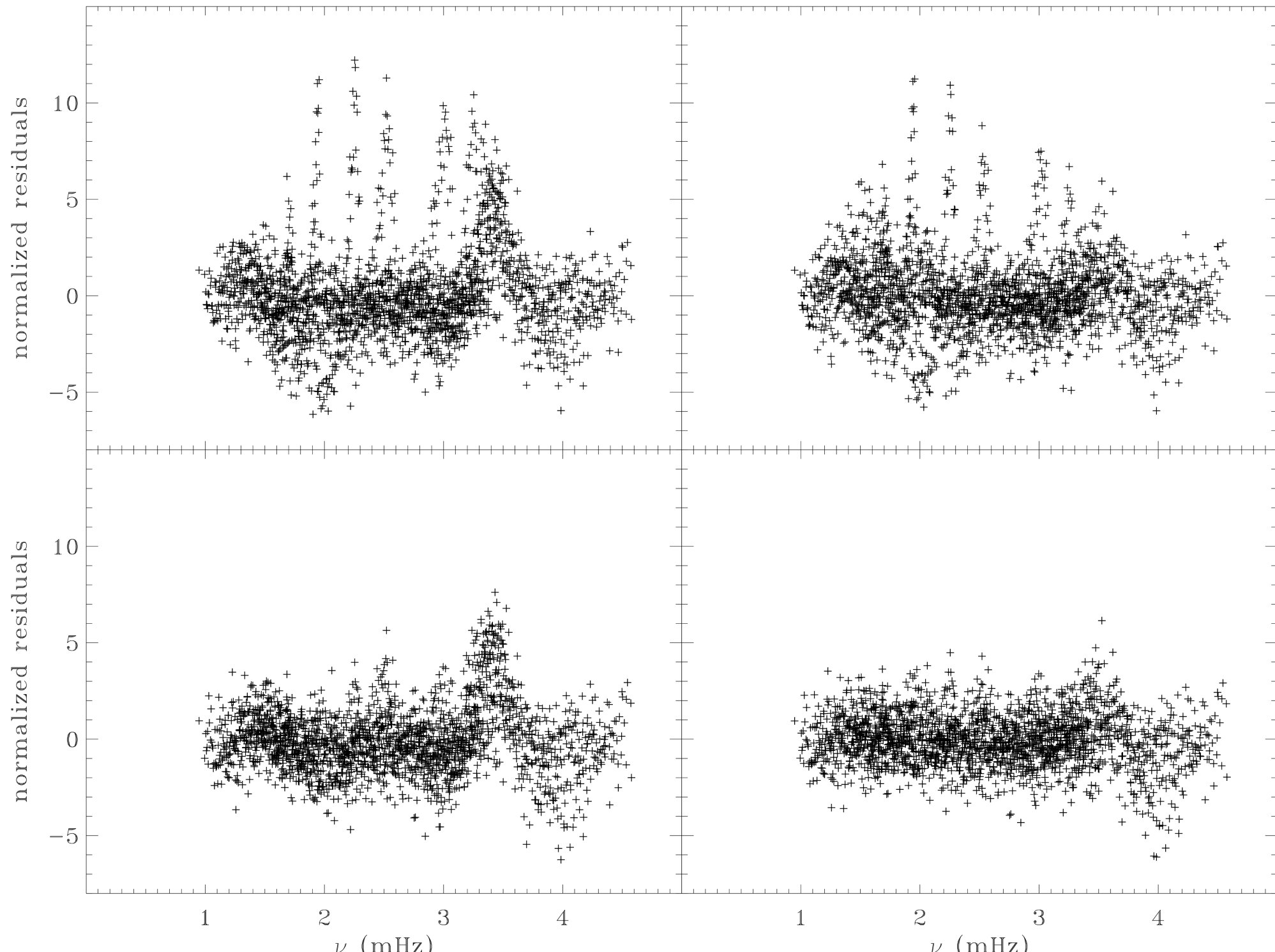


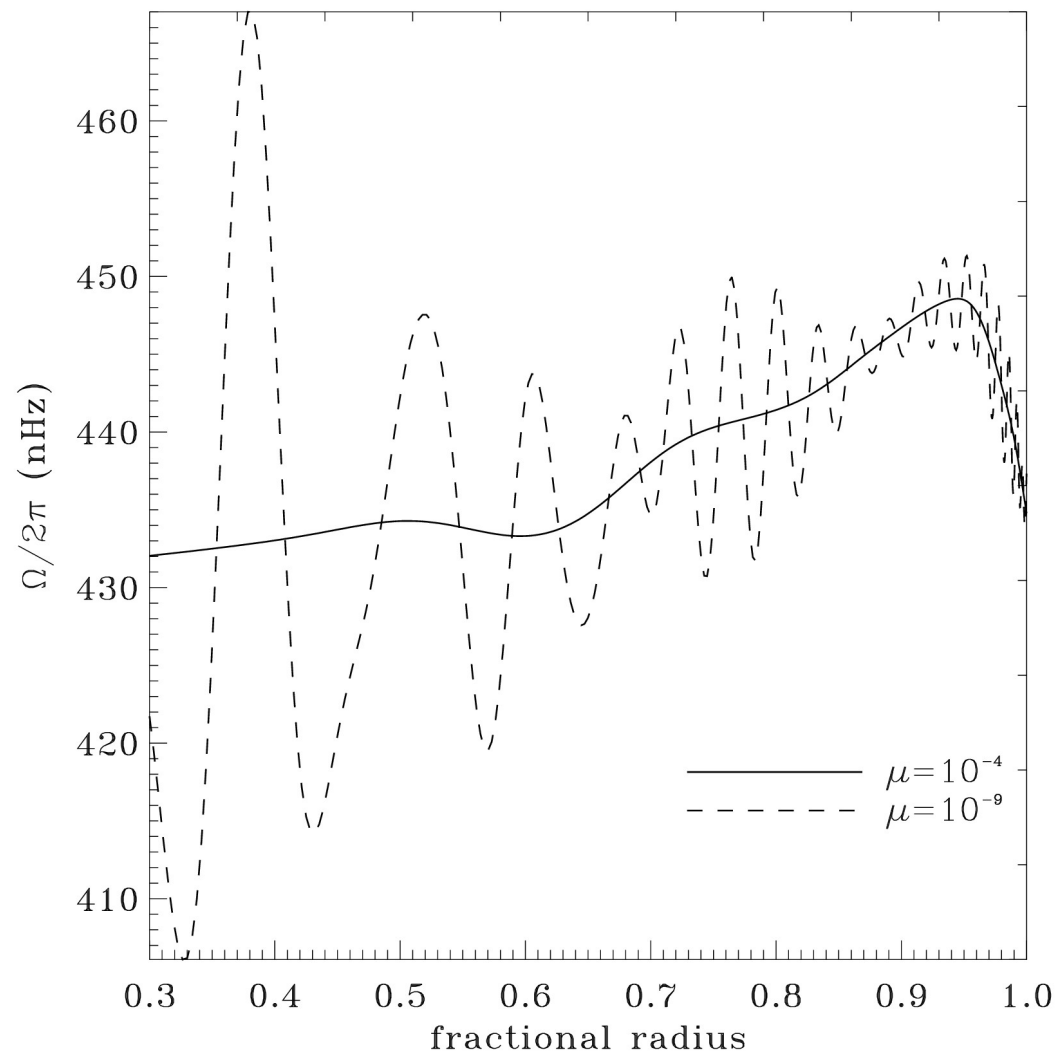
360d error

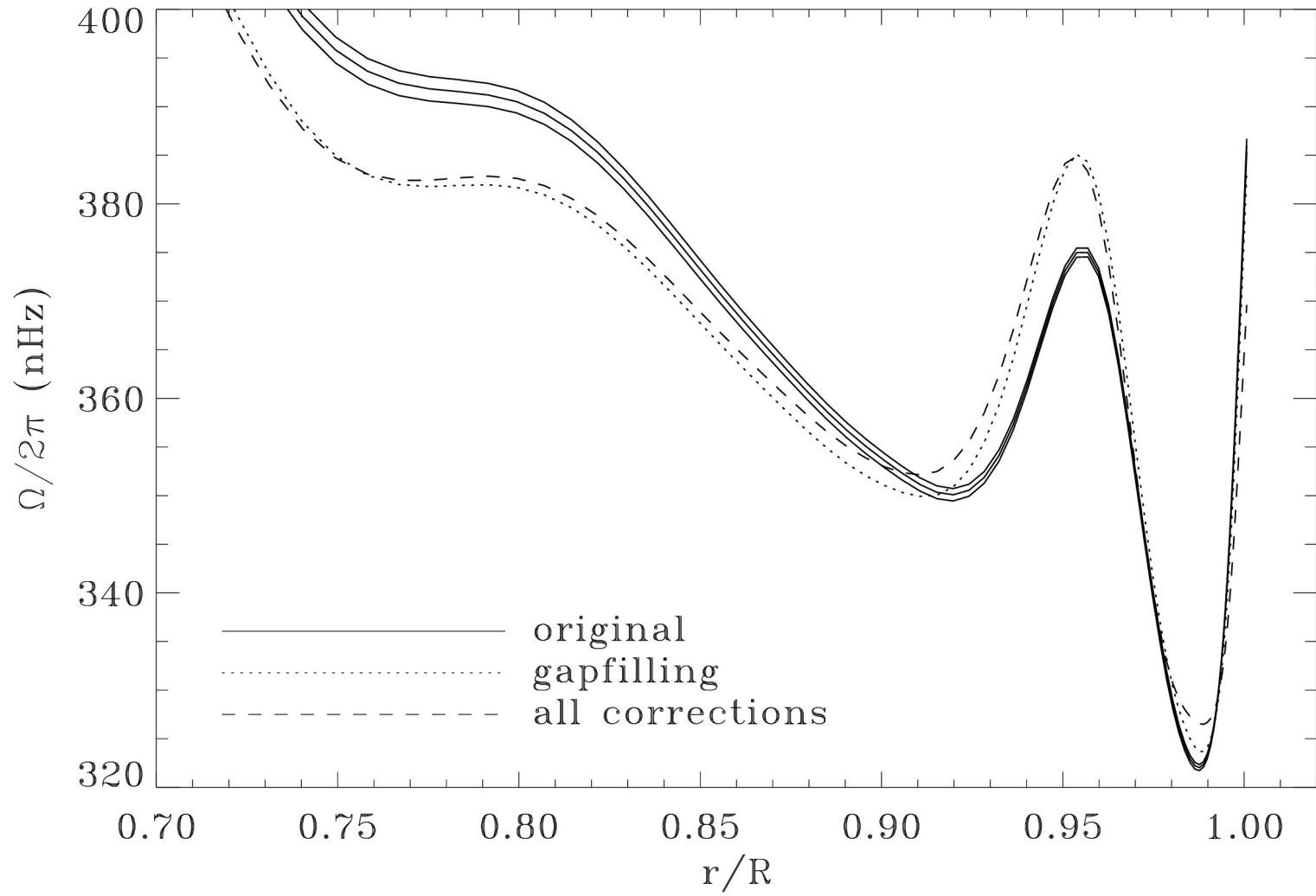


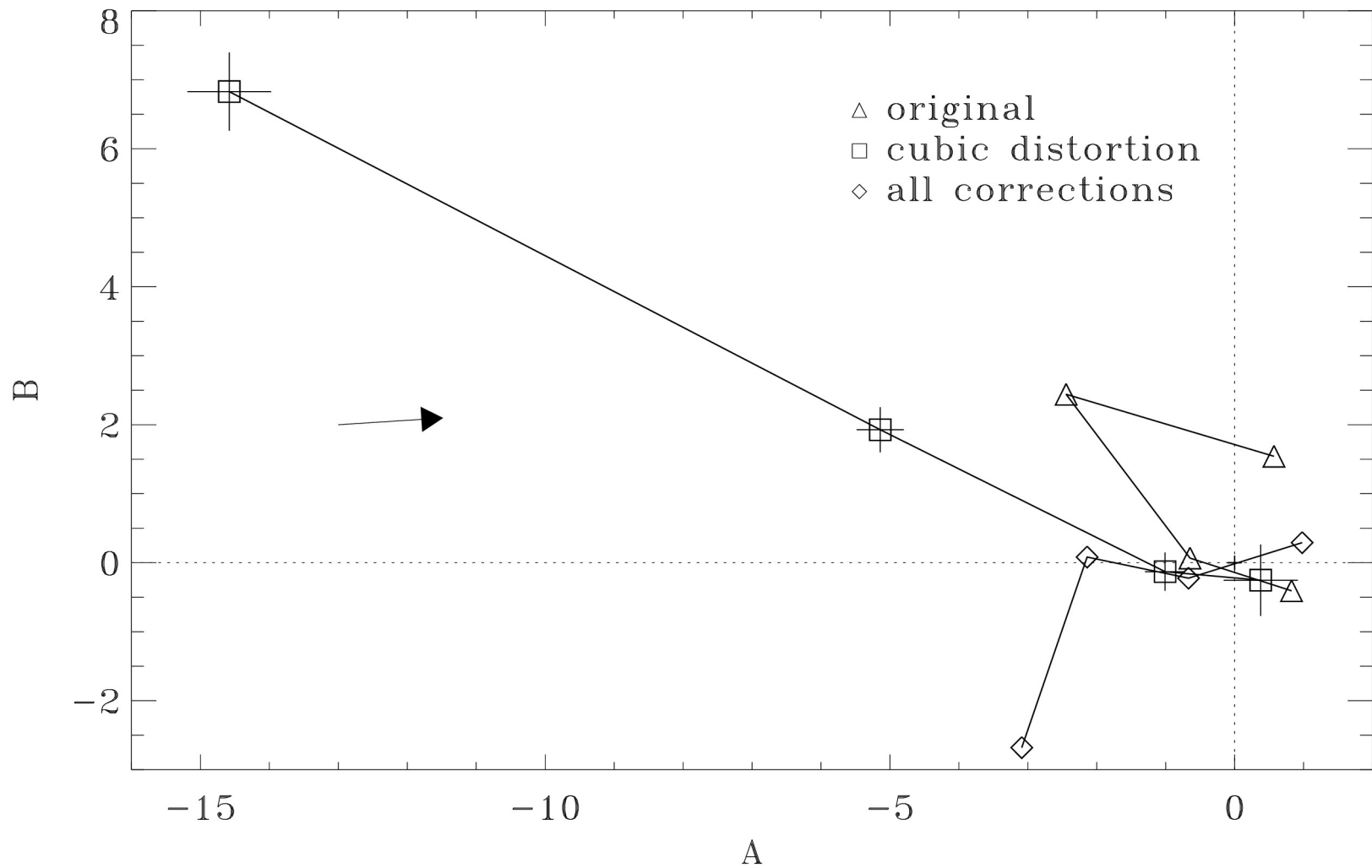
Systematic Errors



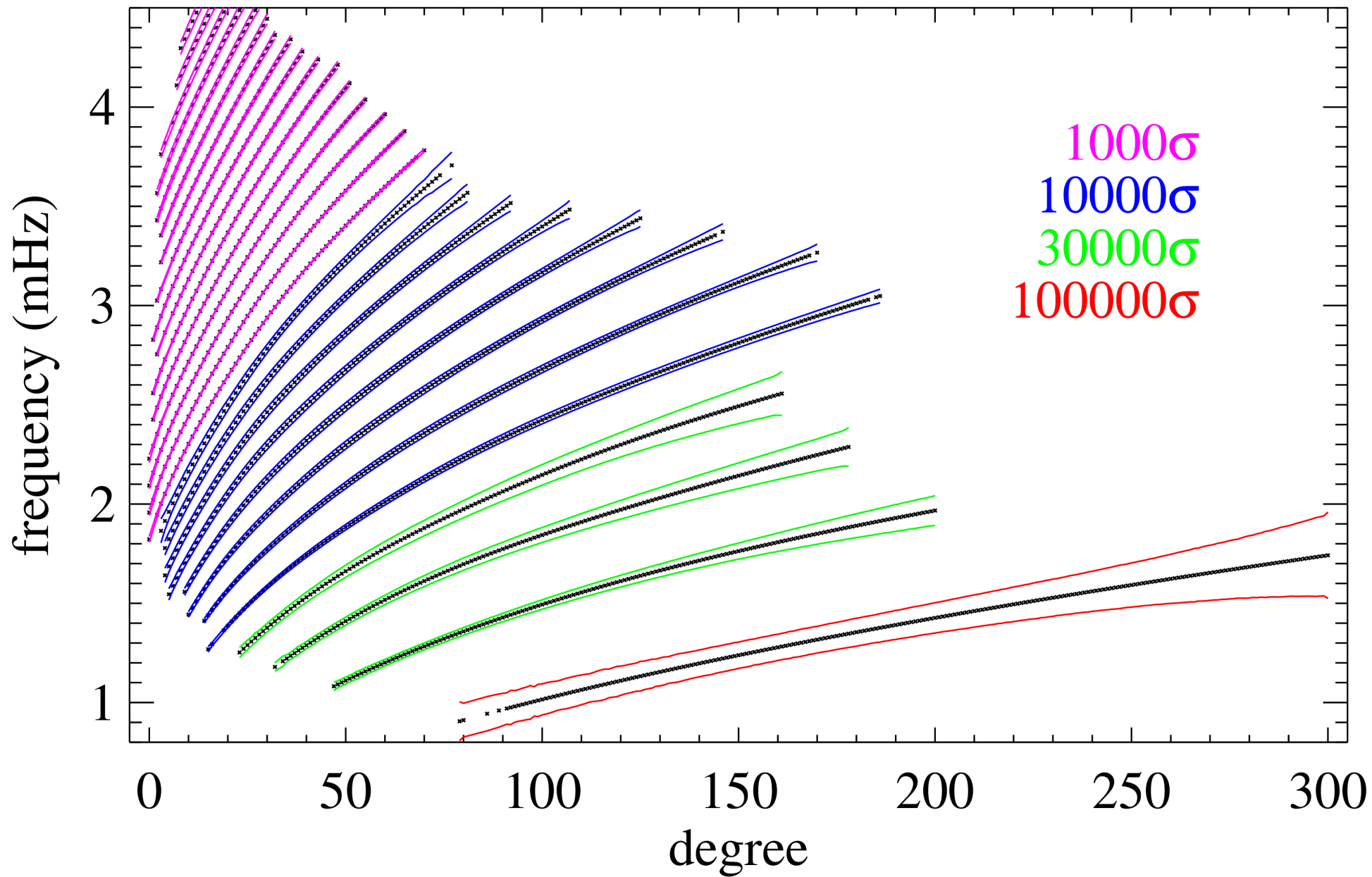




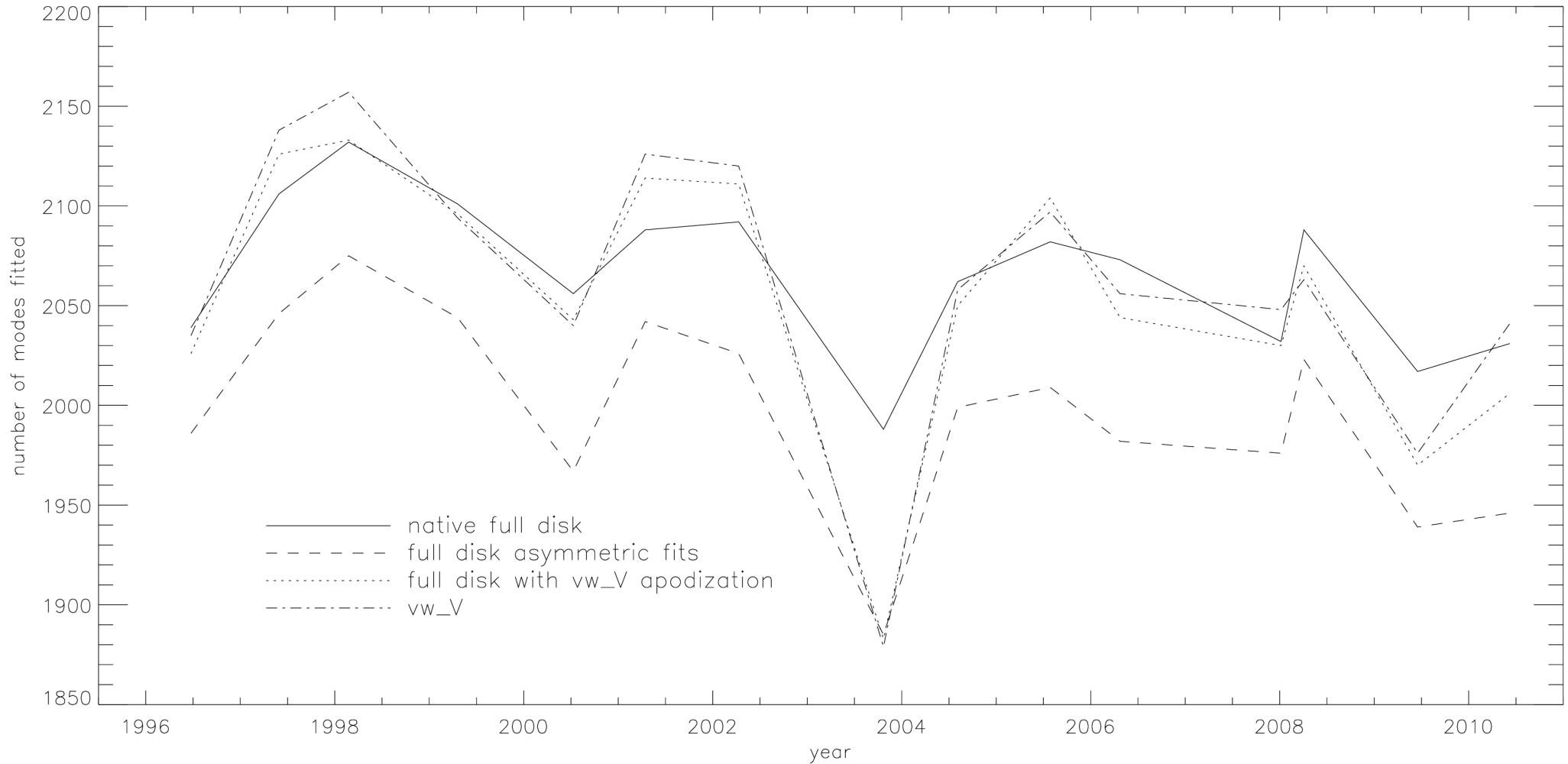


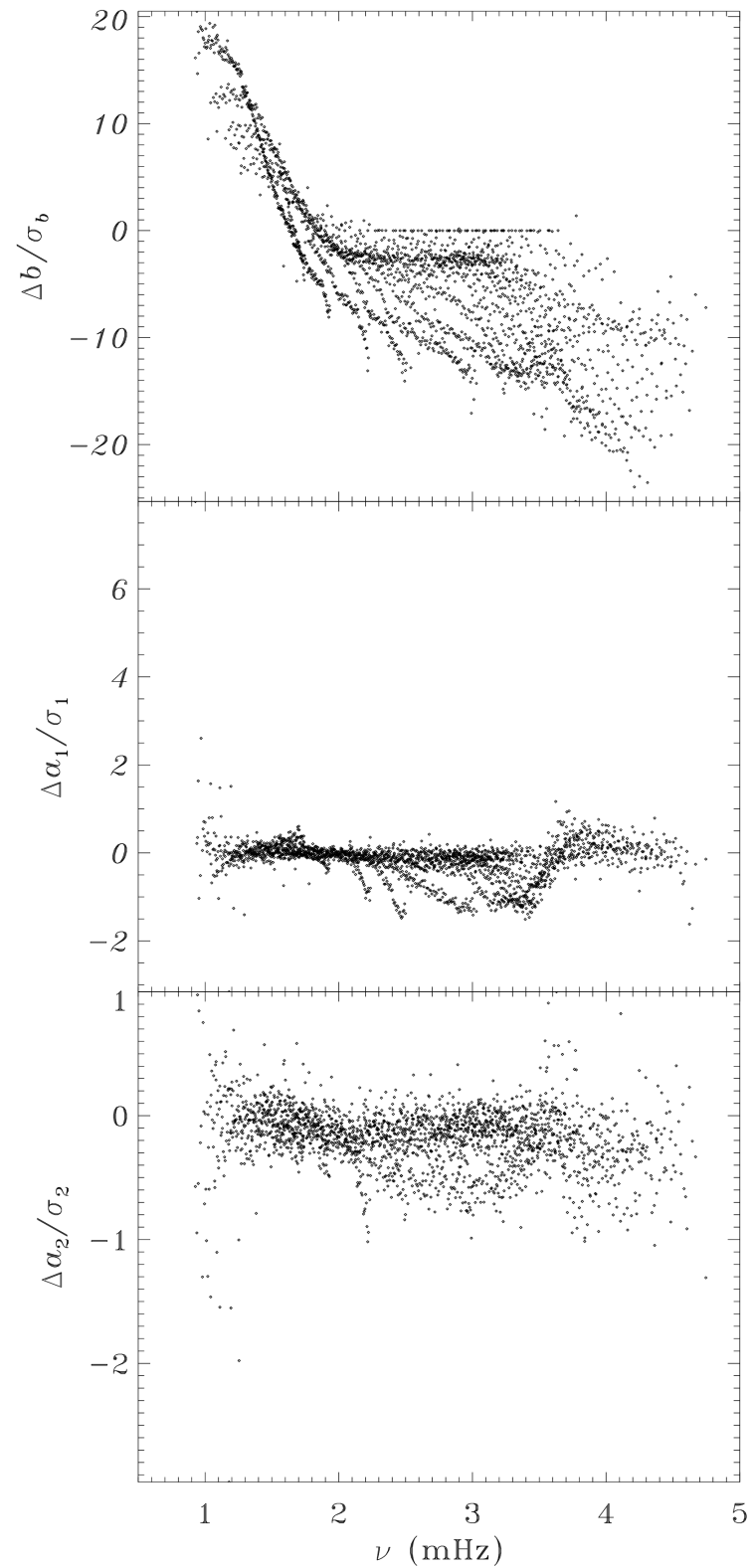
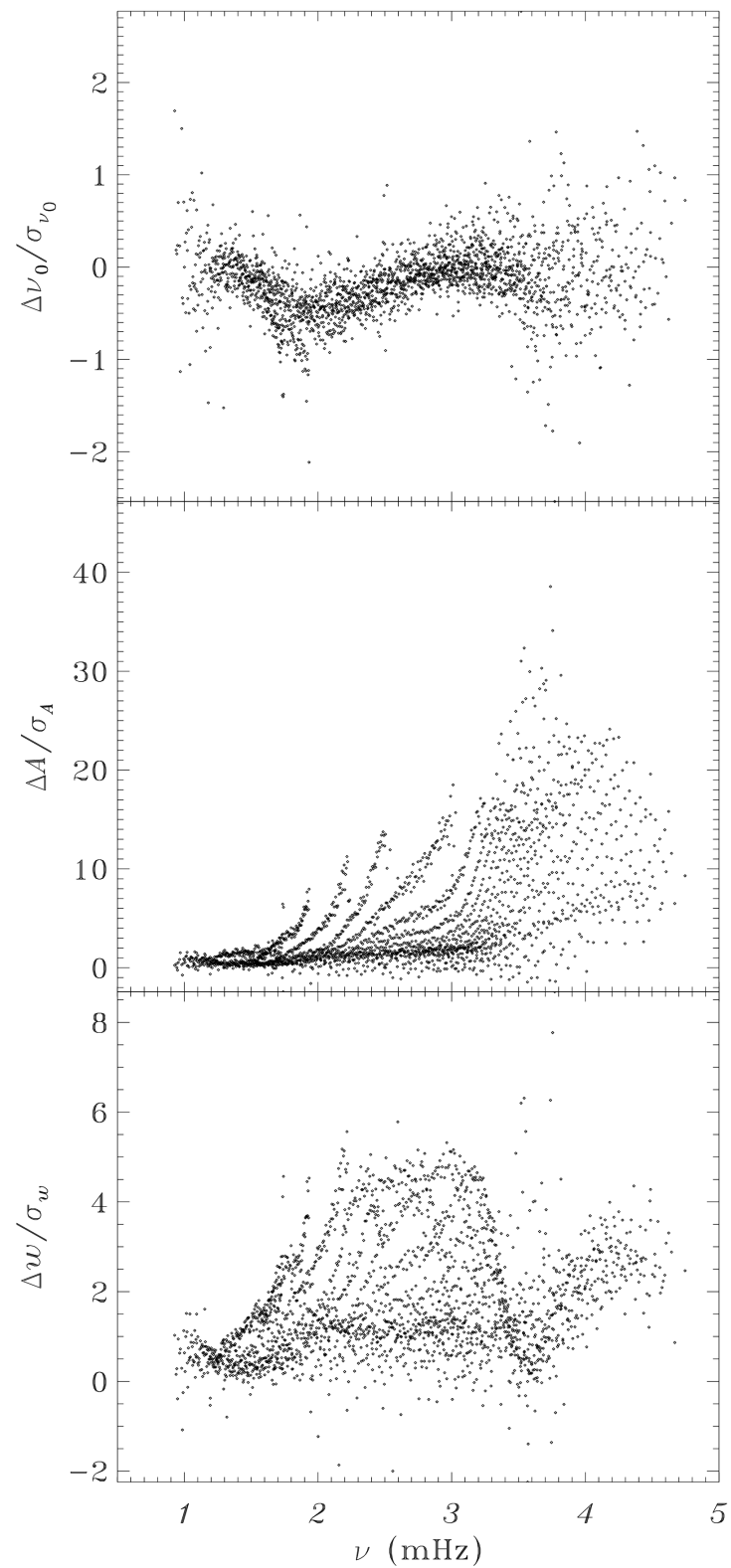


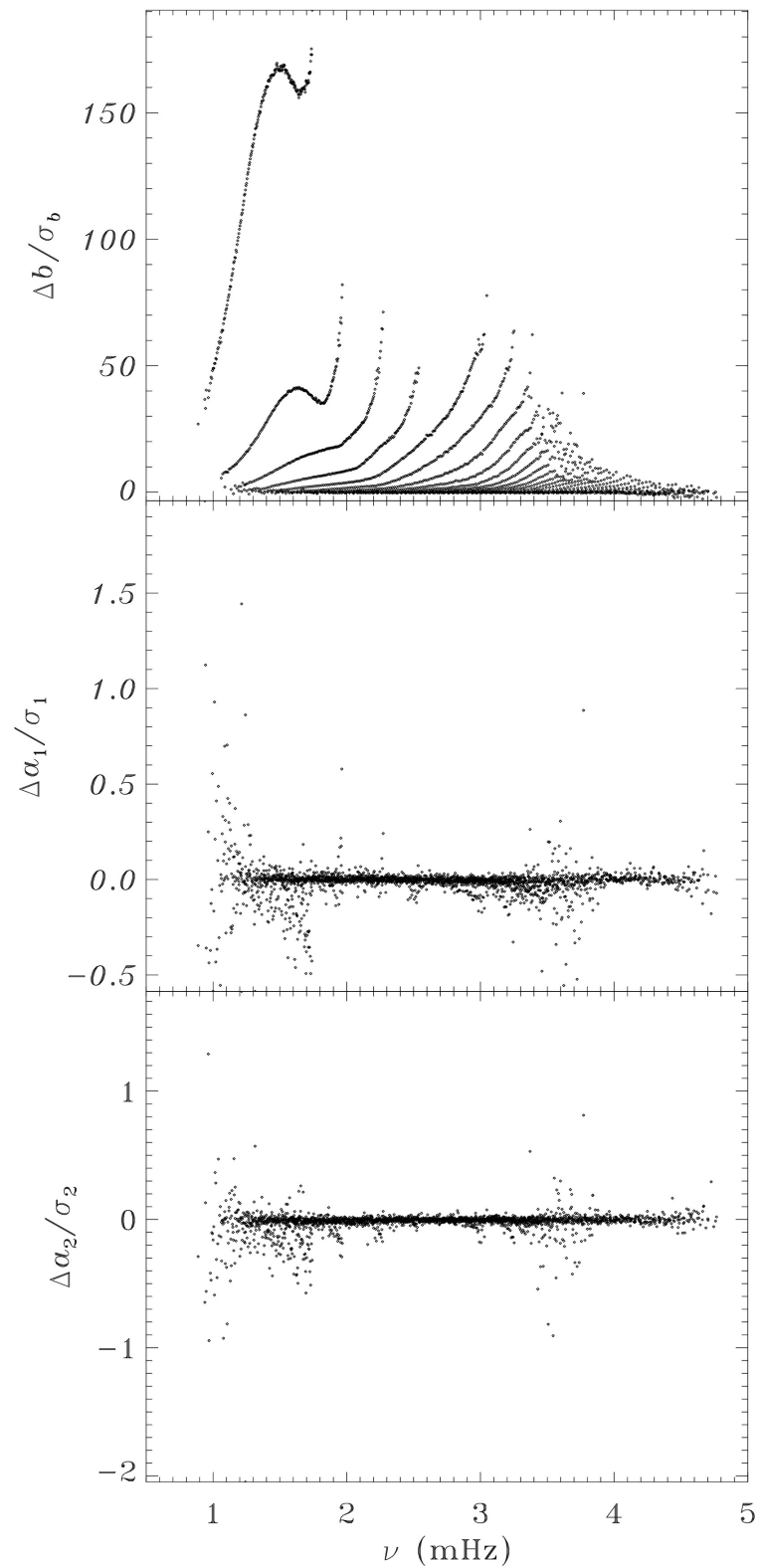
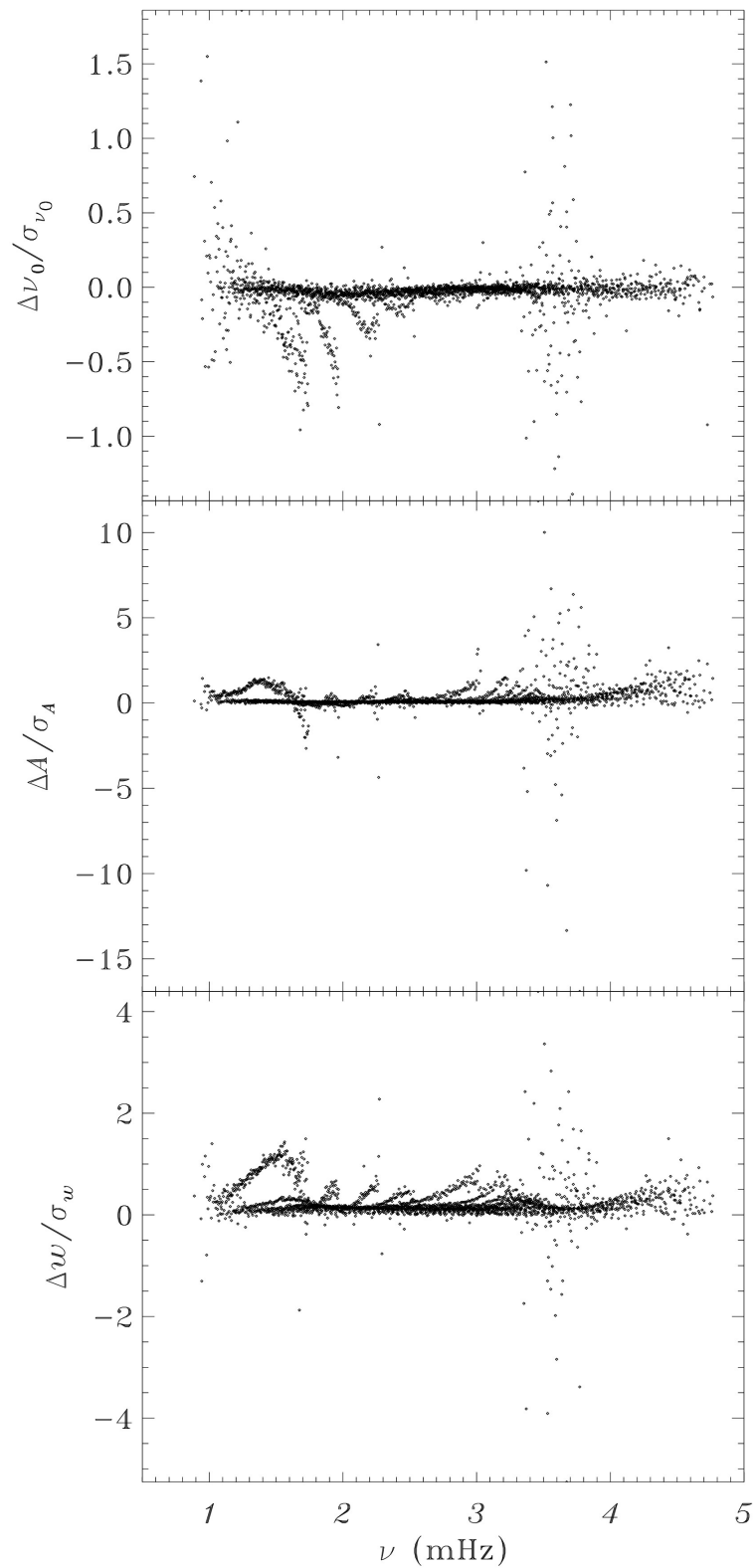
$$f(t) = A \sin(\omega_{\text{yr}} t) + B \cos(\omega_{\text{yr}} t) + Ct + D$$

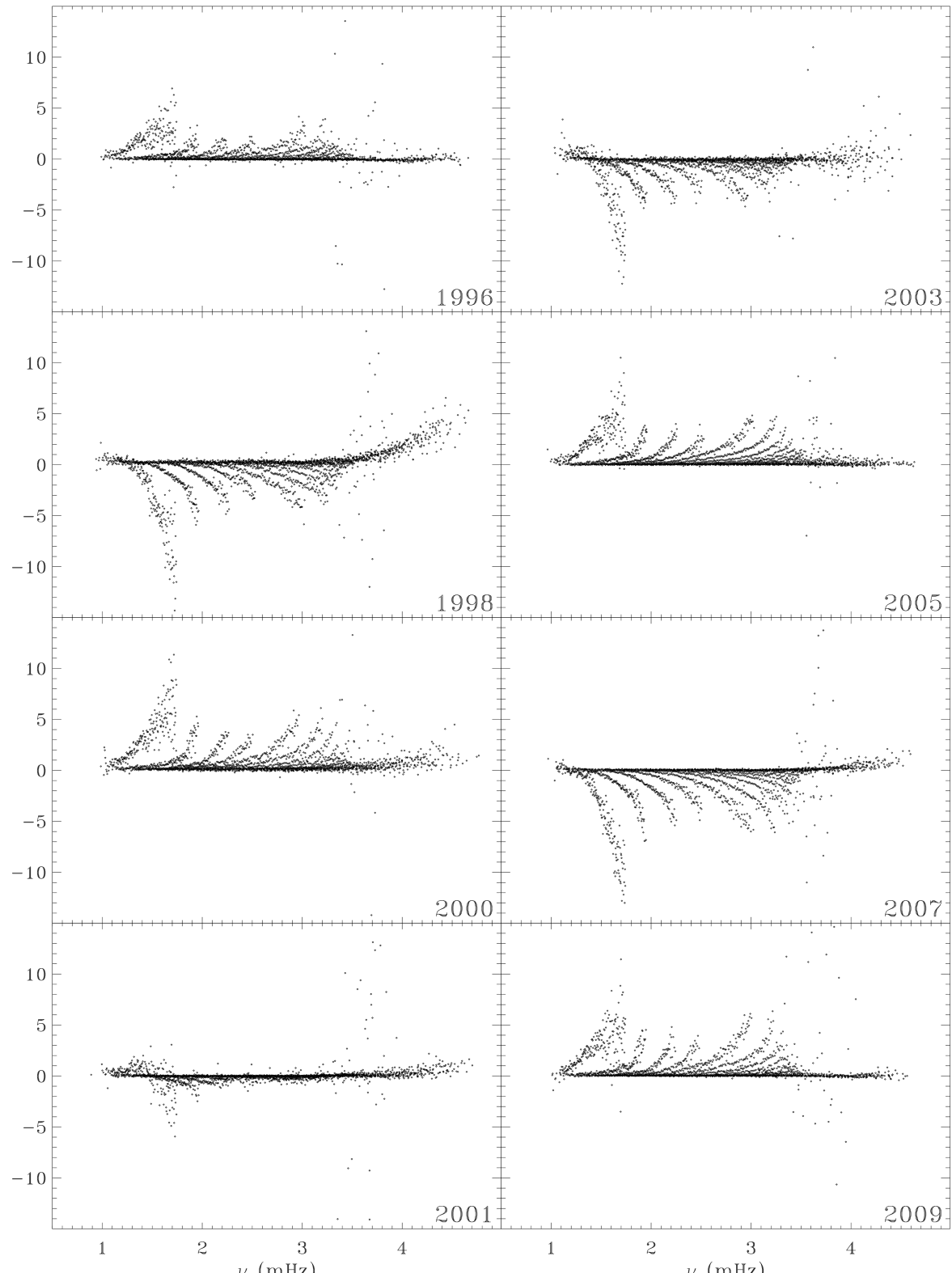


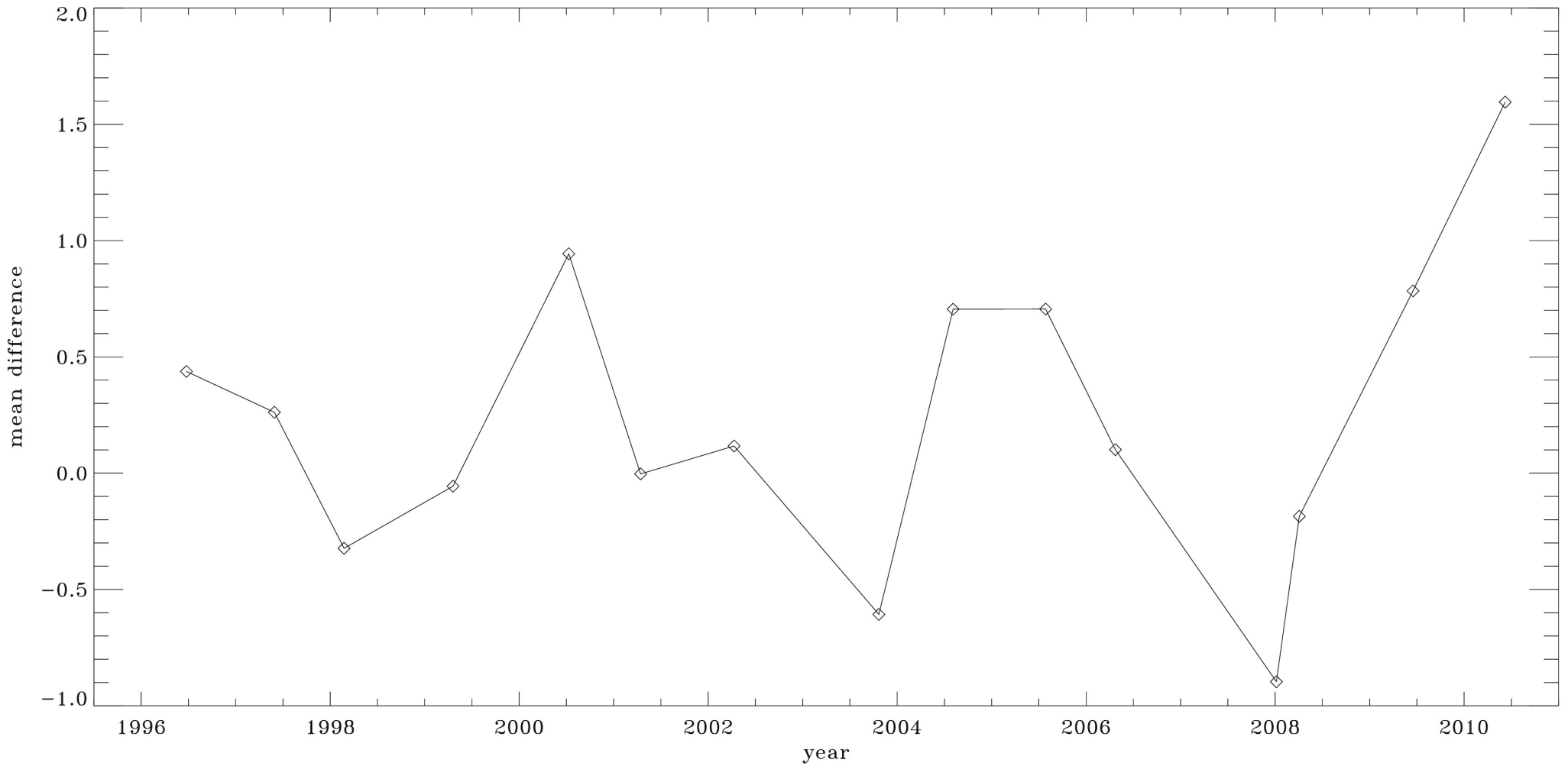
Full Disk Results from MDI

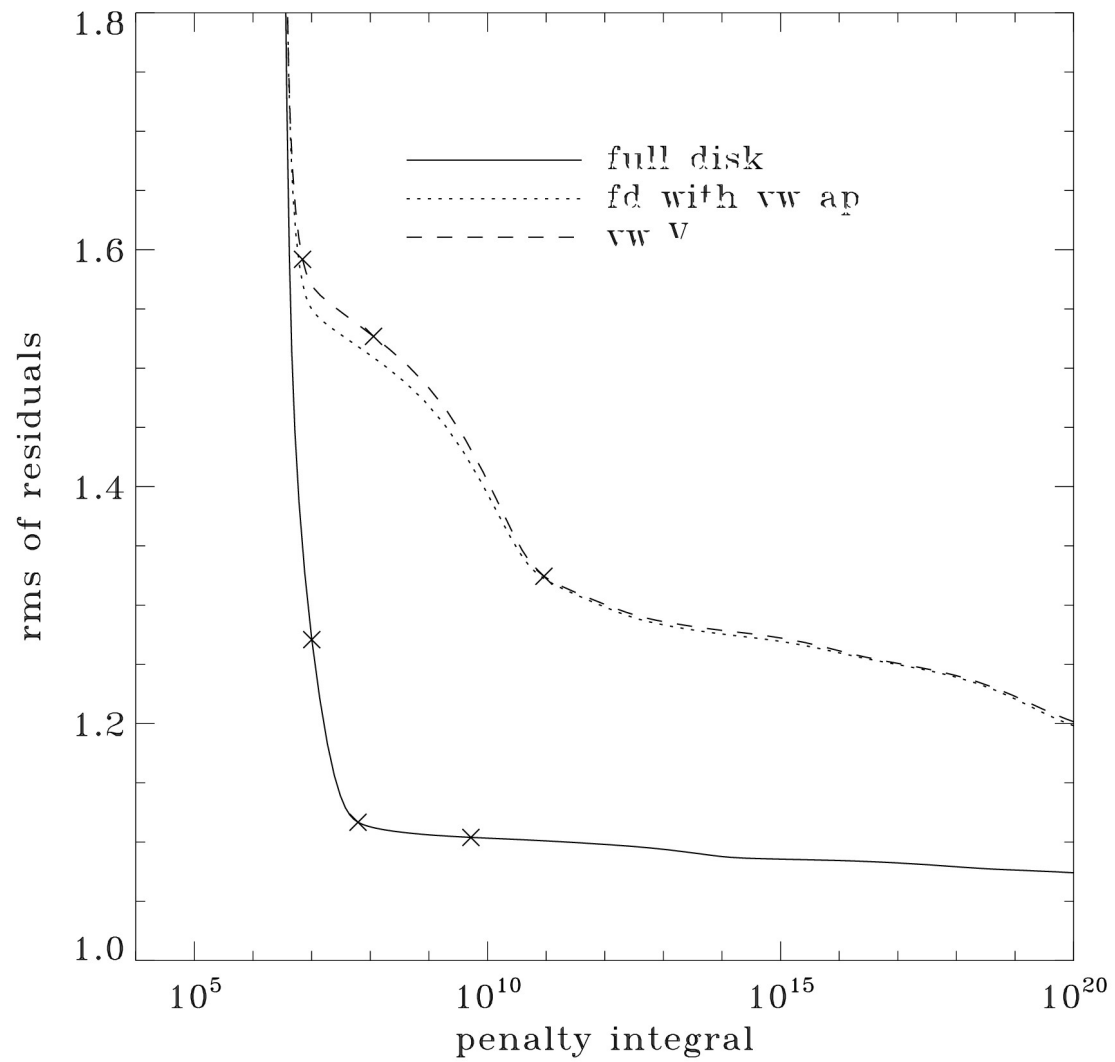


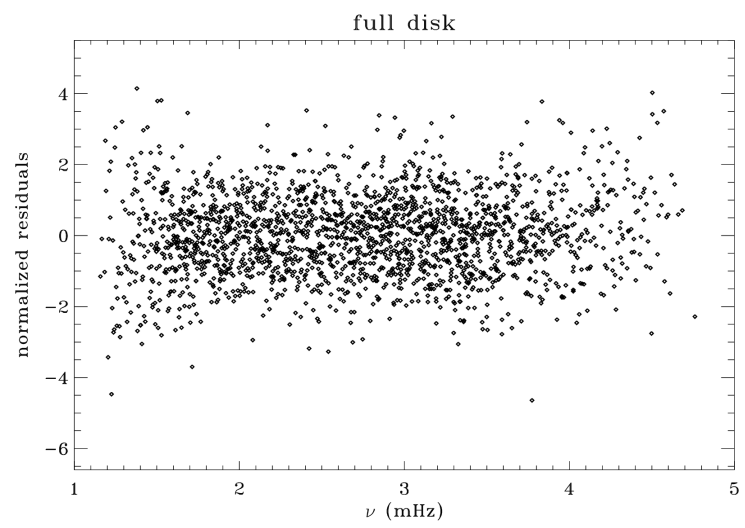
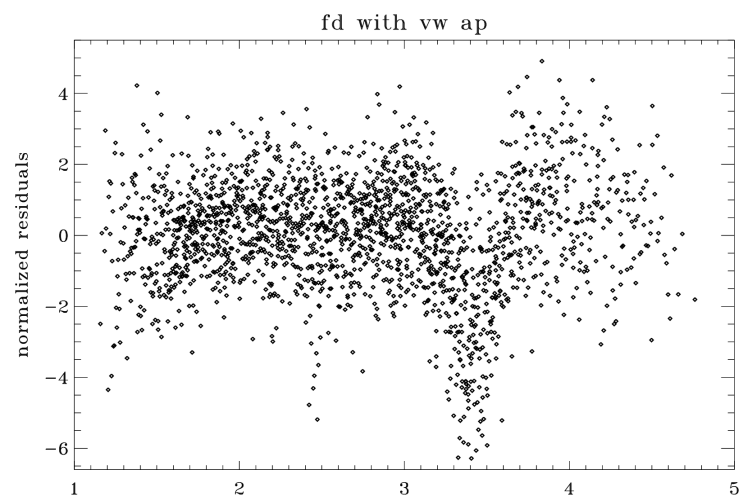
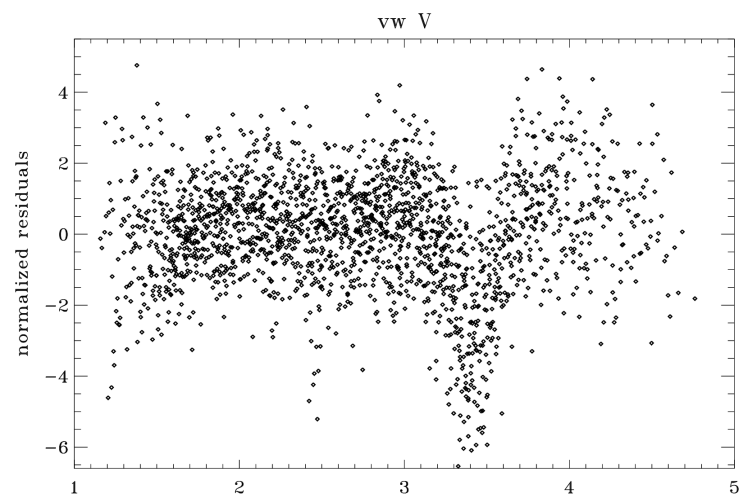


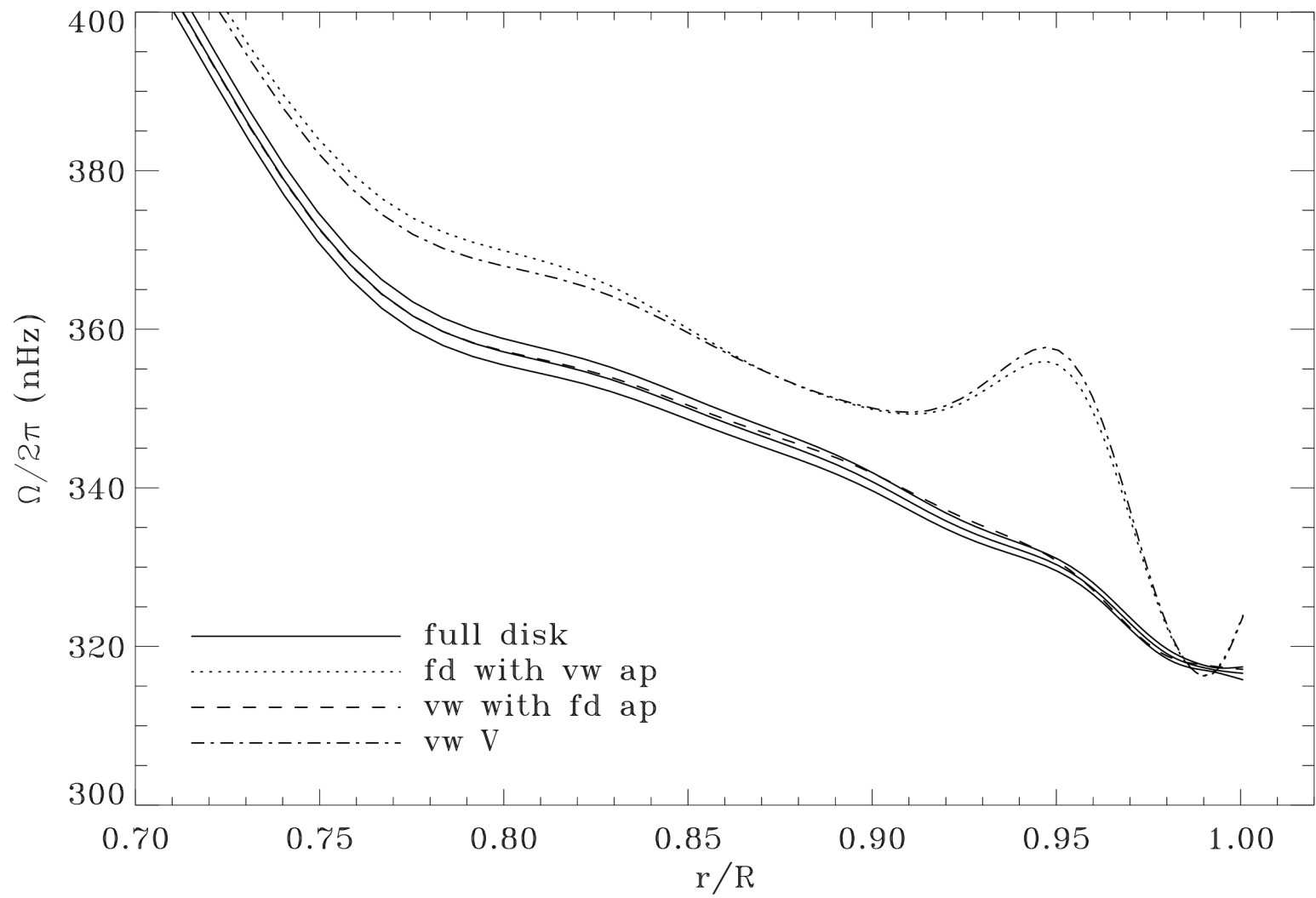




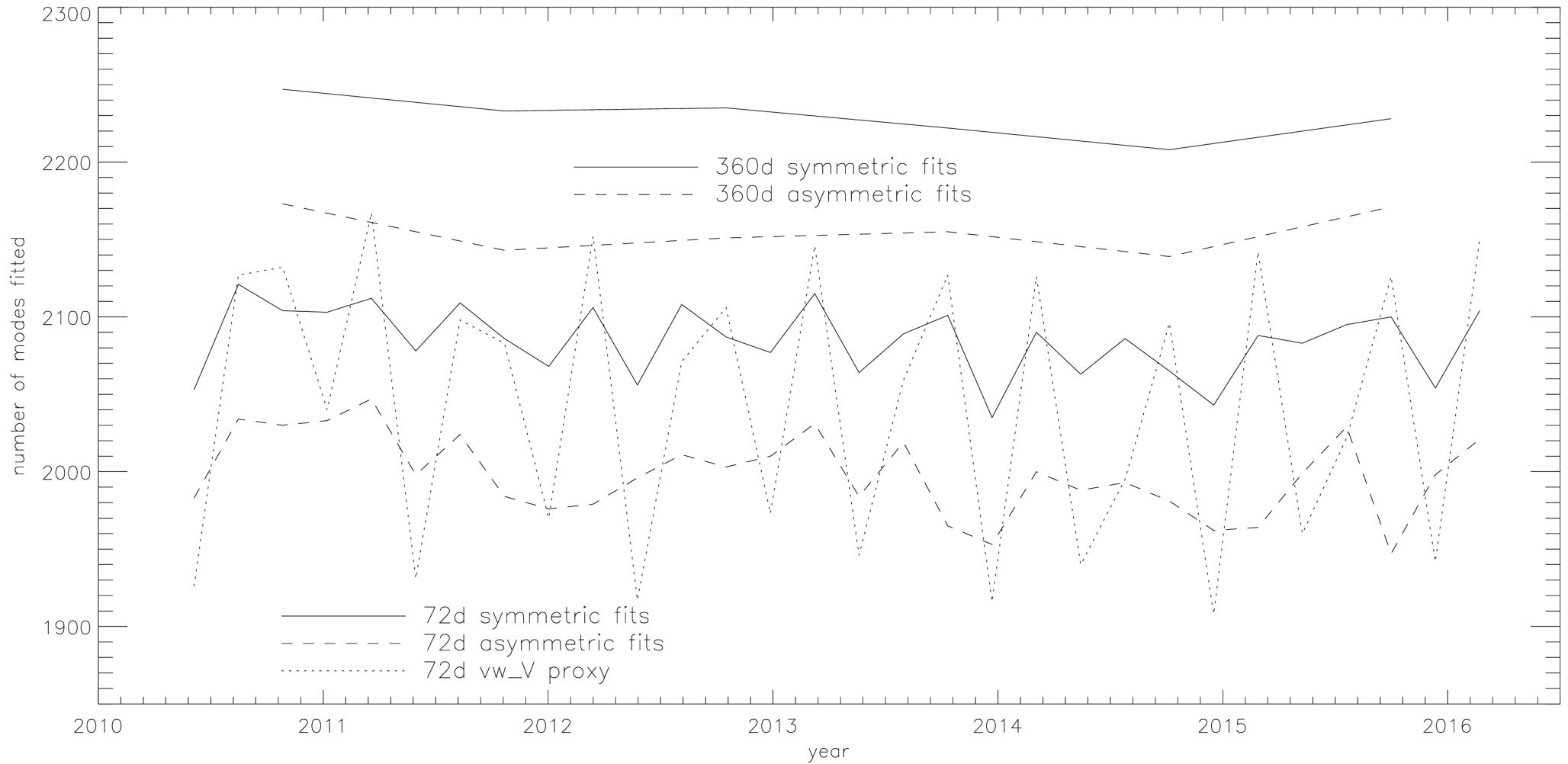


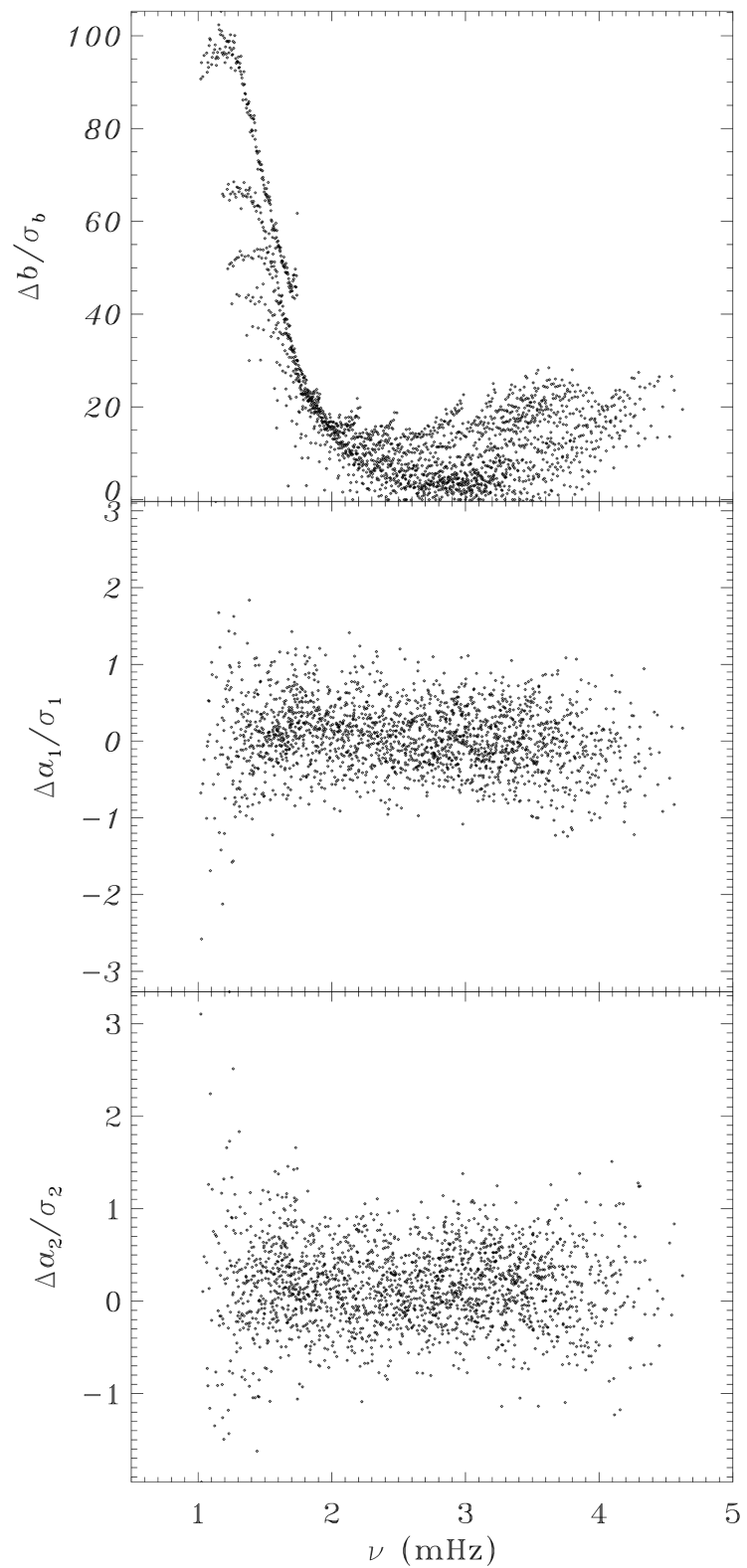
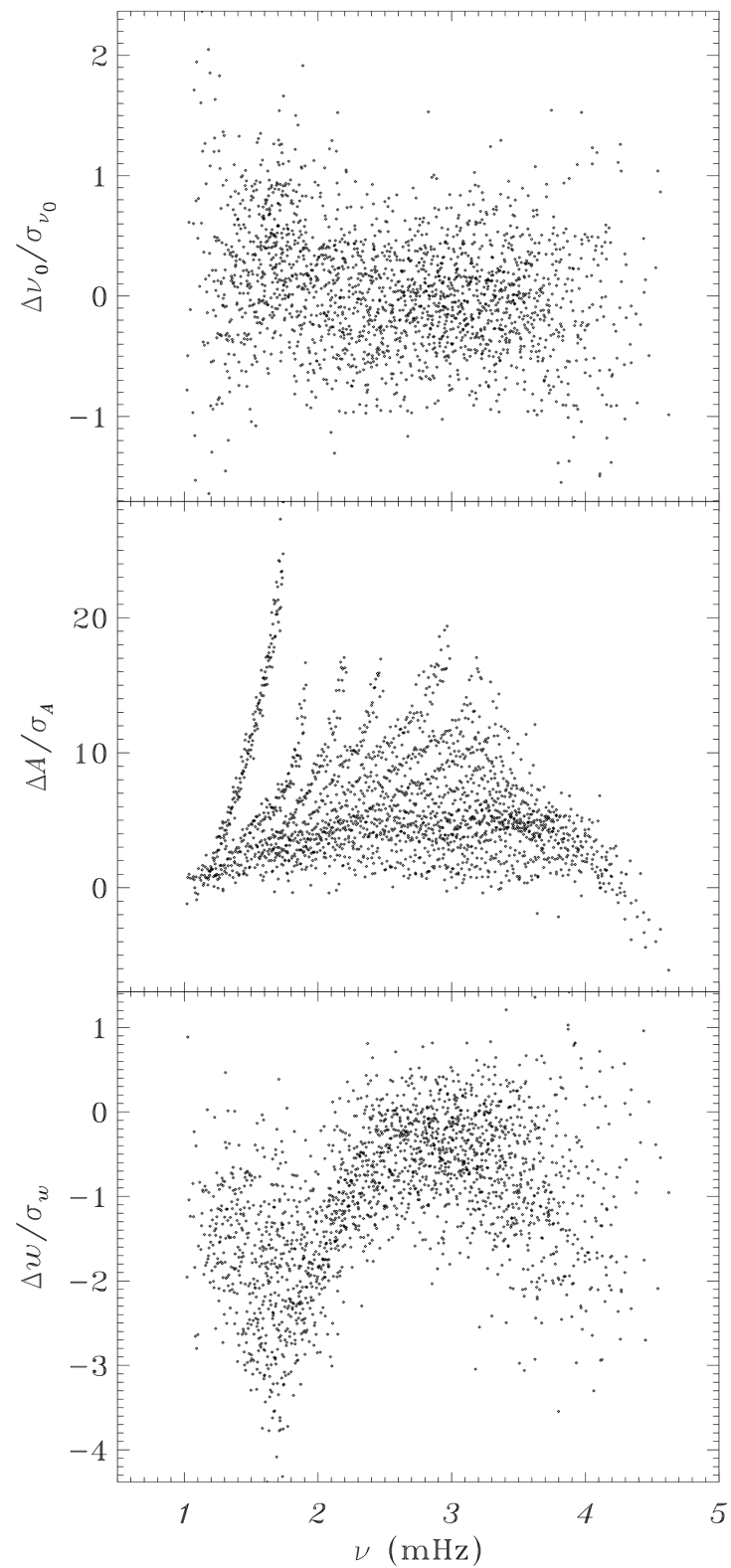


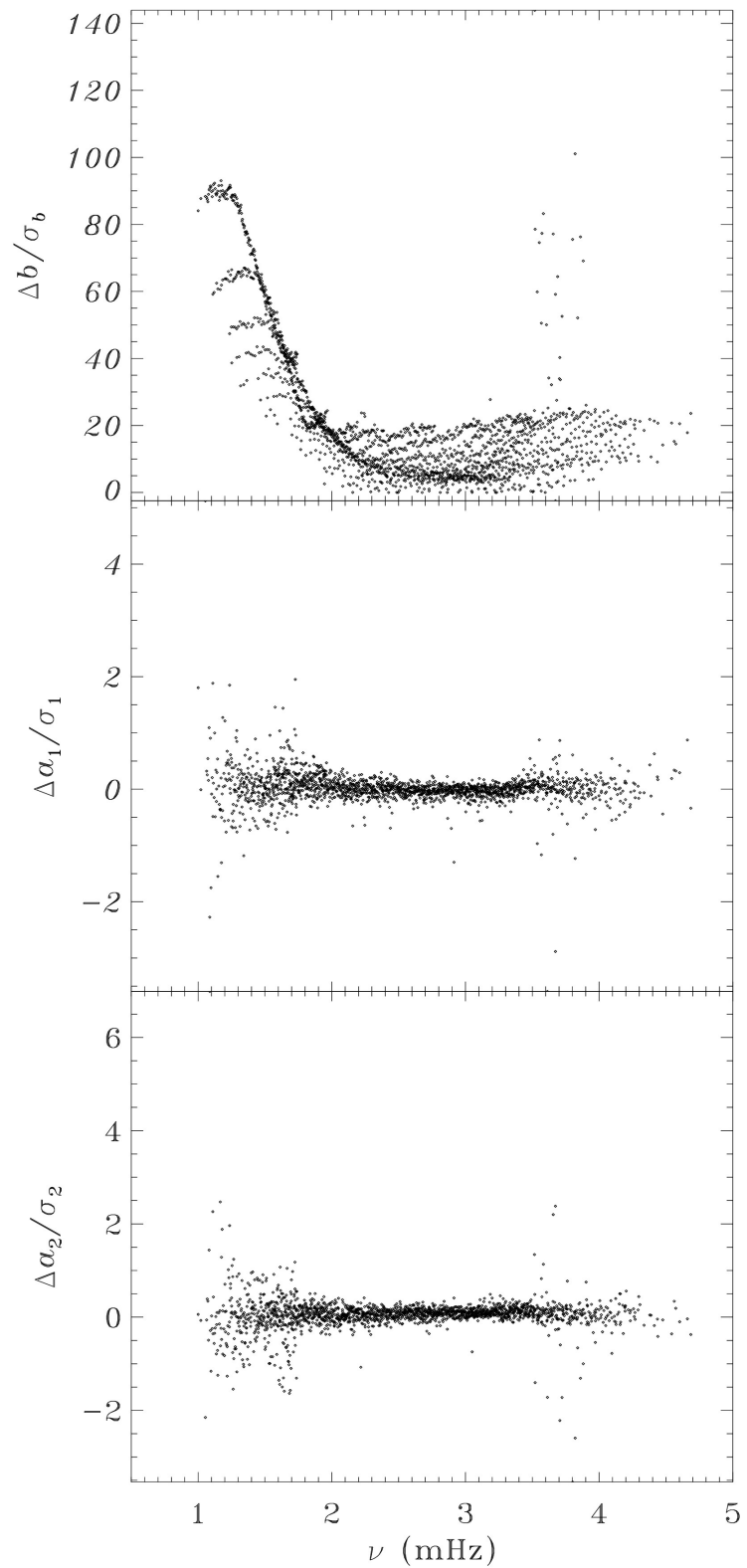
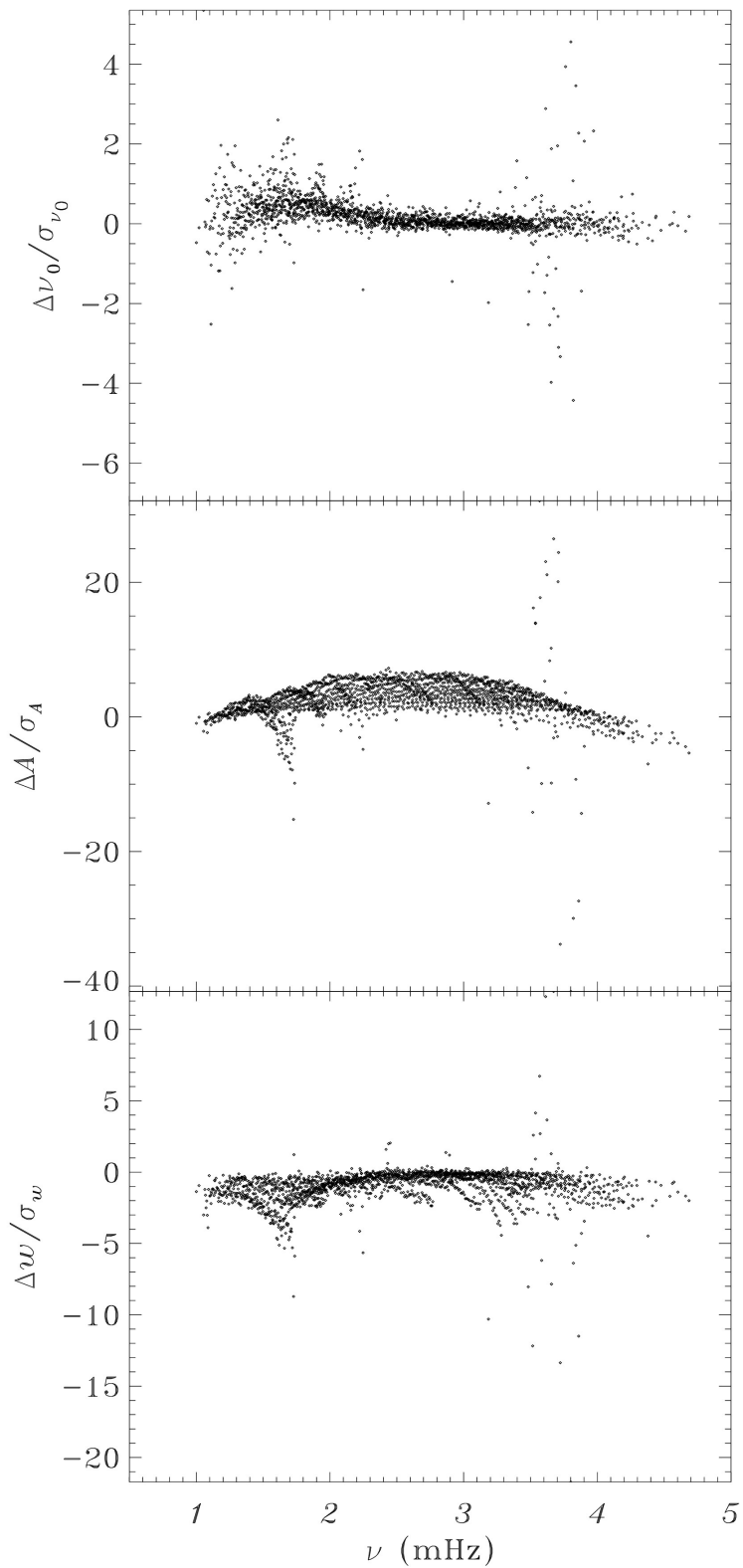


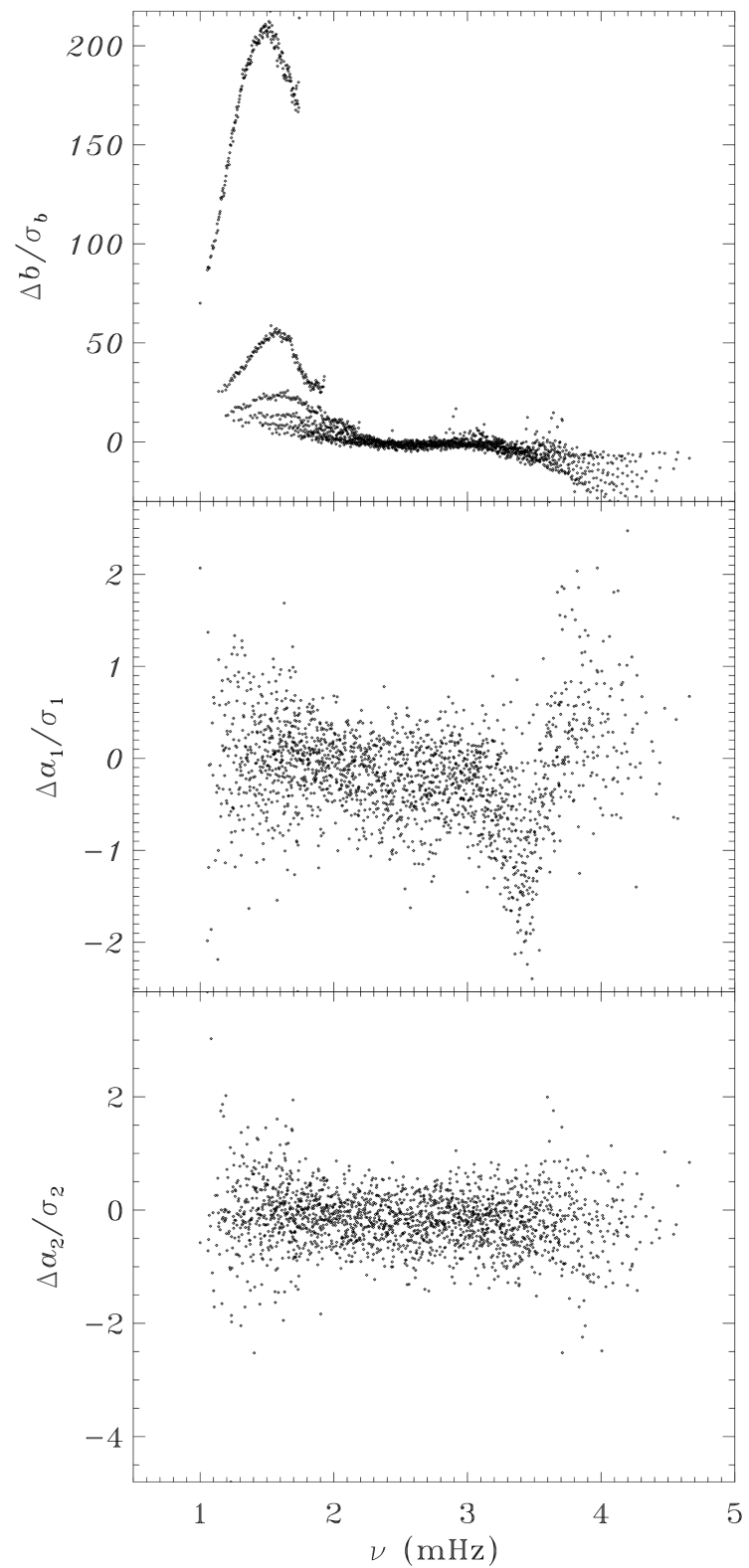
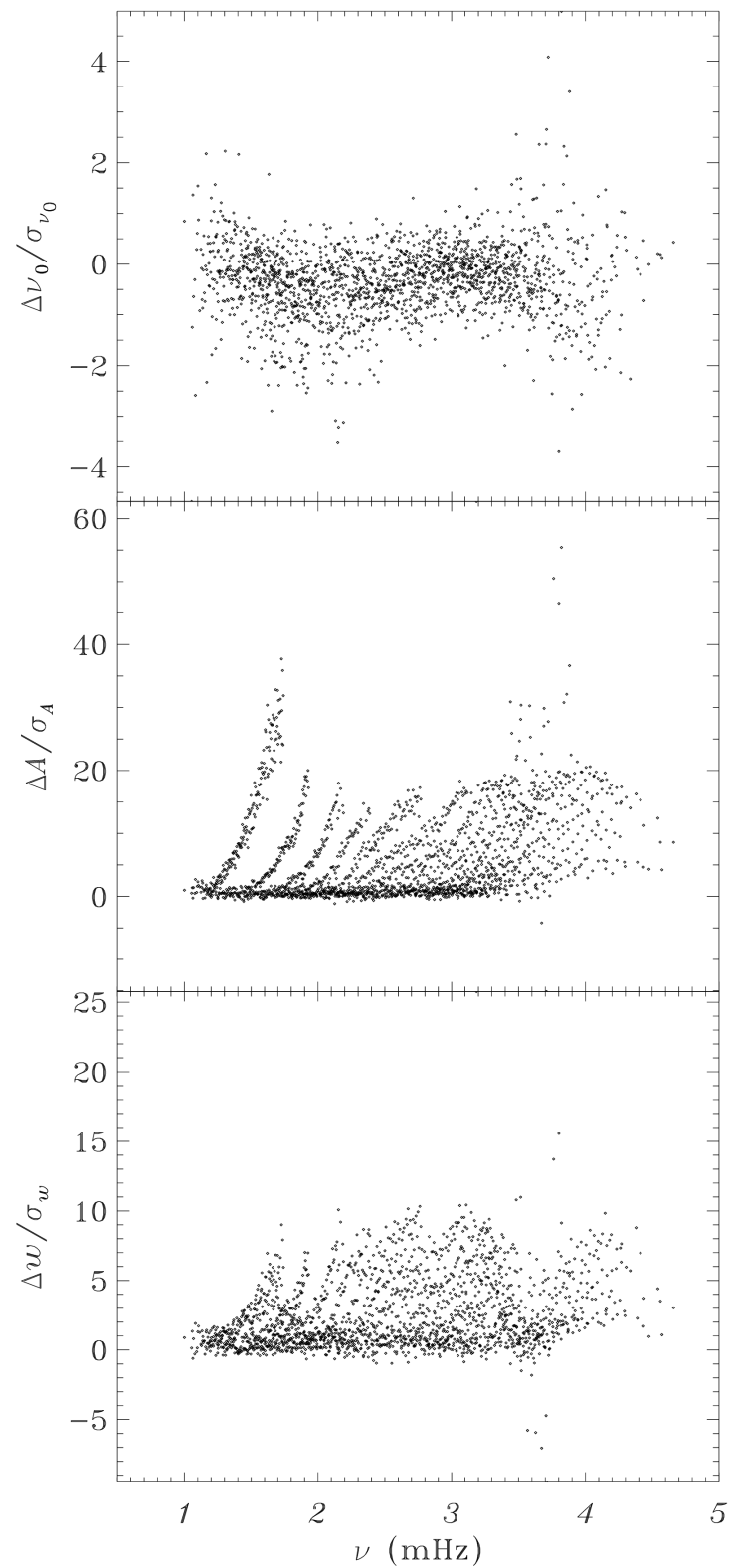


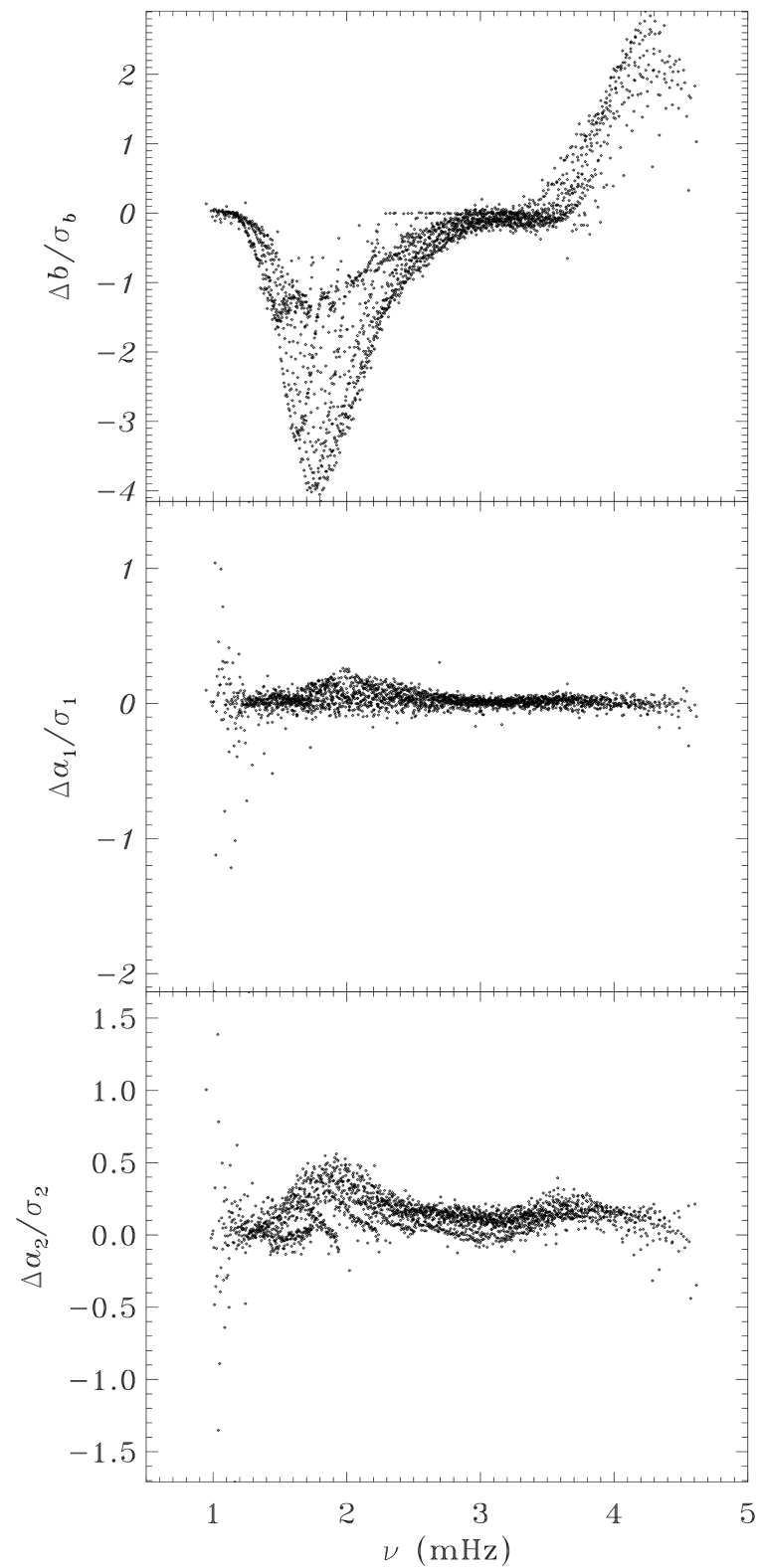
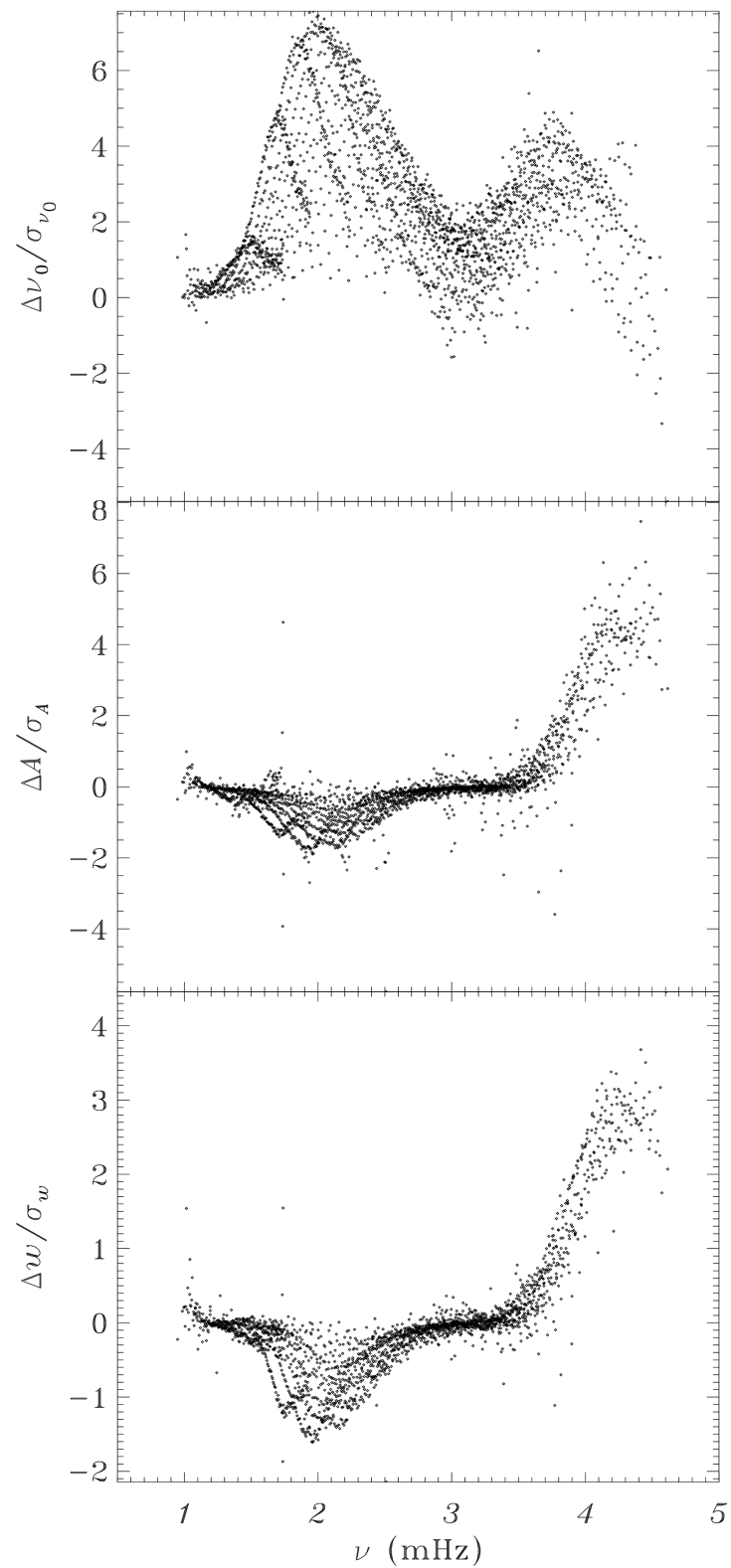
and HMI

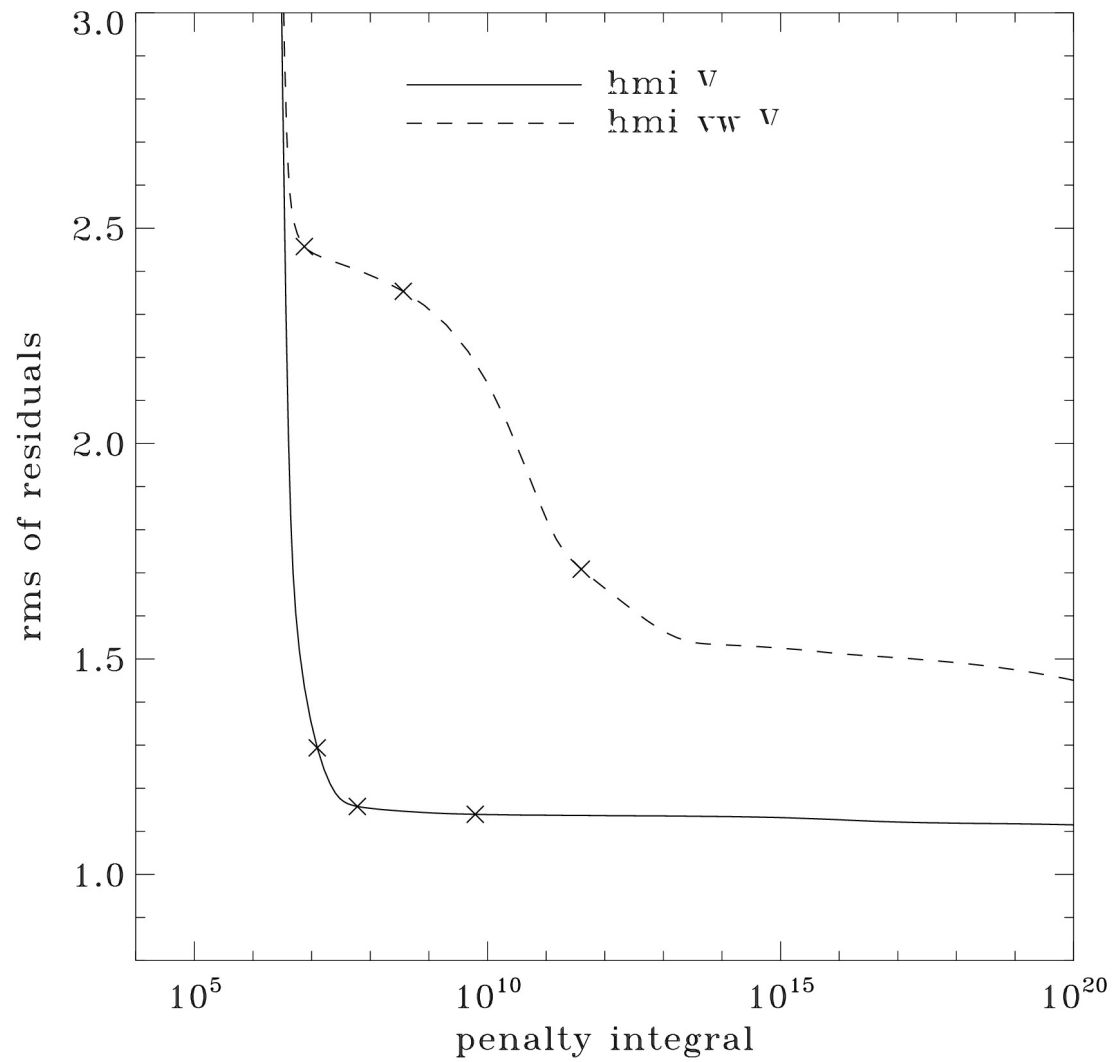


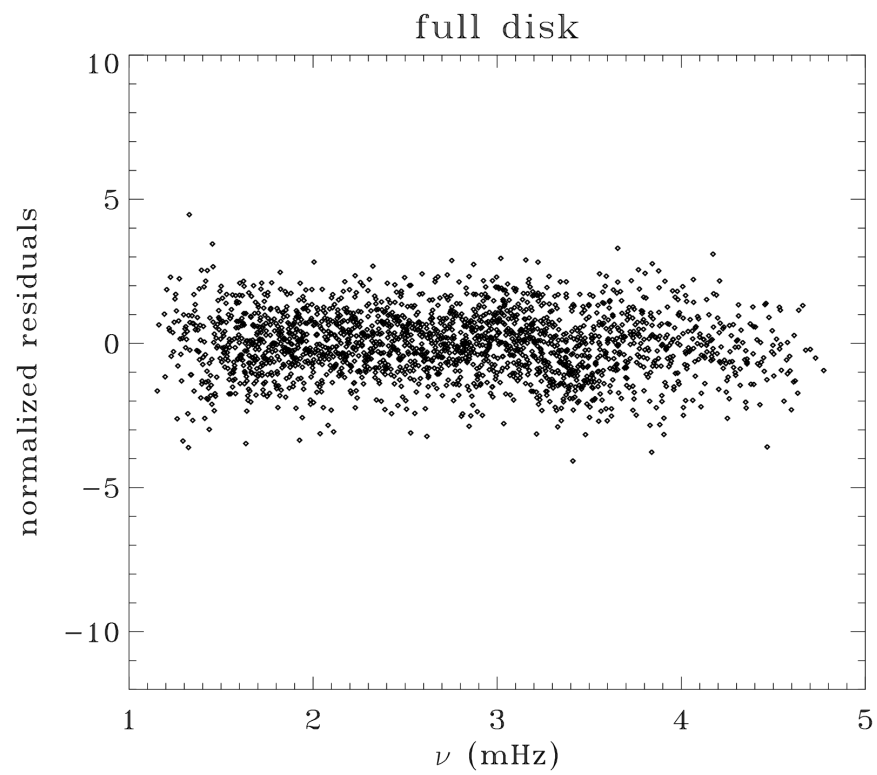
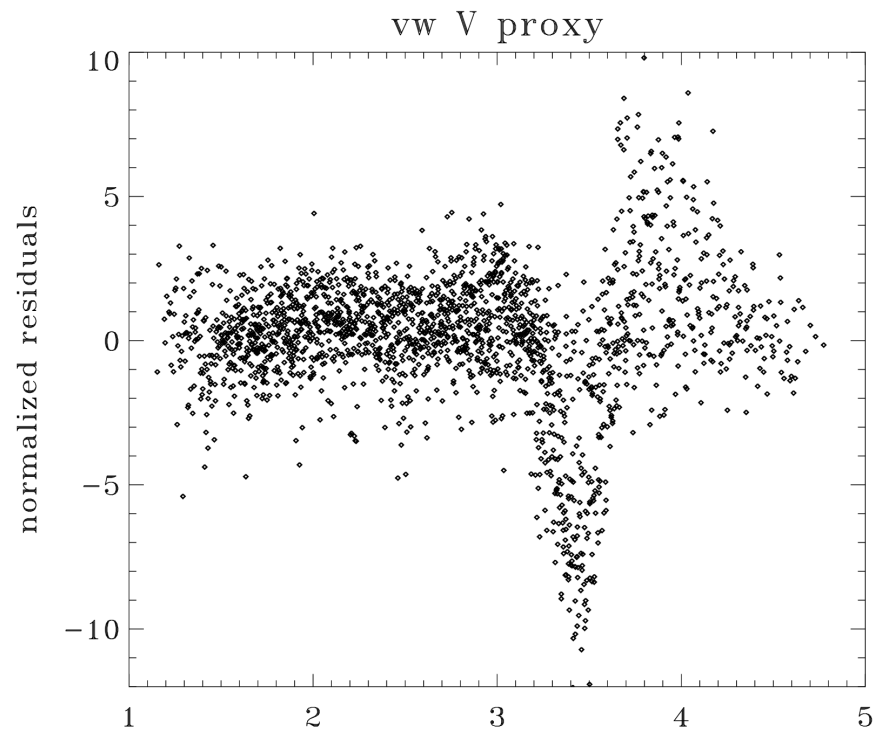


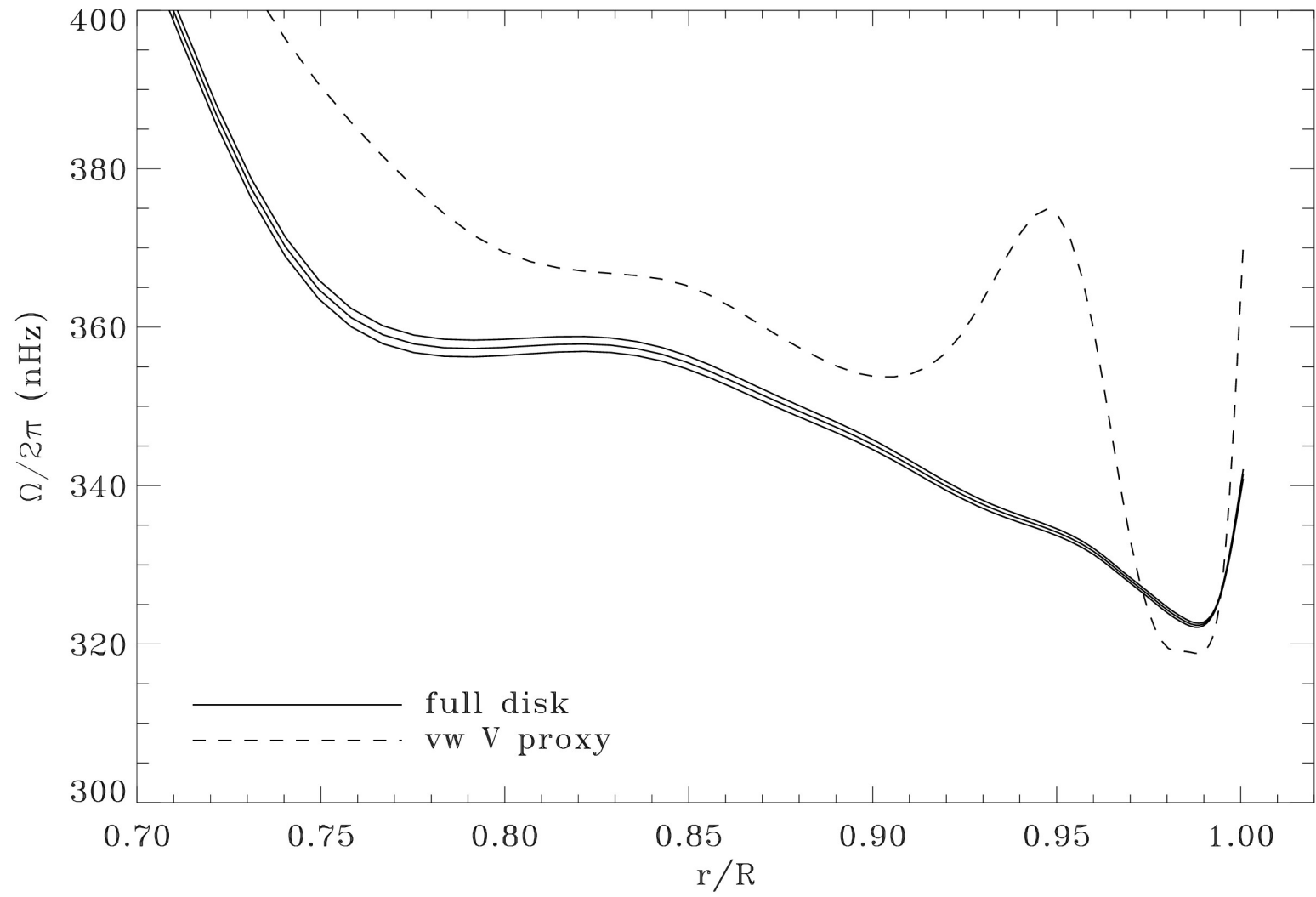


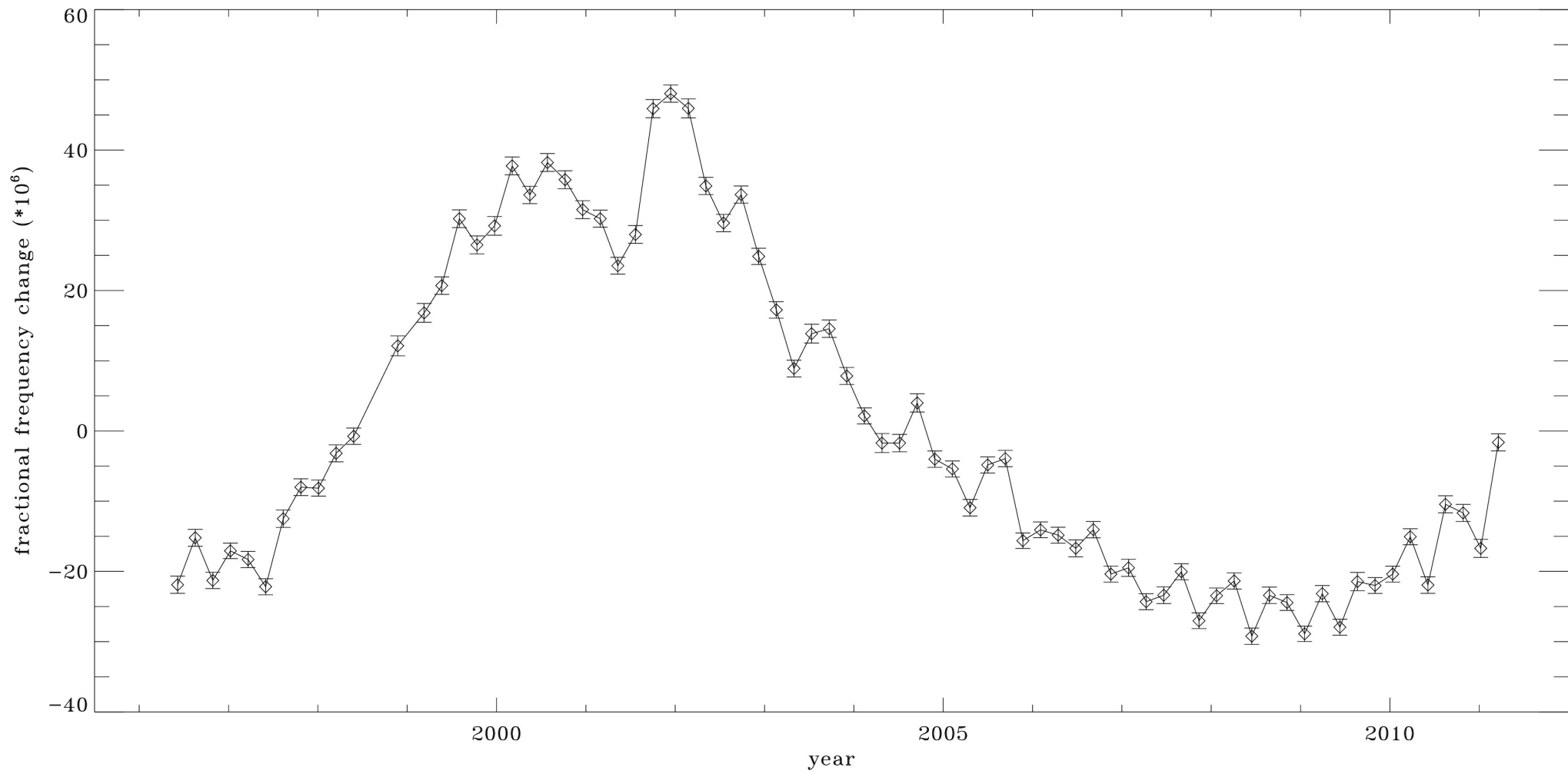


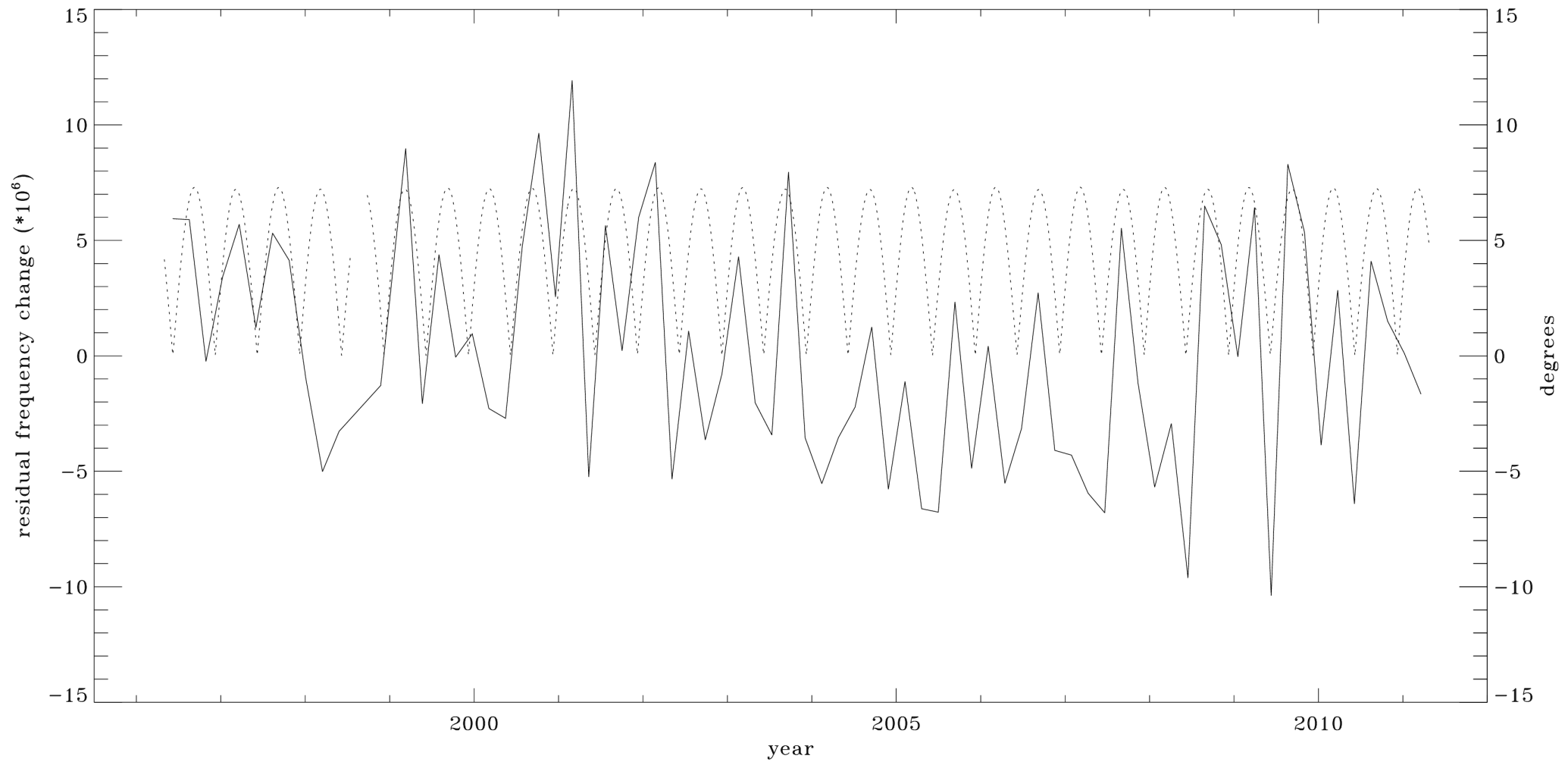


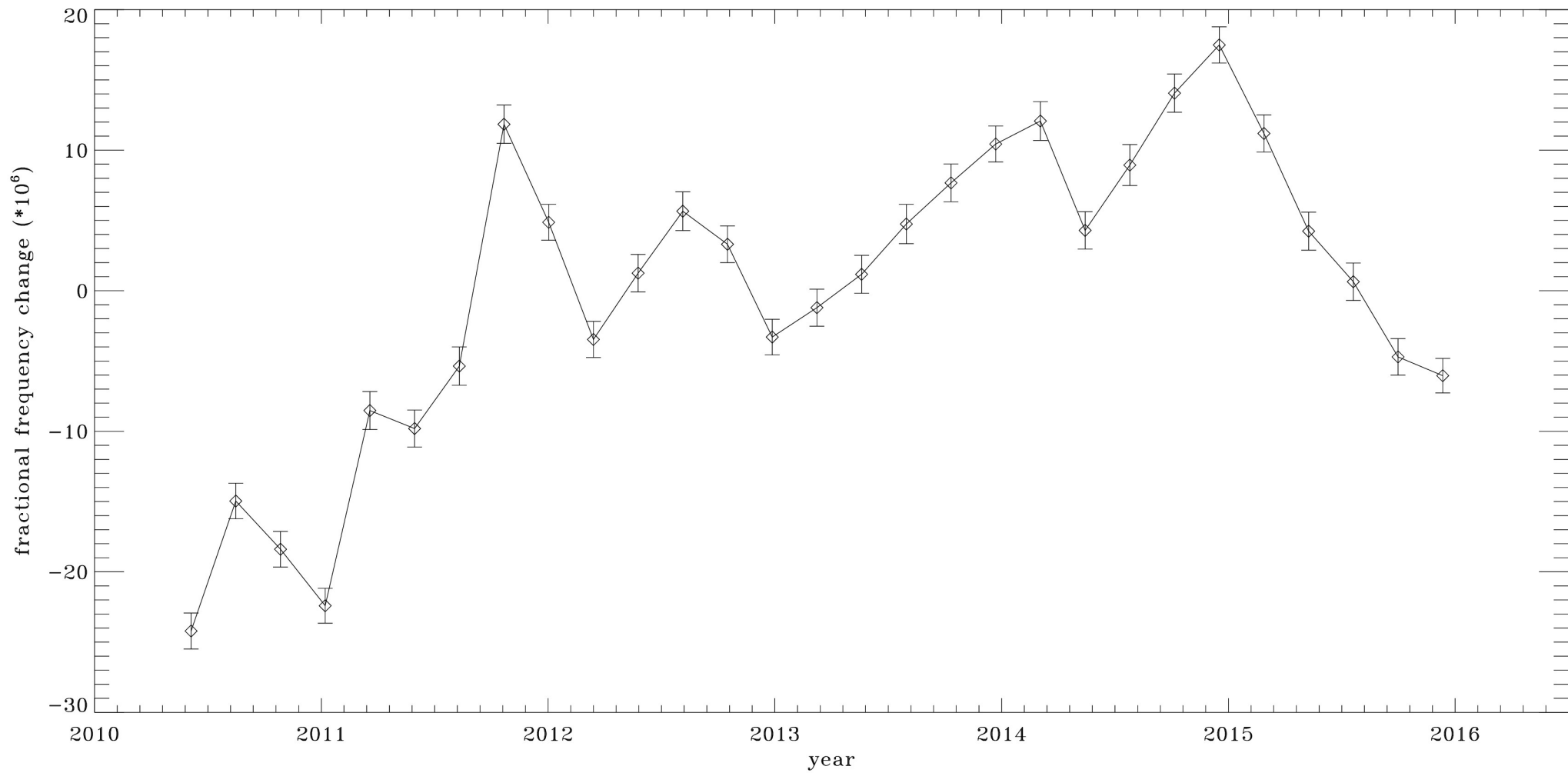


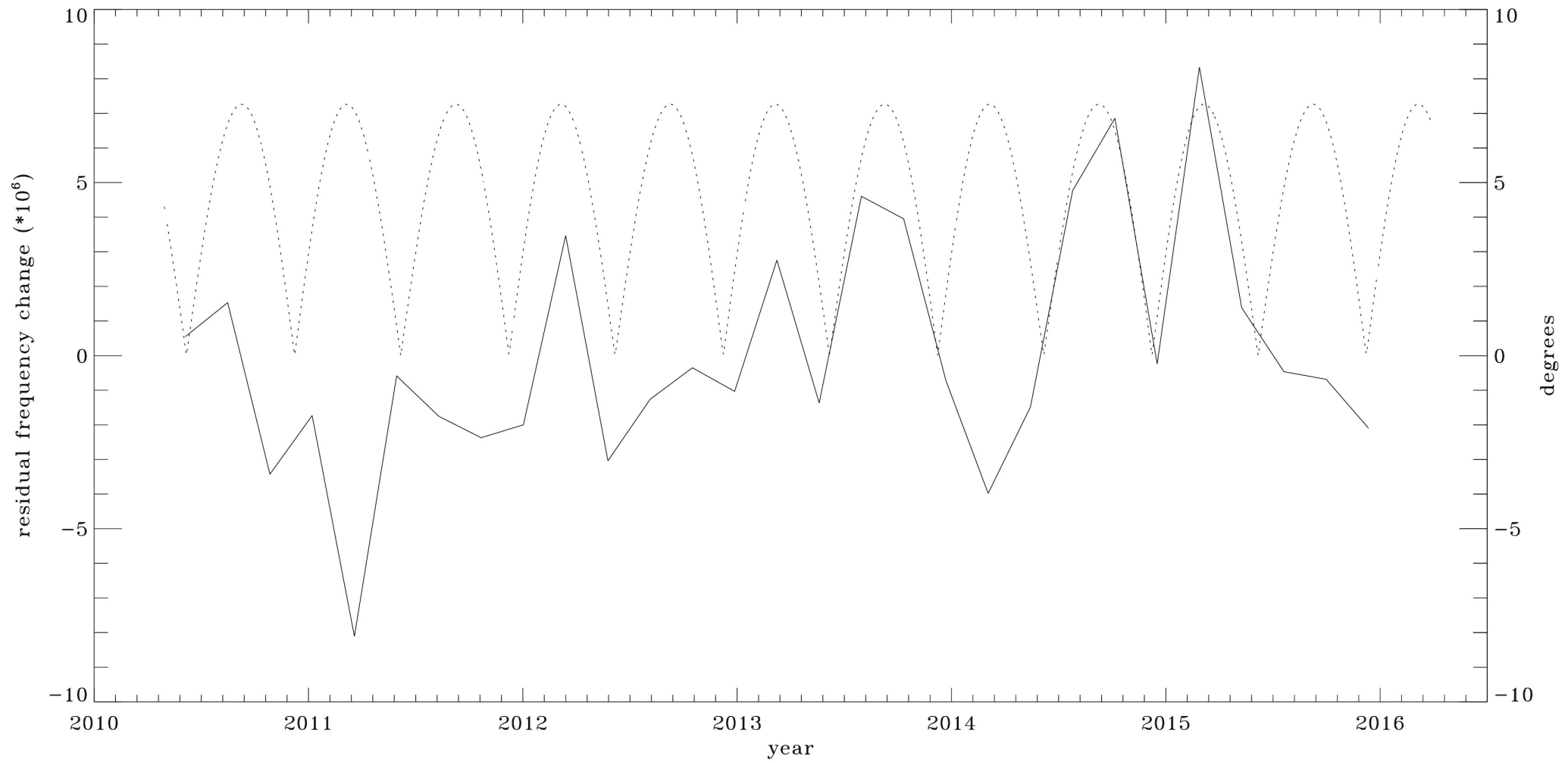


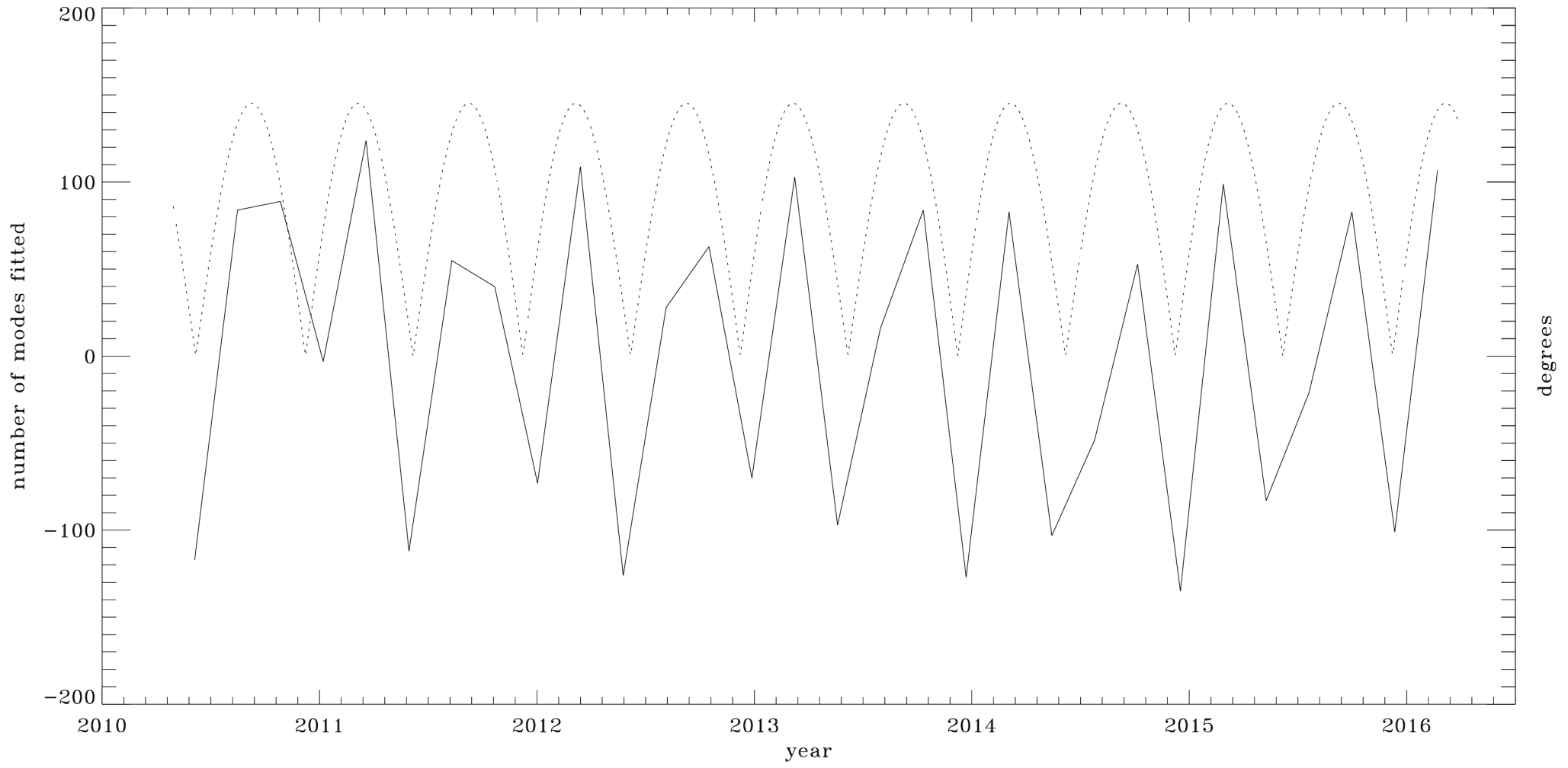


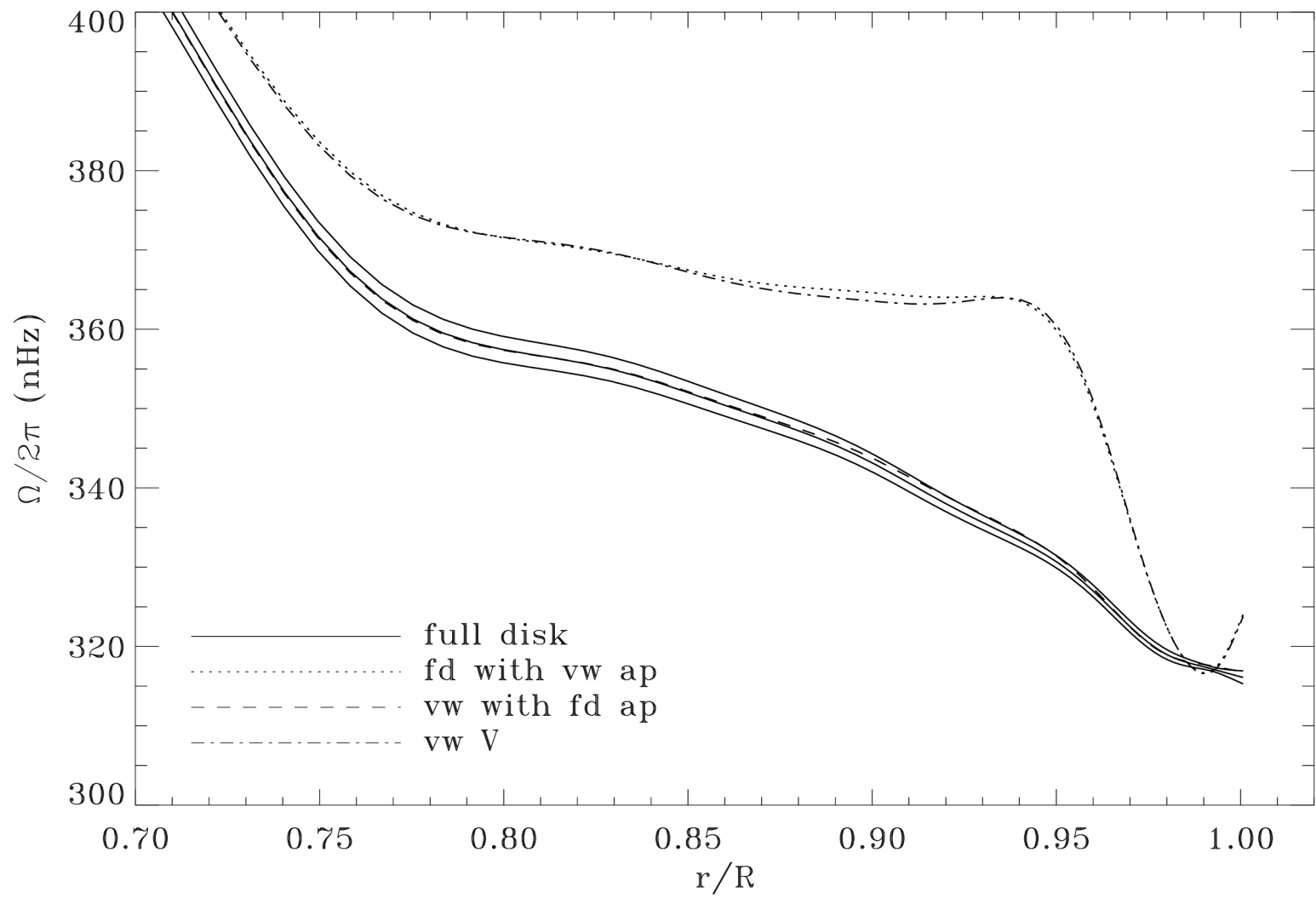


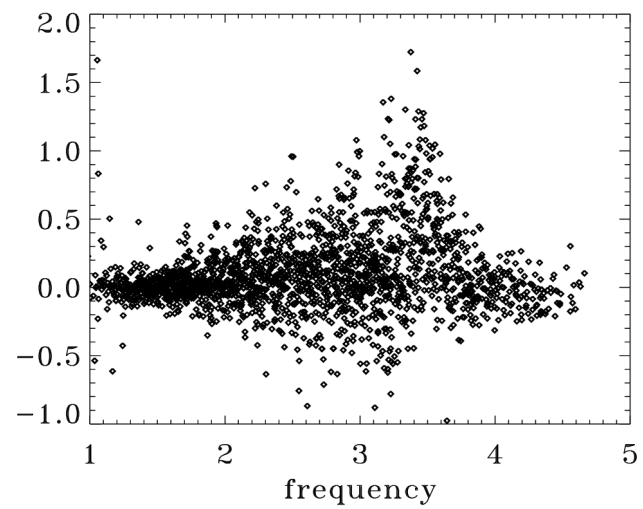
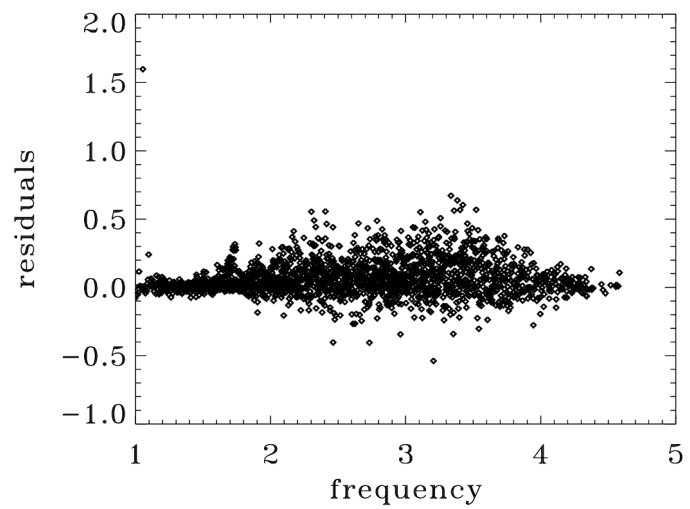
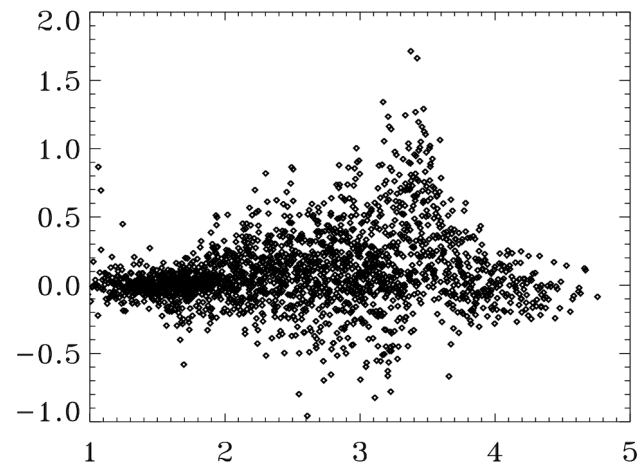
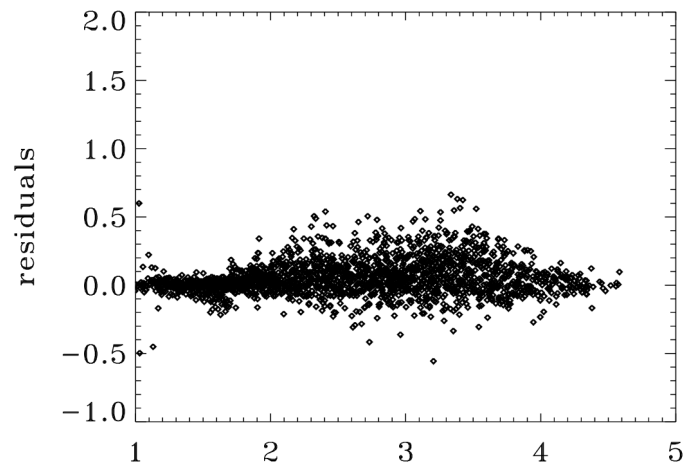












Conclusions

- none of the changes we applied to the vw_V analysis removed the bump or the jet, but the horns are gone
- changing the apodization does get rid of them